ACOL106: Data Structures and Algorithms

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Data Structures: Universal Hashing

- How do we design a good hash function?
- A set S of keys from a universe $U = \{0, 1, ..., m-1\}$ is supposed to be stored in a table of size n with indices $T = \{0, 1, ..., n-1\}$.
  - Collisions are resolved using an auxiliary data structure.
- What we need is a hash function $h : U \rightarrow T$ with the following main requirements:
  1. The hash function should minimize the number of collisions.
  2. The space used should be proportional to the number of keys stored. (i.e., $n \approx |S|$)
- The issue is that the key set S is not known a priori. That is, before using the data structure.
- Question: How do we solve this problem then?
  - Randomly select a hash function from a family H of hash functions.

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- Question: Can you think of a 2-universal hash function family?
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  - Do you see any issues with using this hash function family? The description of any hash function from this family is large.
  - Question: Can we design a more compact hash function family?

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- A compact 2-universal hash function family:
  - Let $m \leq p \leq 2m$.
  - $H = \{h_{a,b} | a \in \{1, ..., p-1\}, b \in \{0, ..., p-1\}\}$ and $h_{a,b}(x) = ((ax + b) \mod p) \mod n$.
  - How many functions does H have?

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- Claim 1: If $h_{a,b}(x) = h_{a,b}(y)$, then $g_{a,b}(x) = g_{a,b}(y) \mod n$.

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- Claim 2: For all $\alpha, \beta \in \{0, ..., p-1\}$:

$$\mathbf{Pr}[g_{a,b}(x) = \alpha \text{ and } g_{a,b}(y) = \beta] = \begin{cases} 0 & \text{if } \alpha = \beta \\ \frac{1}{p(p-1)} & \text{otherwise} \end{cases}$$

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- Claim 3: We have:

$$\mathbf{Pr}[h_{a,b}(x) = h_{a,b}(y)] = \frac{|\{(\alpha, \beta) : \alpha \neq \beta \text{ and } \alpha \equiv \beta \mod n\}|}{p(p-1)} \leq \frac{1}{n}.$$

End