

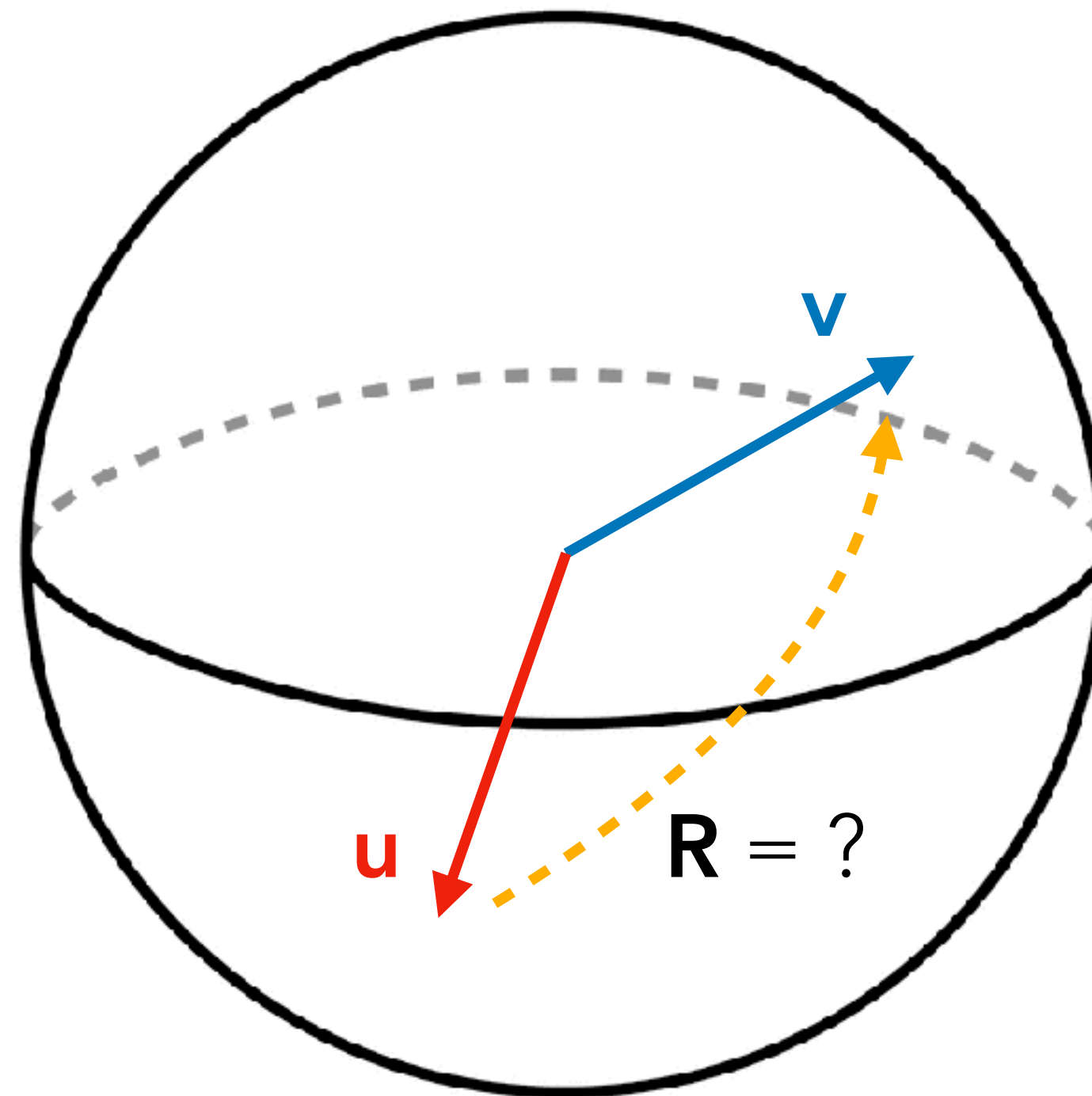


**COL781: Computer Graphics**

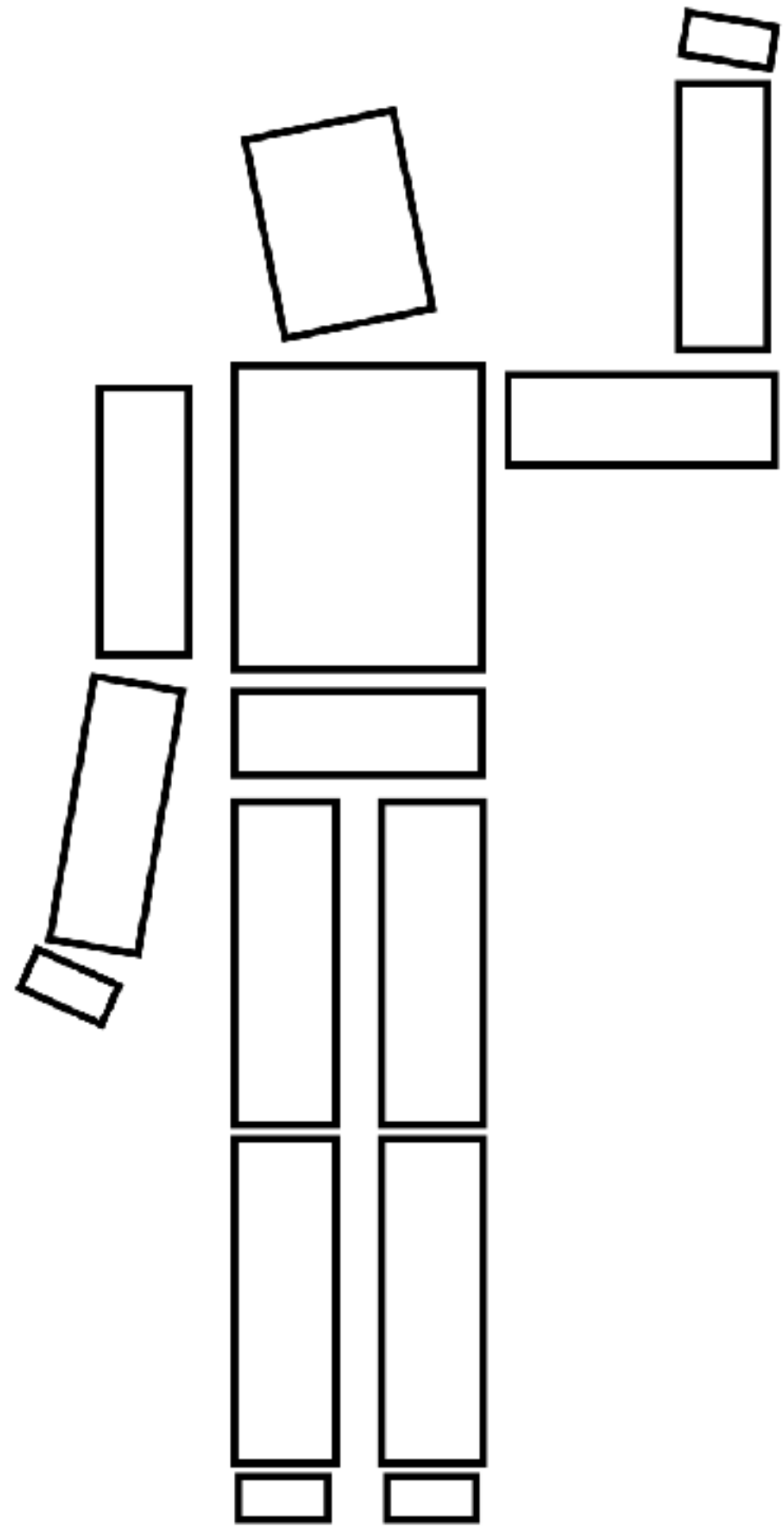
# **6. Perspective Projection**

# Last class's homework

Given unit vectors  $\mathbf{u}$  and  $\mathbf{v}$ , find a way to construct a rotation matrix  $\mathbf{R}$  which maps  $\mathbf{u}$  to  $\mathbf{v}$ , i.e.  $\mathbf{R}\mathbf{u} = \mathbf{v}$ . Is it unique, or are there many different such rotations?



# Hierarchical transformations



hip

chest

head

left upper arm

left lower arm

left hand

right upper arm

right lower arm

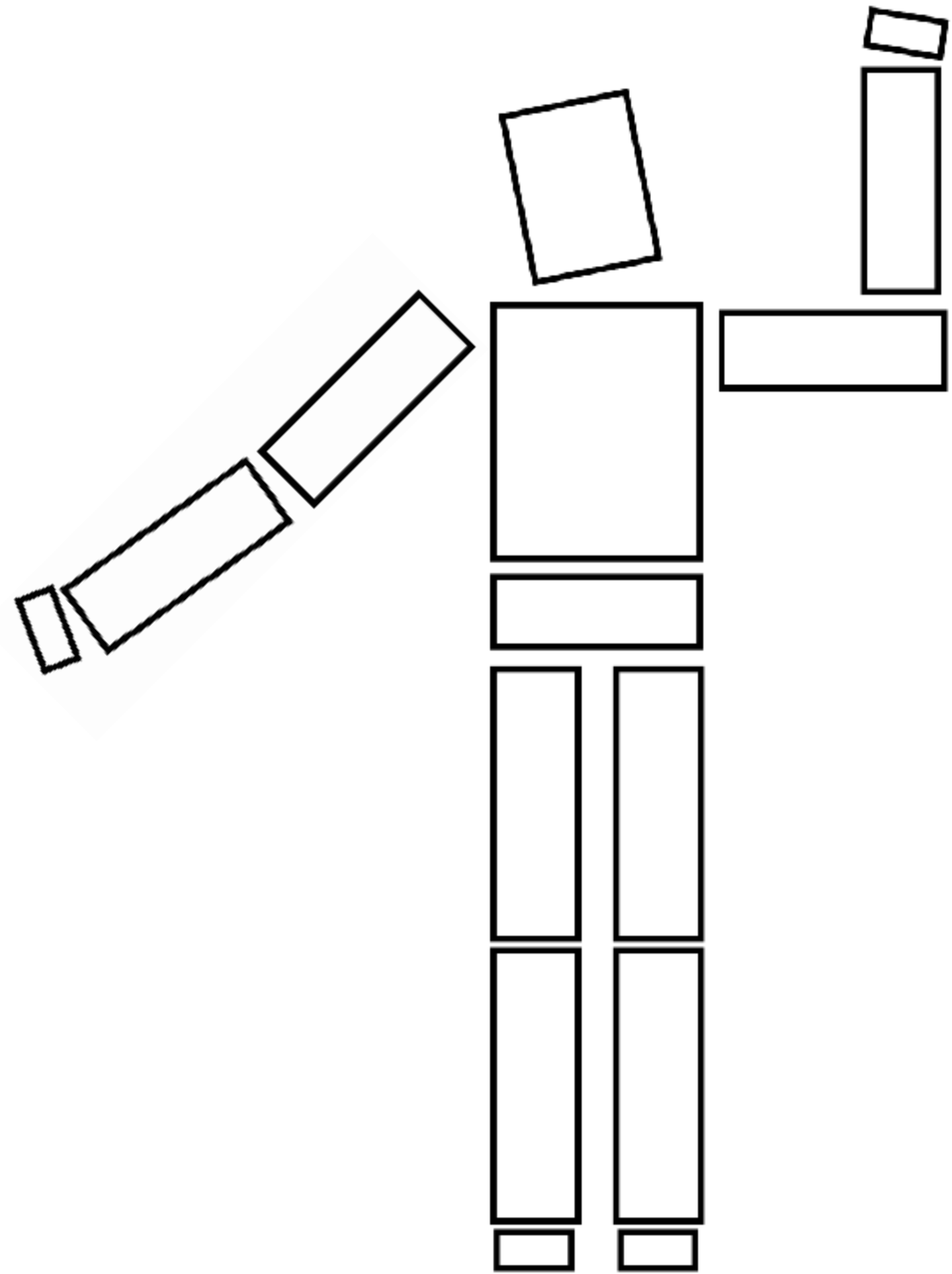
right hand

left upper leg

...

...

# Hierarchical transformations



hip

chest

head

**left upper arm**

**left lower arm**

**left hand**

right upper arm

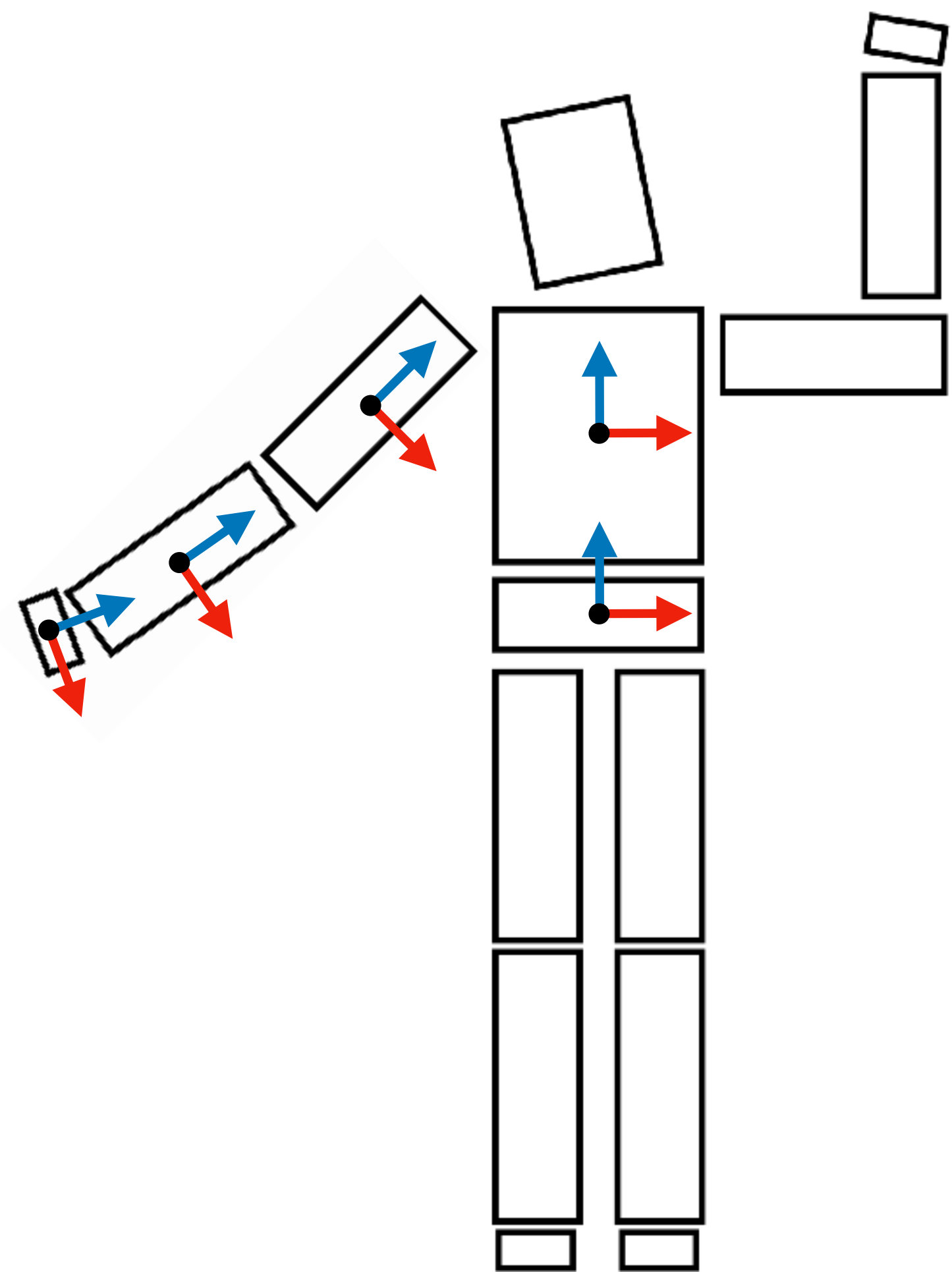
right lower arm

right hand

left upper leg

...

...



Shapes are specified in the corresponding part's **local coordinate frame**

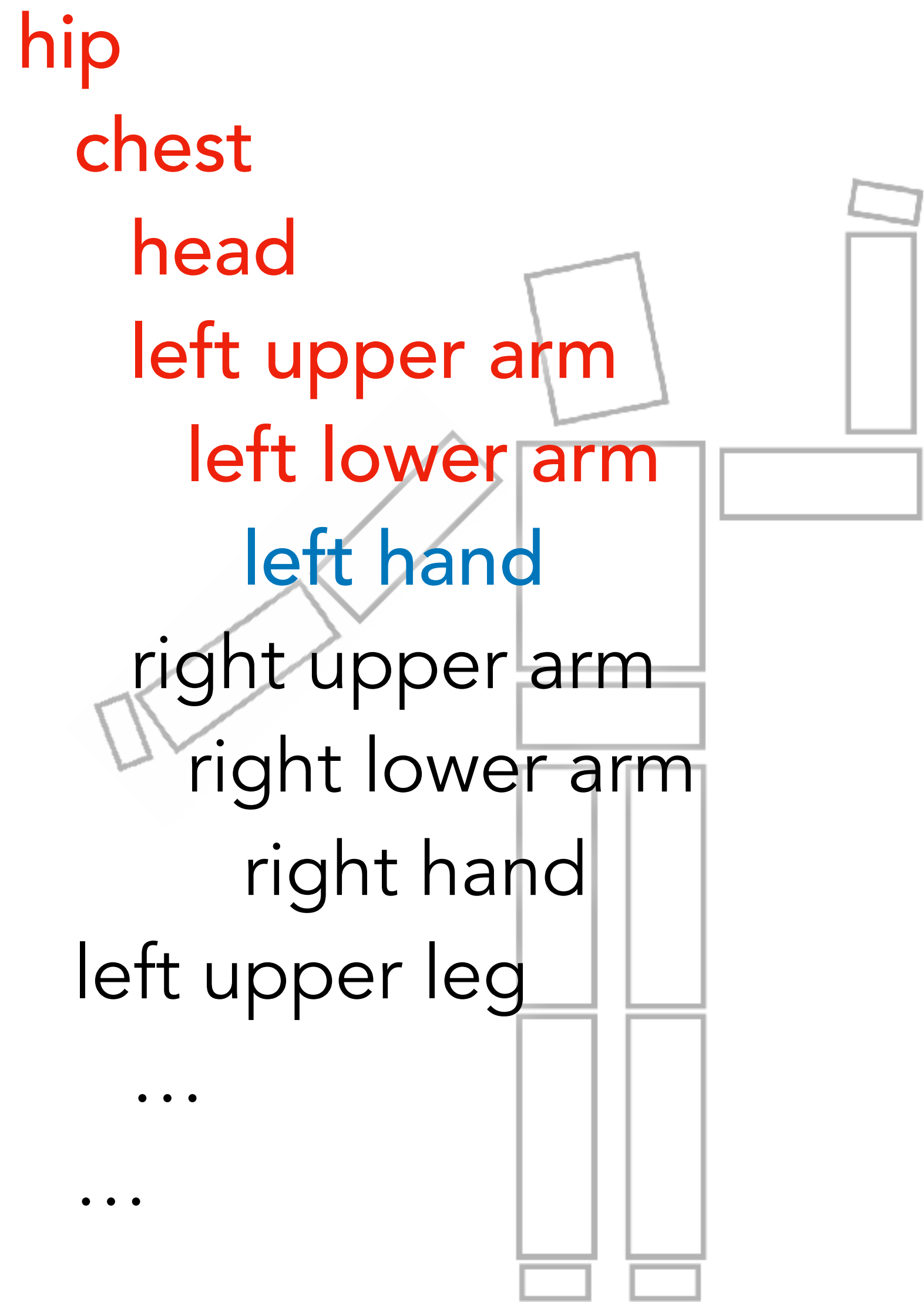
Each part's transformation is **relative** to its parent

Given point in left hand frame,

```
Vec3 world_point  
  = world_from_hip * hip_from_chest  
  * chest_from_ularm * uarm_from_llarm  
  * llarm_from_lhand * lhand_point
```

or simply

```
Mat3x3 world_from_lhand  
  = world_from_hip * hip_from_chest  
  * chest_from_ularm * uarm_from_llarm  
  * llarm_from_lhand
```



```
Mat3x3 world_from_lhand  
= world_from_hip * hip_from_chest  
* chest_from_uarm * uarm_from_llarm  
* llarm_from_lhand
```

```
Mat3x3 world_from_lhand  
= world_from_llarm * llarm_from_lhand
```

### Going down the tree:

Push parent's matrix on stack

Multiply child's matrix on right

**Going back up:** Pop parent's matrix from stack

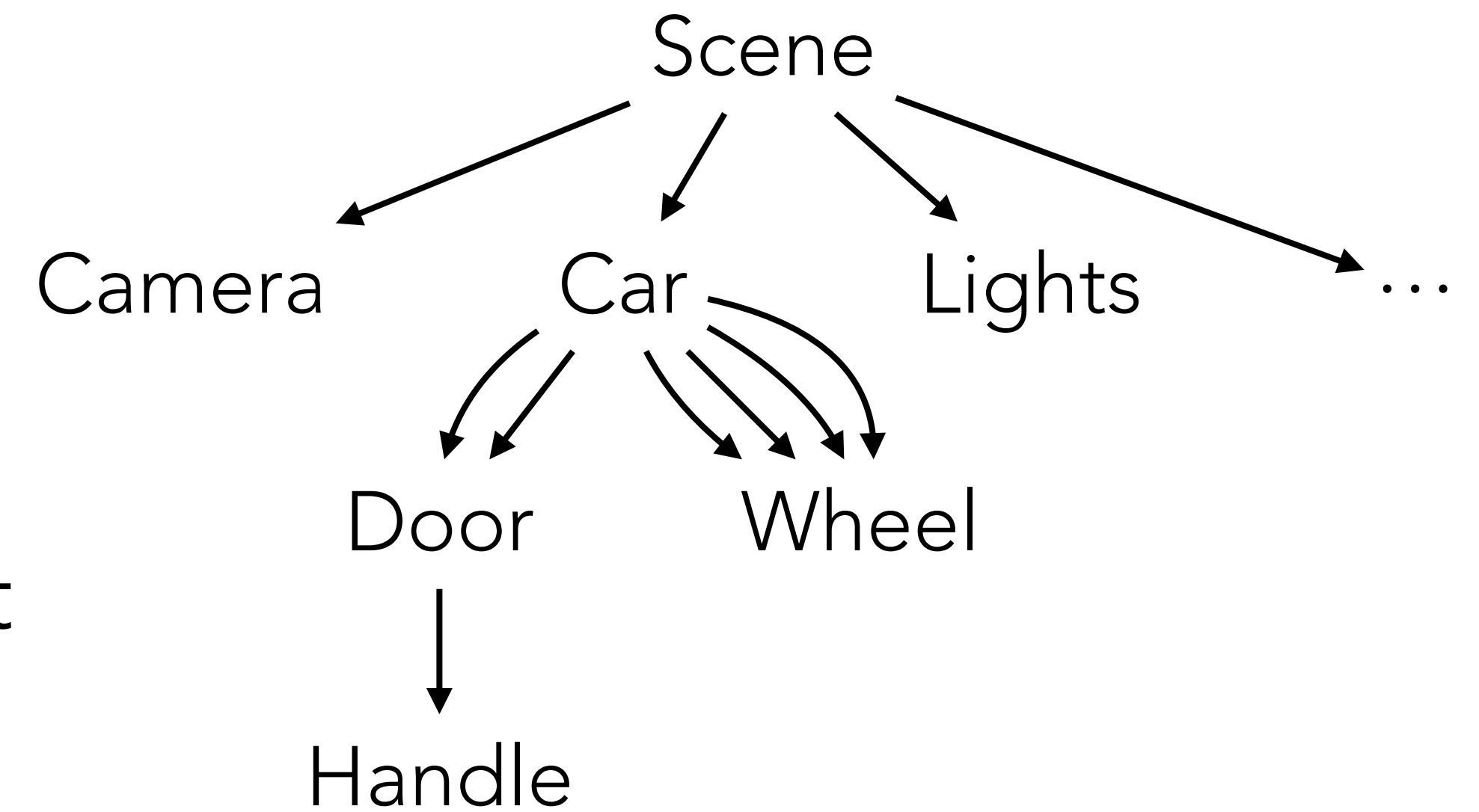
# Scene graph

Usually the entire scene is represented as a tree / DAG!

Nodes may contain geometry or other content

Edges contain transformations

Why a DAG? So we can reuse the same geometry multiple times: **instancing**



So far we know:

- How to draw 2D shapes
- How to transform 2D and 3D shapes

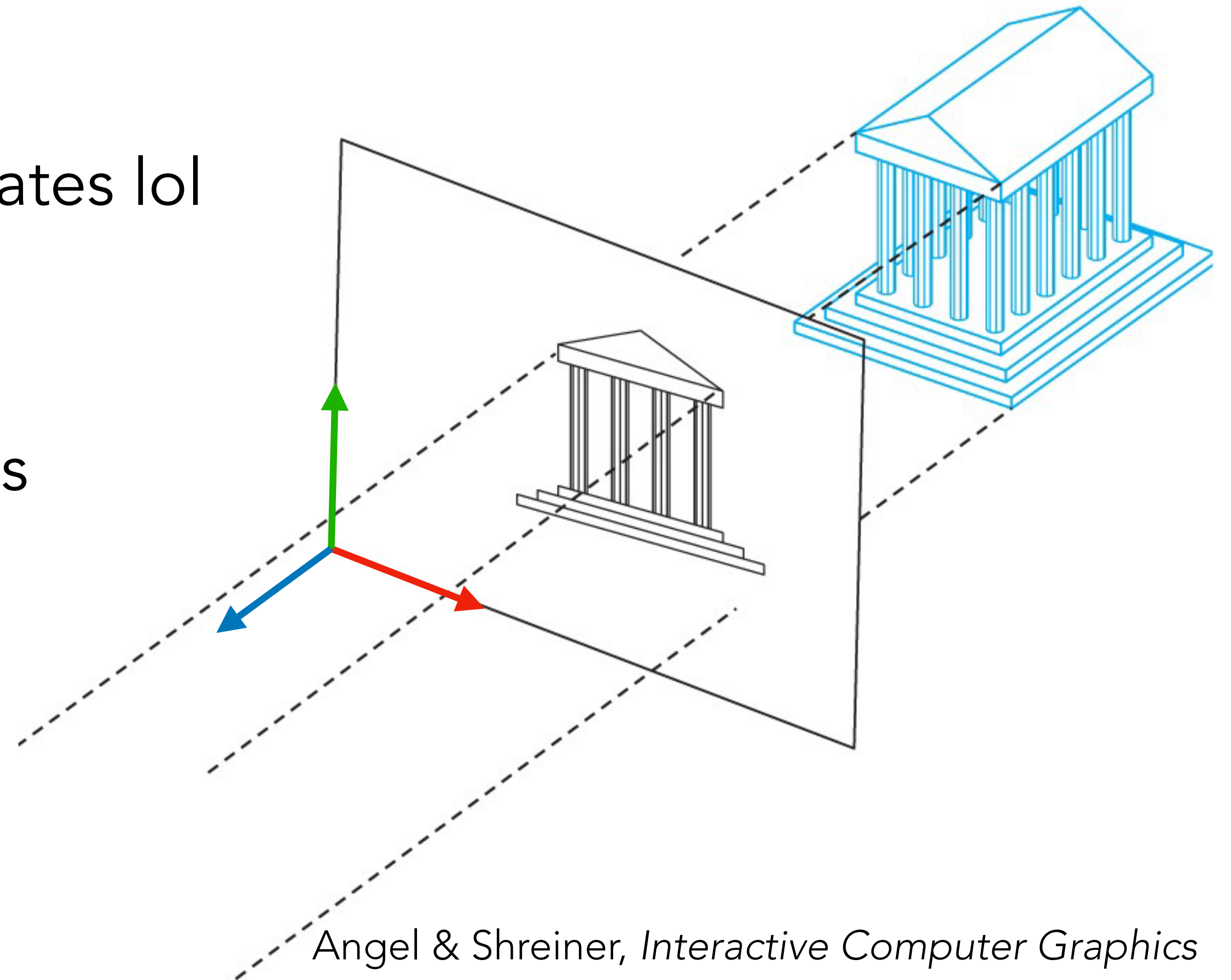
**Today:** How to draw 3D shapes on a 2D screen?



# Parallel projection

Easy way: Just drop one of the coordinates lol

- Useful for engineering drawings
- Doesn't match how eyes and cameras actually see things!

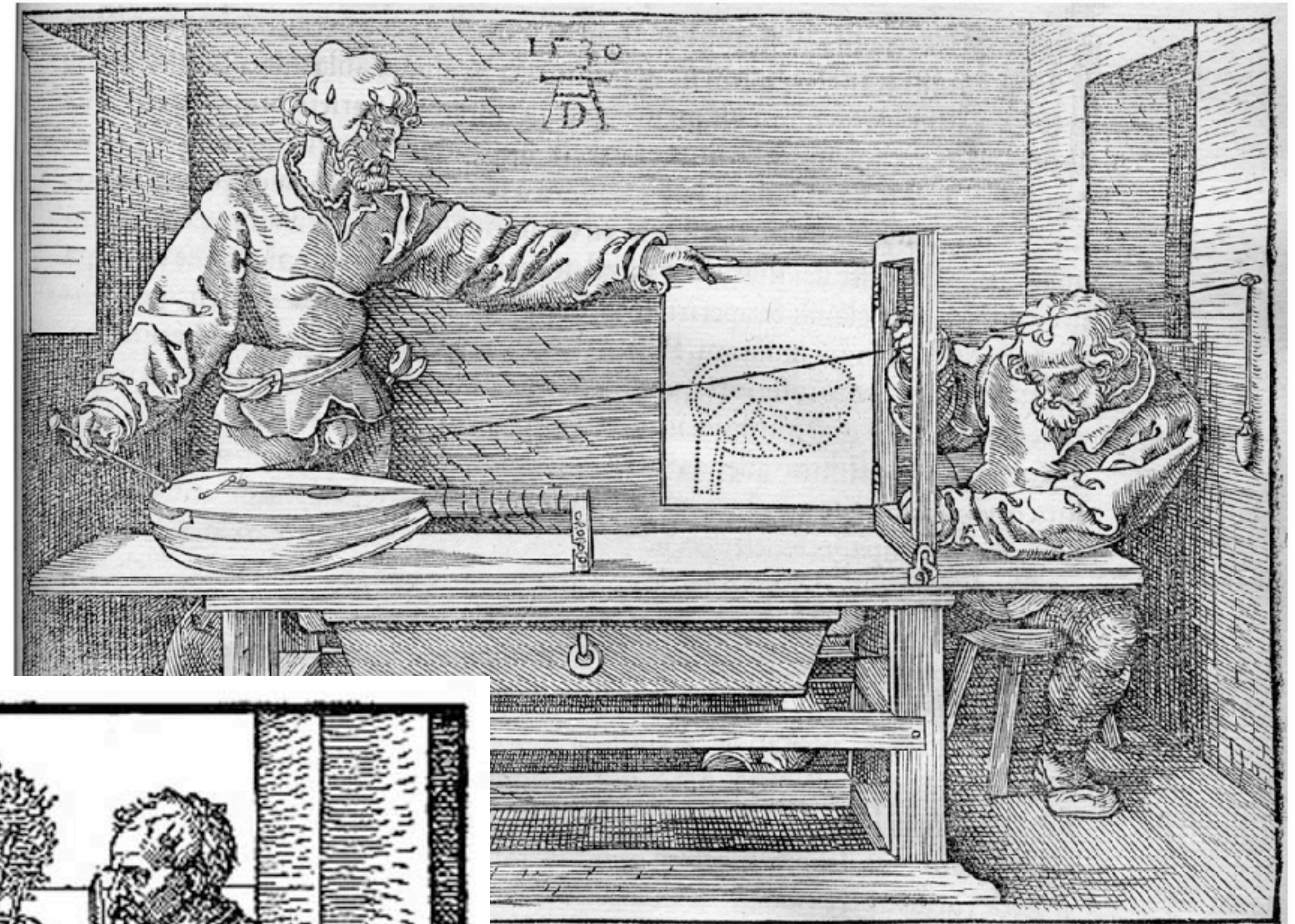


# Perspective

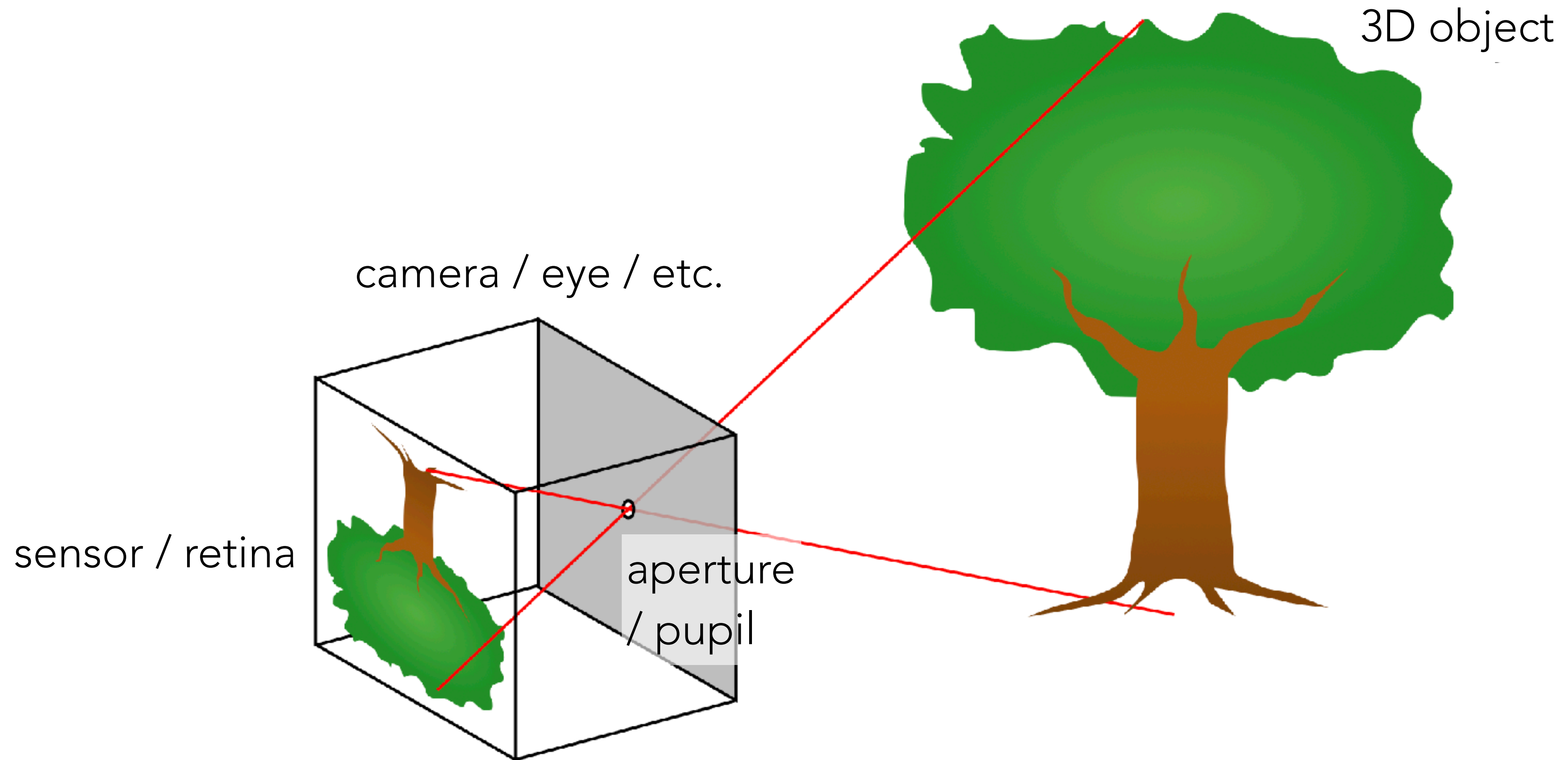


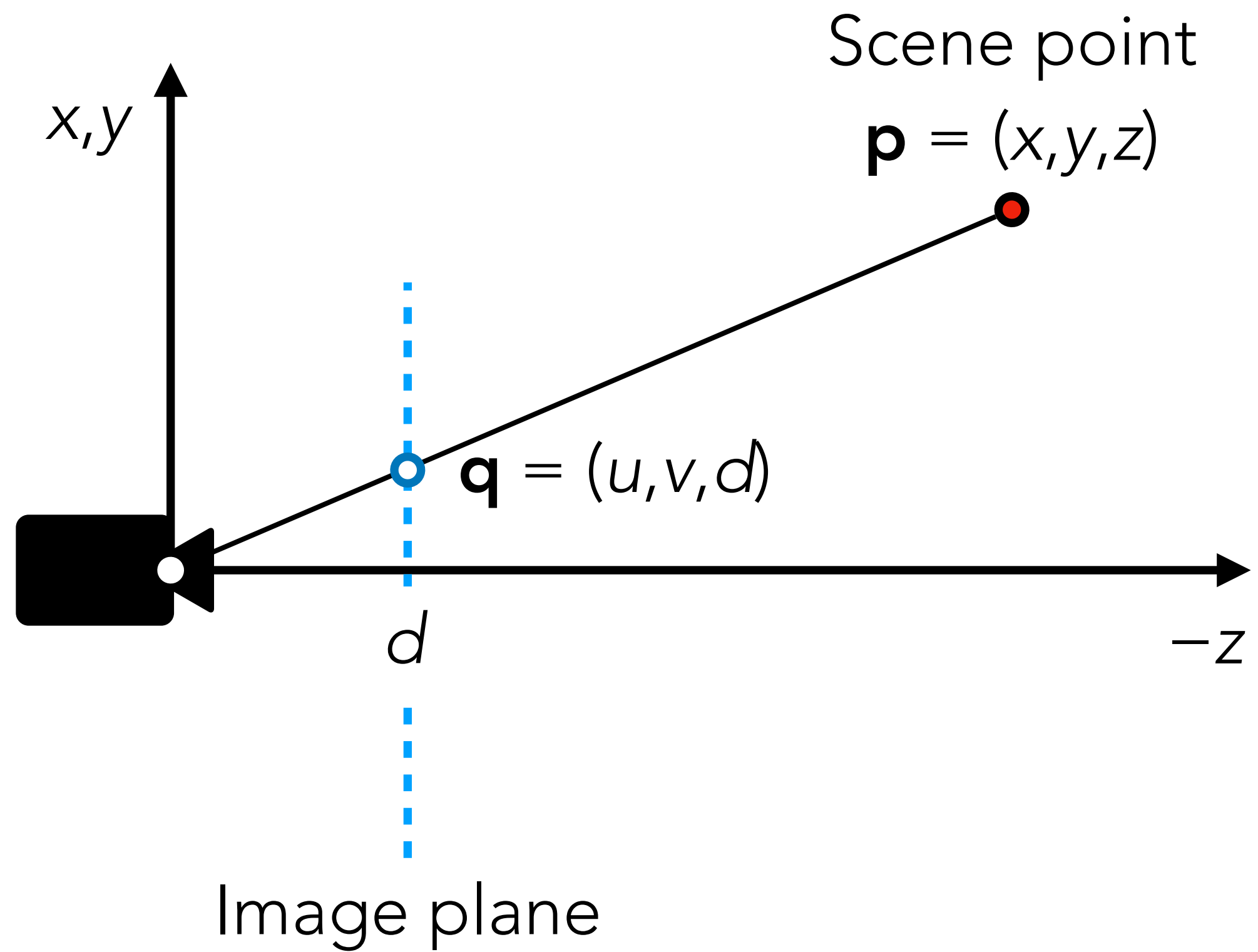
# Algorithmic drawing in the 1500s

A point is drawn where the ray from the viewpoint meets the image plane.



# Pinhole camera model





Assume camera is at the origin,  
pointing in the direction  $-z$ .

Where is the point  $\mathbf{p}$  projected to?

$$\frac{x}{z} = \frac{u}{d}$$

$$u = \frac{xd}{z}$$

Similarly  $v = yd/z$

(W.l.o.g., let's take  $d = -1$ )

What if the camera is not at the origin and/or not looking along  $-z$ ?



Just change to a coordinate system in which it is.

# Viewing transformation

Usually, user specifies:

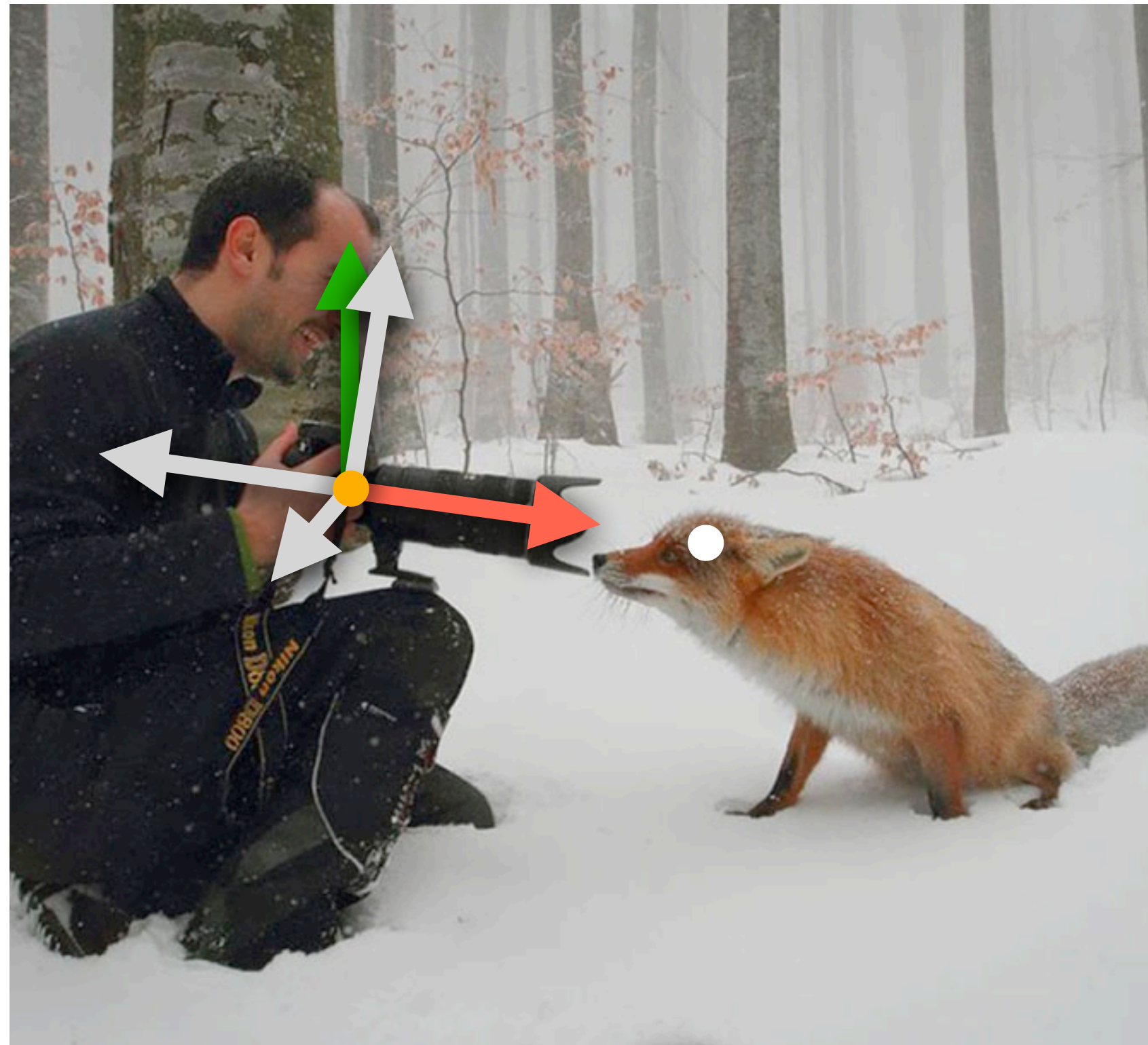
- center of projection **c**
- target point **t** or view vector **v** =  $(\mathbf{t}-\mathbf{c})/\|\mathbf{t}-\mathbf{c}\|$
- "up vector" **u**

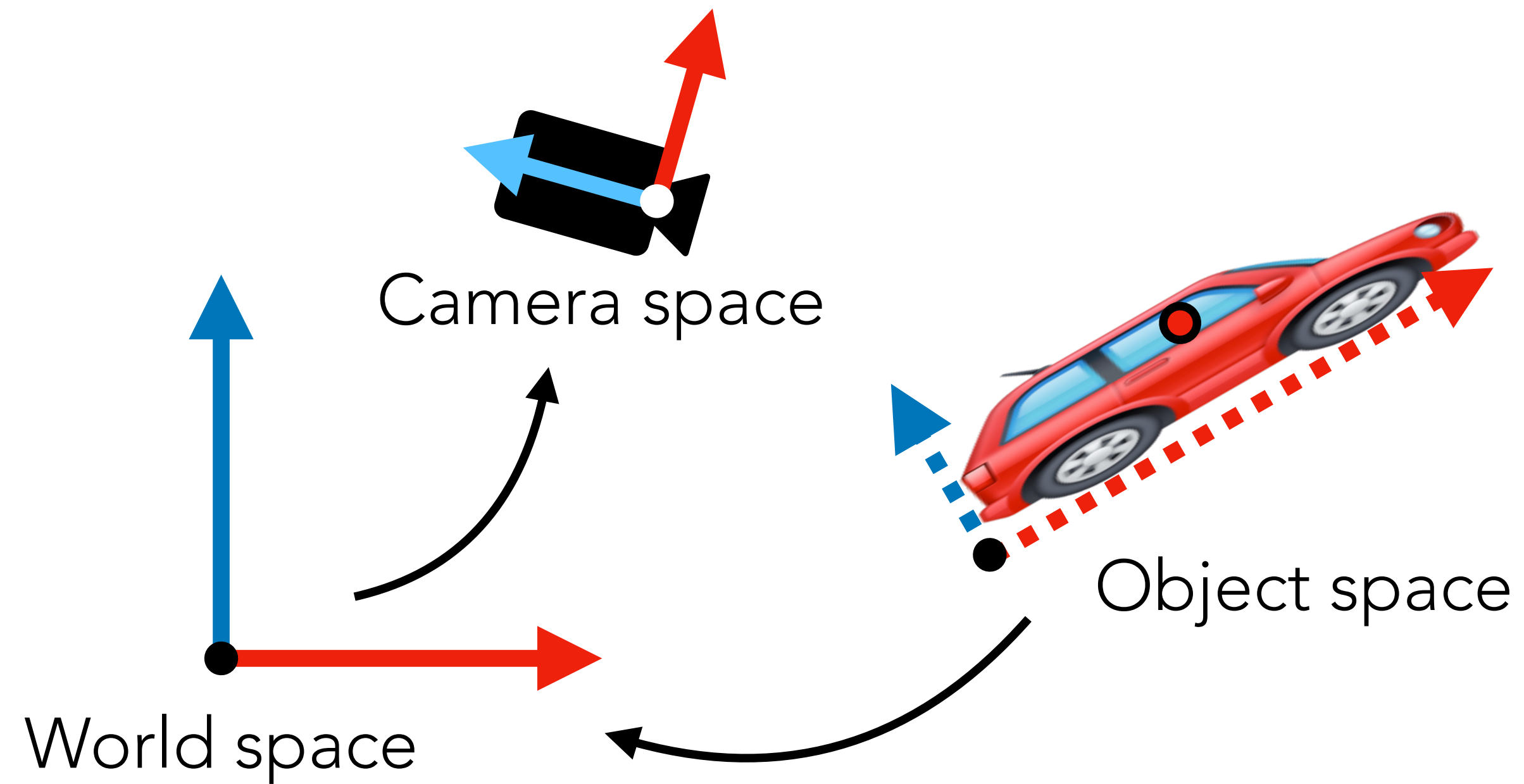
Construct orthonormal basis

$$\mathbf{e}_2 = (\mathbf{v} \times \mathbf{u}) / \|\mathbf{v} \times \mathbf{u}\|$$

$$\mathbf{e}_1 = \mathbf{v} \times \mathbf{e}_2$$

$$\mathbf{e}_3 = -\mathbf{v}$$



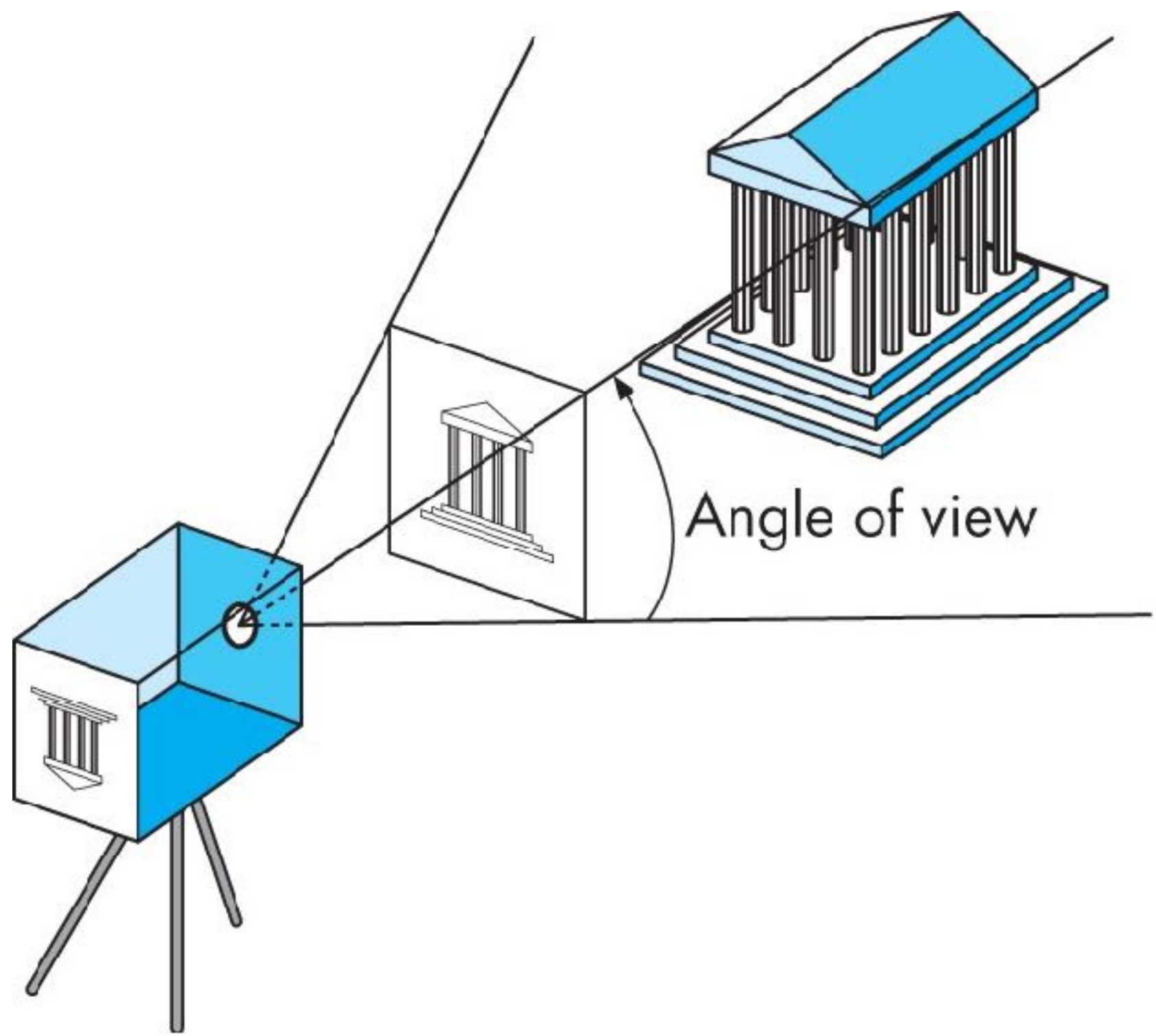


Camera  $\rightarrow$  world:  $\mathbf{M} = [\mathbf{e}_1 \ \mathbf{e}_2 \ \mathbf{e}_3 \ \mathbf{c}]$

World  $\rightarrow$  camera:  $\mathbf{M}^{-1}$

Once point is in camera space, projected point =  $\begin{bmatrix} xd/z \\ yd/z \end{bmatrix}$





16mm



24mm



50mm

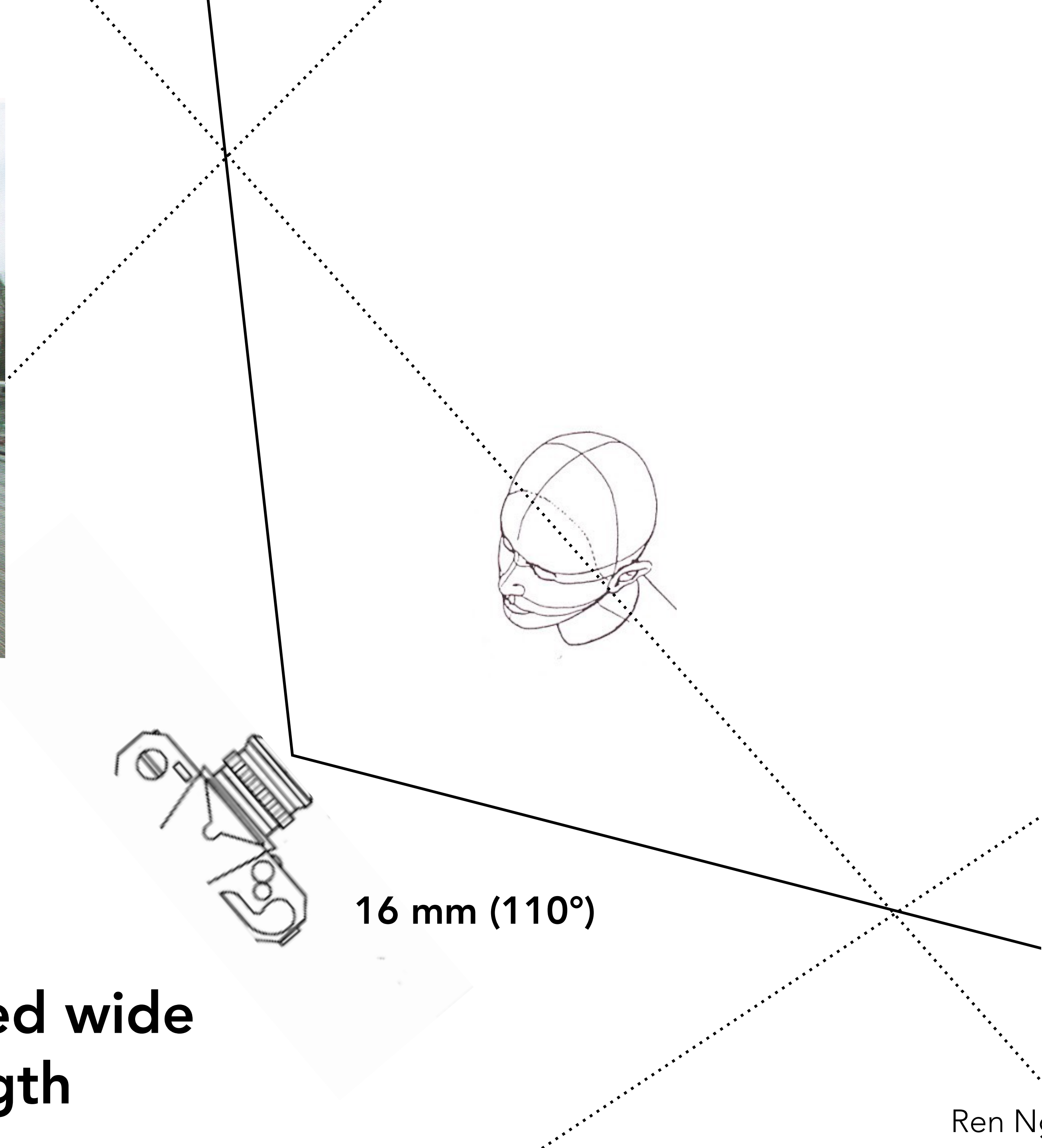


200mm

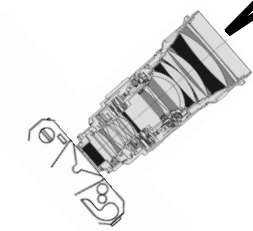
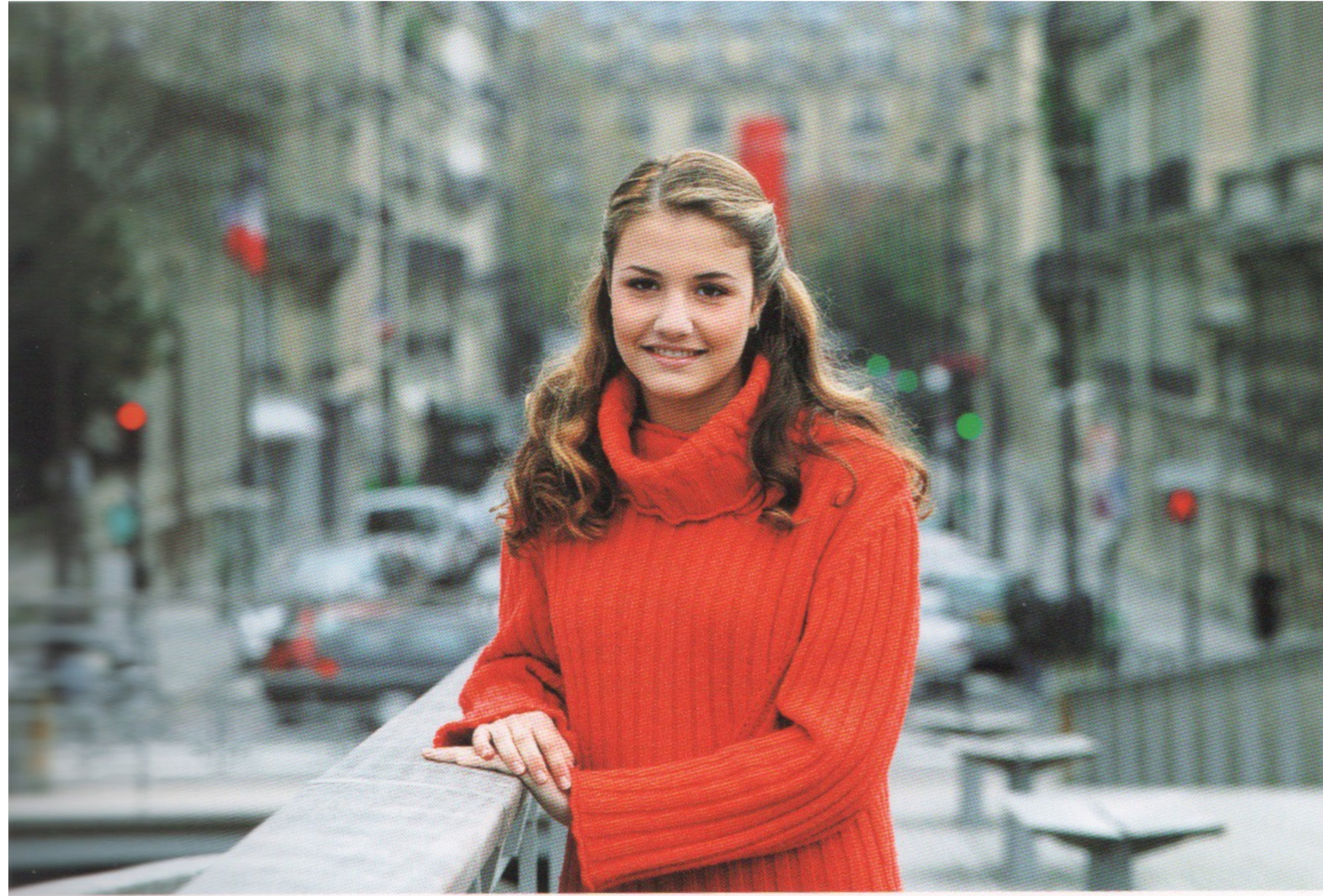


135mm



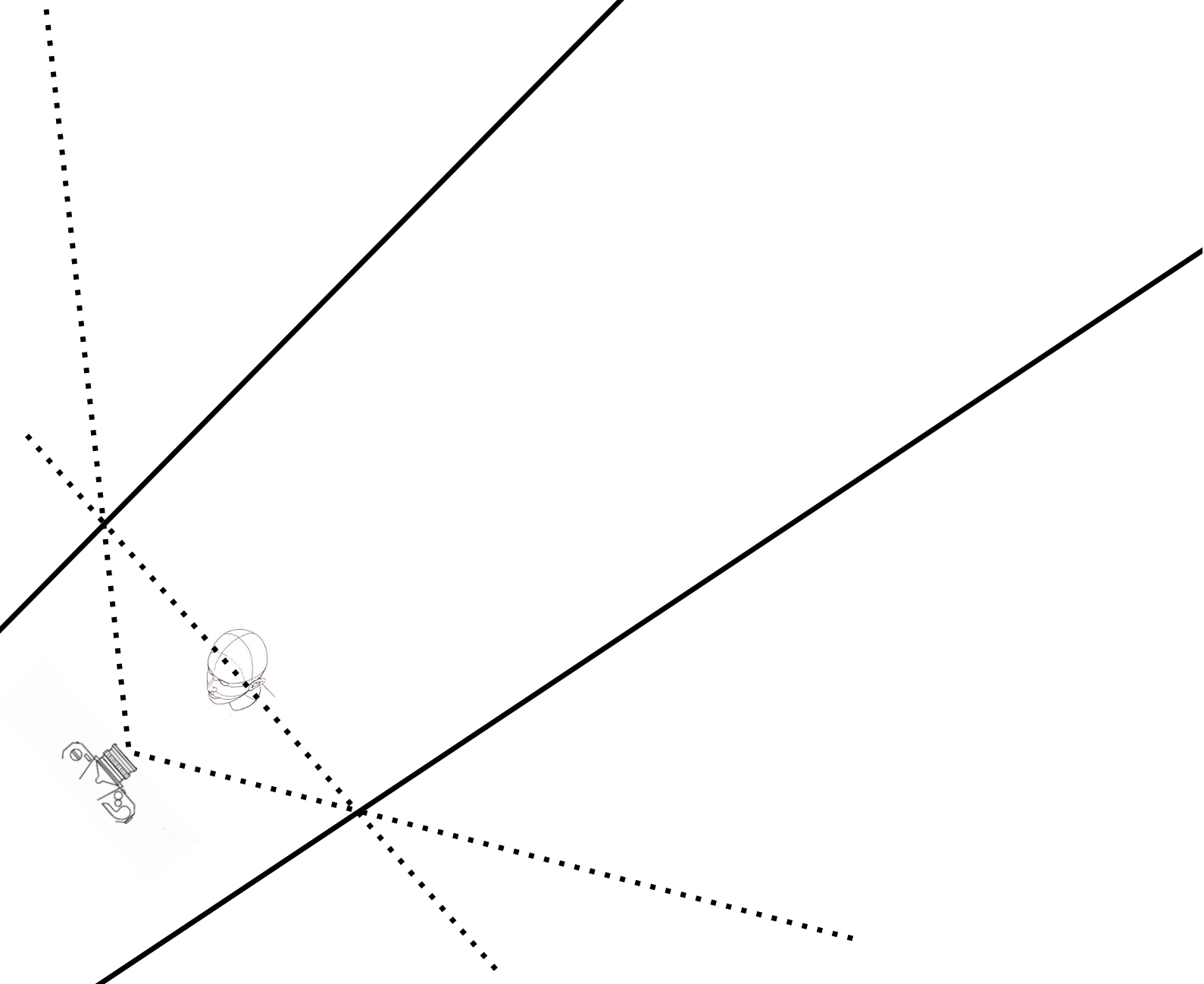


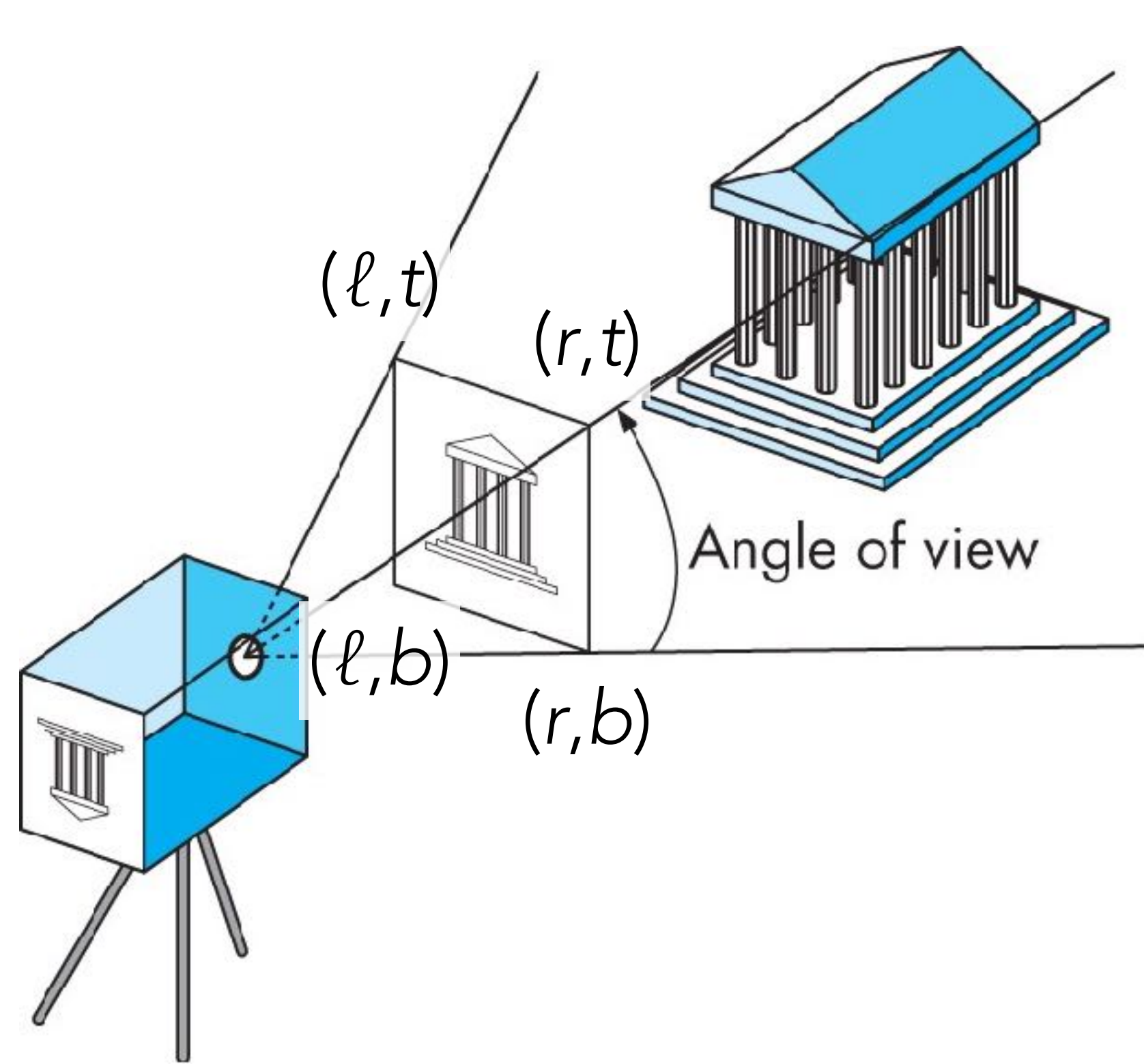
**Up close and zoomed wide  
with short focal length**



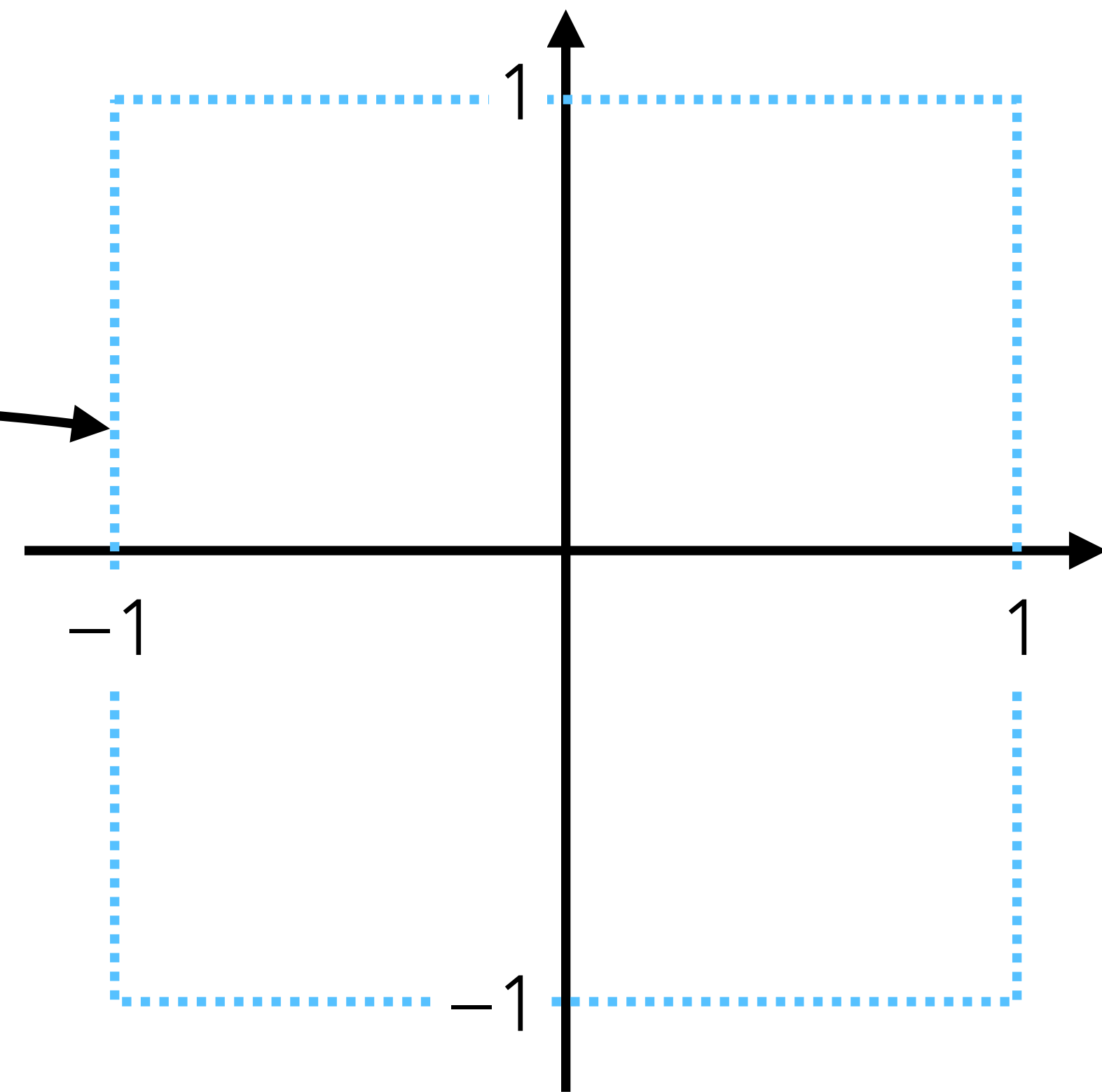
200 mm (12°)

**Walk back and zoom in  
with long focal length**





Coordinates after perspective division



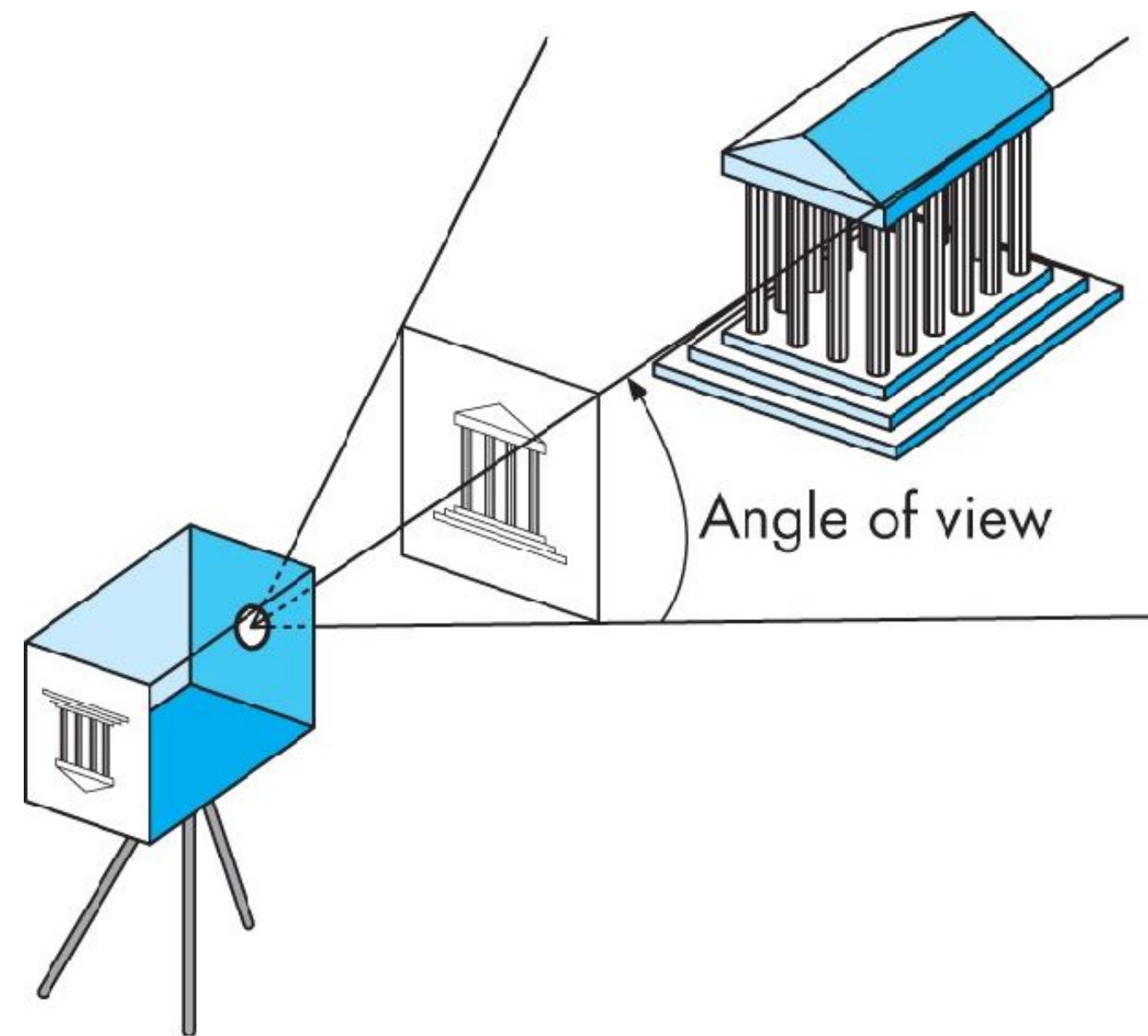
"Normalized device coordinates"

(Actually there's a bit more in NDC... Will correct later!)

Choose transformation so that points in field of view fall inside  $[-1, 1] \times [-1, 1]$

## Puzzle:

What is the maximum possible angle of view in perspective projection?



Why does no graphics application or game let you set your angle of view to anything remotely close to it?



Angle of view: 90°



Angle of view: 120°

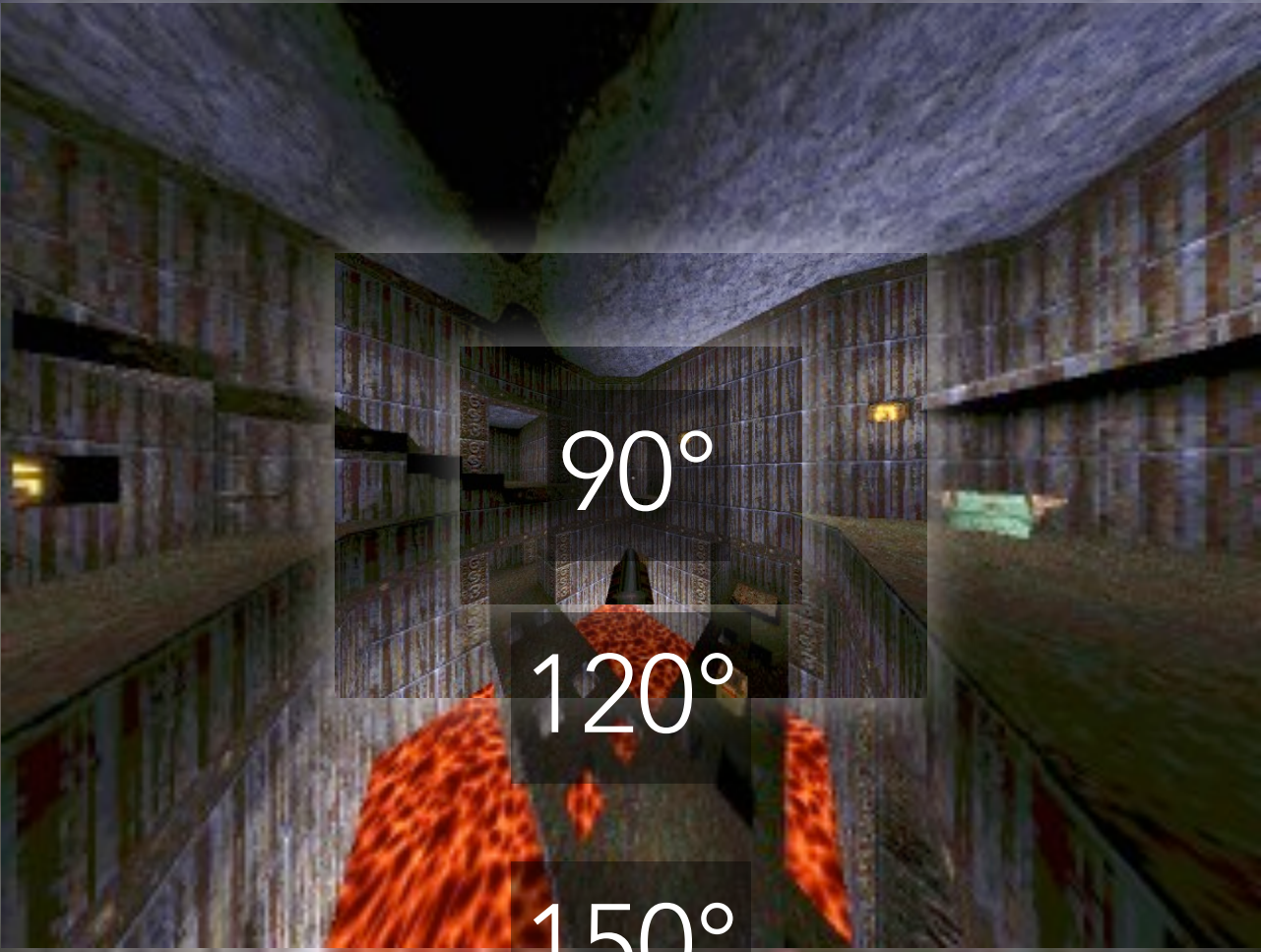
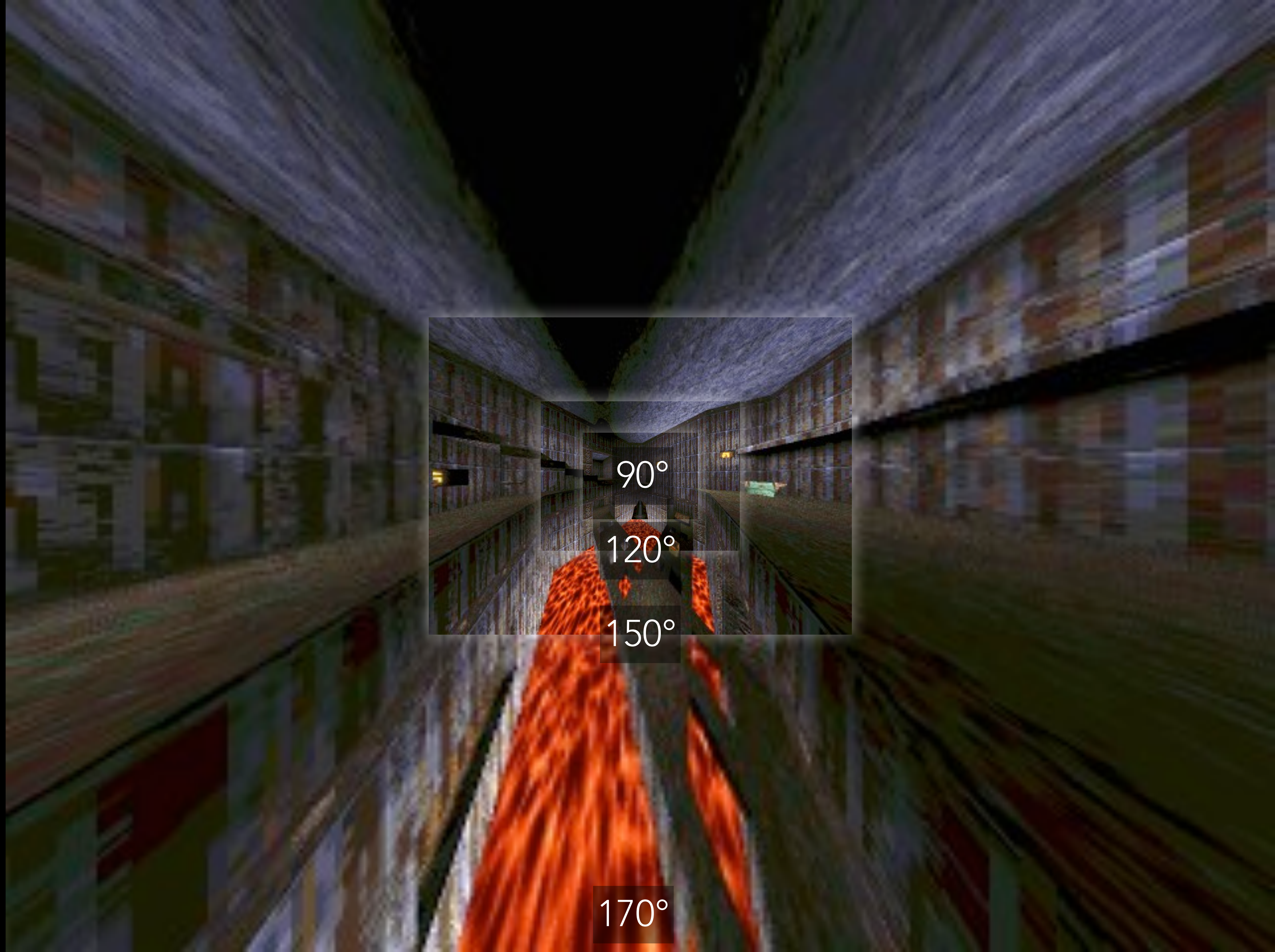


Angle of view: 150°





Angle of view: 170°

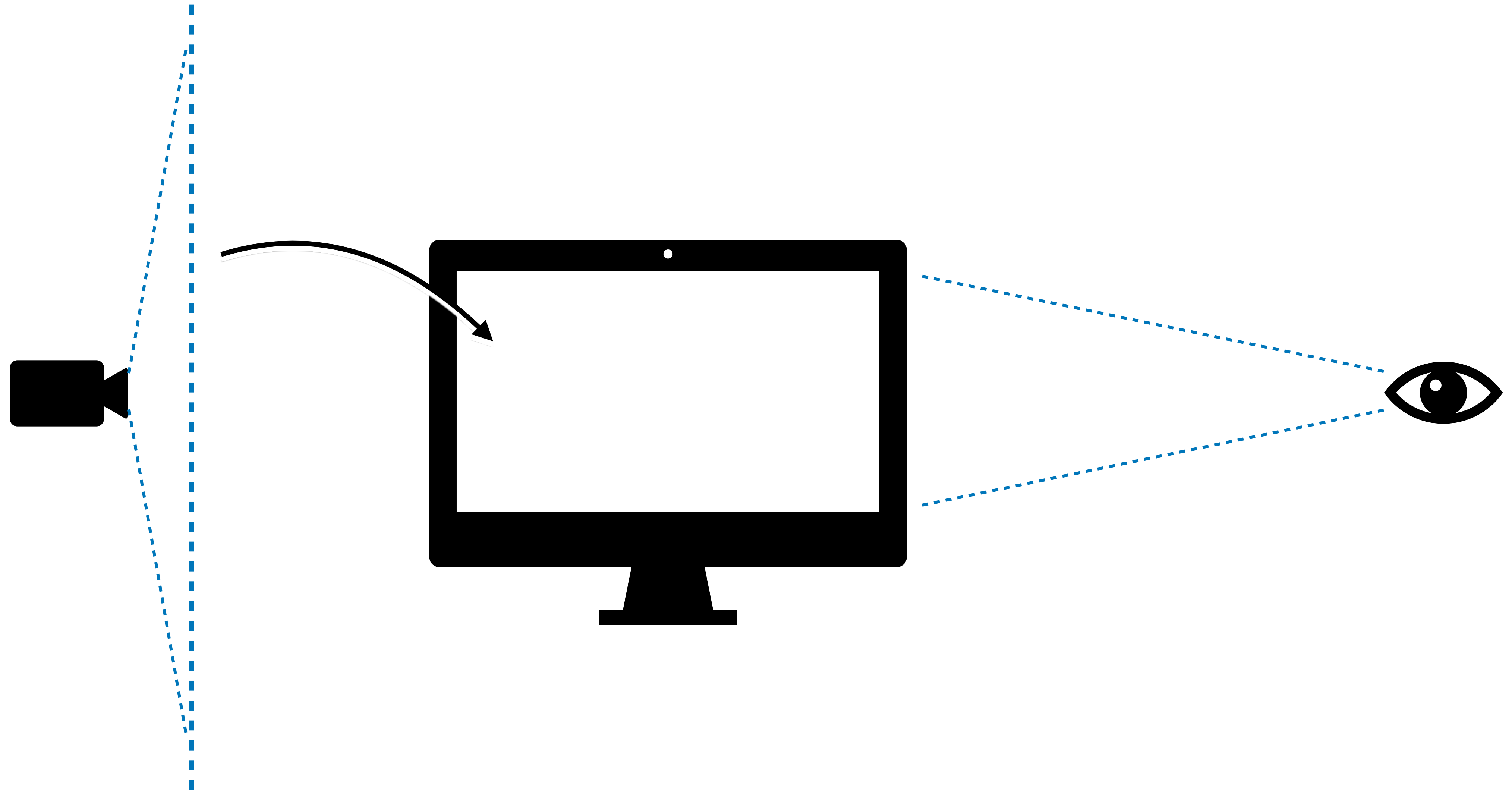


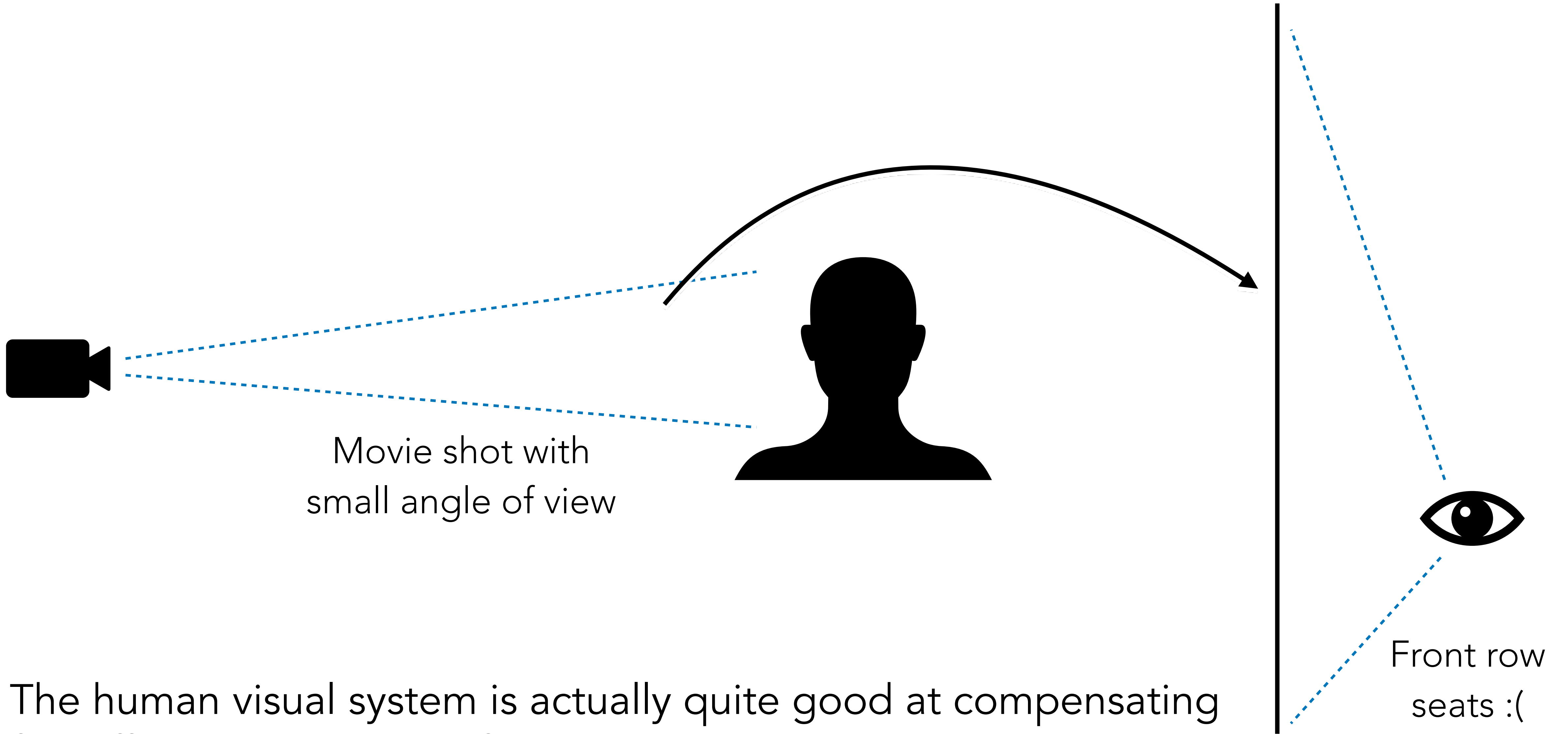
90°

120°

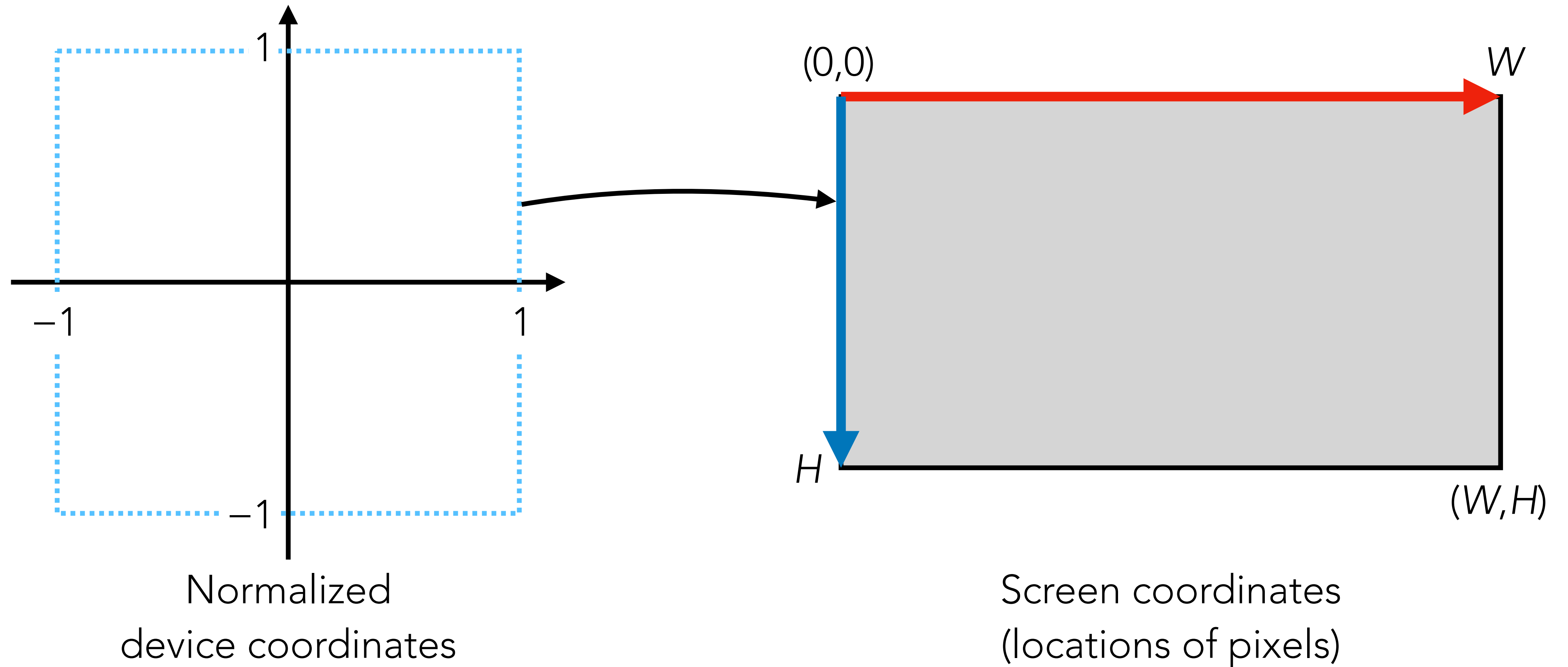
150°

170°

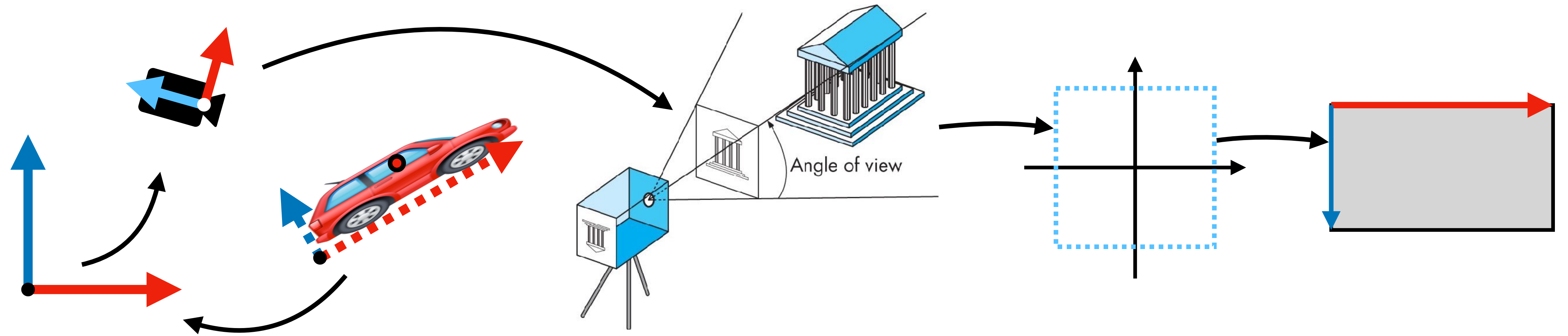




The human visual system is actually quite good at compensating for differences in angle of view... but only up to a point.



And finally, we can rasterize our triangles!



- Object space  $\rightarrow$  world space
- World space  $\rightarrow$  camera space
- Camera space  $\rightarrow$  projection plane (division by  $z$ )
- Projection plane  $\rightarrow$  NDC
- NDC  $\rightarrow$  screen coordinates

Two problems:

- Every step is a matrix, **except perspective division.**
- Final result has lost depth information (the  $z$  coordinate): don't know which points are in front of which

# Homework exercise: DIY 3D GFX

**Draw a cube!** (manually, or with Excel, or using a plotting library)

Start with vertices at  $(\pm 1, \pm 1, \pm 1)$ , translate somewhere along  $-z$ , maybe apply some rotation, then draw the projected points and join them with edges.

Translated by  $(2, 3, -5)$ ,  
no rotation

