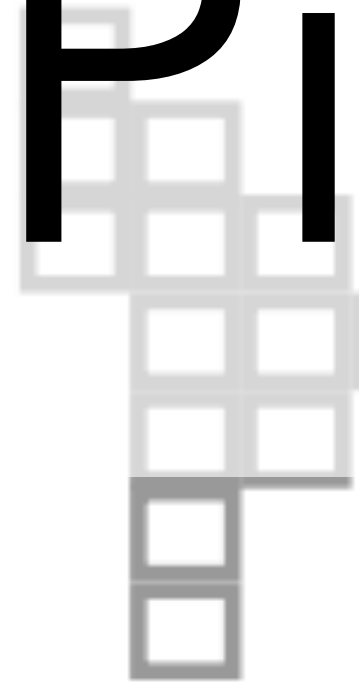


# COL781: Computer Graphics

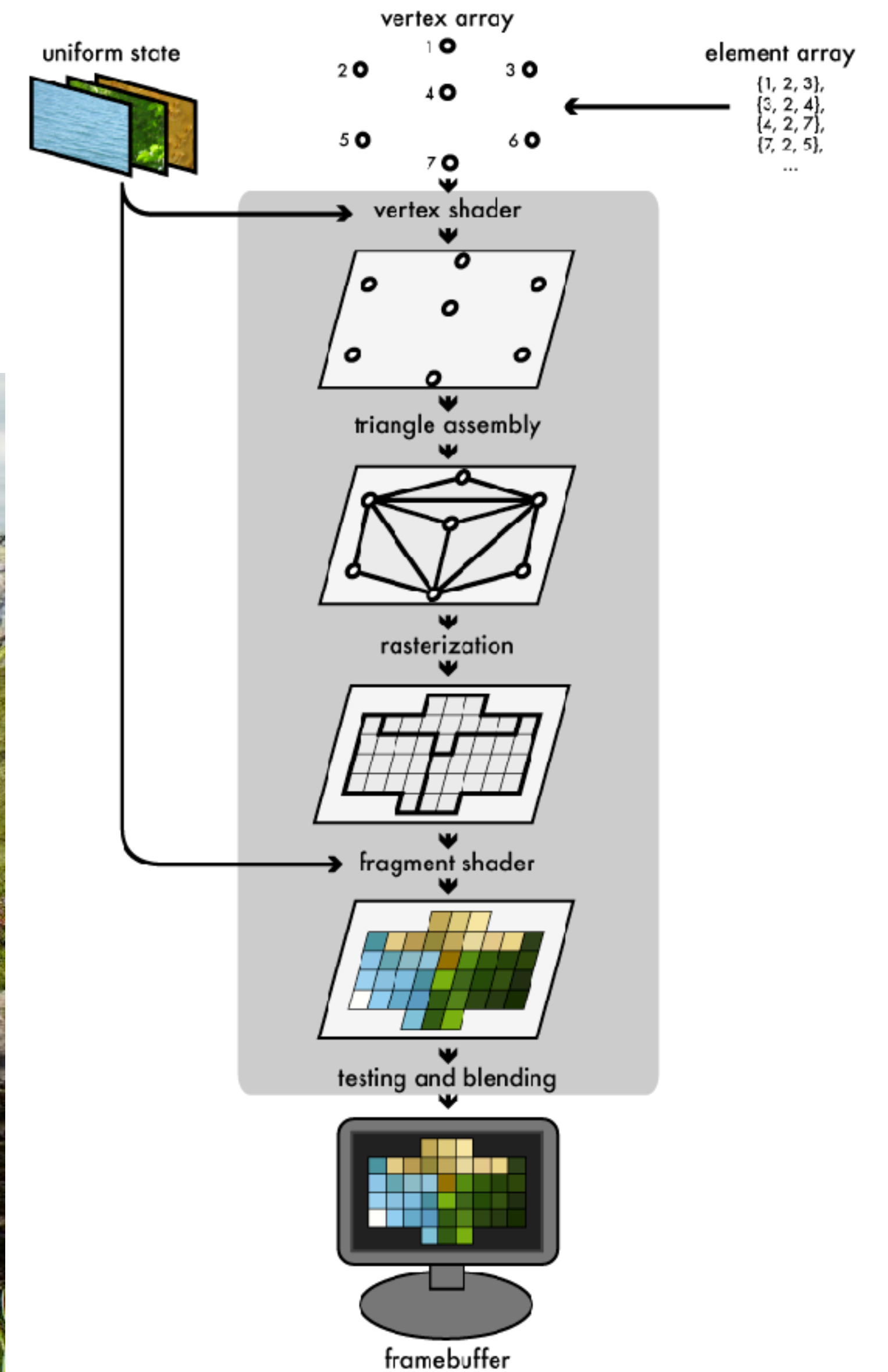
## 10. The Rasterization Pipeline

### Pipeline

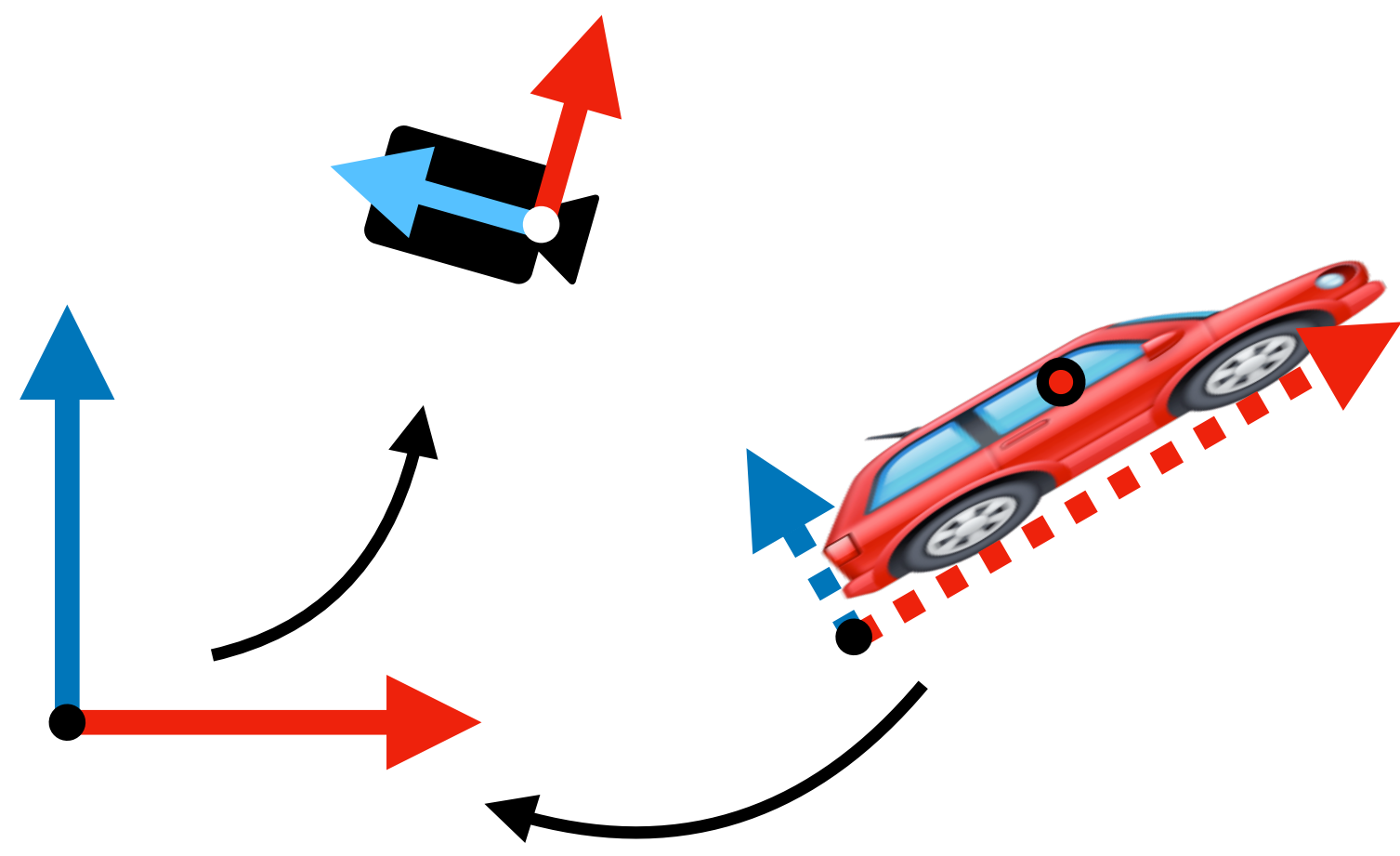




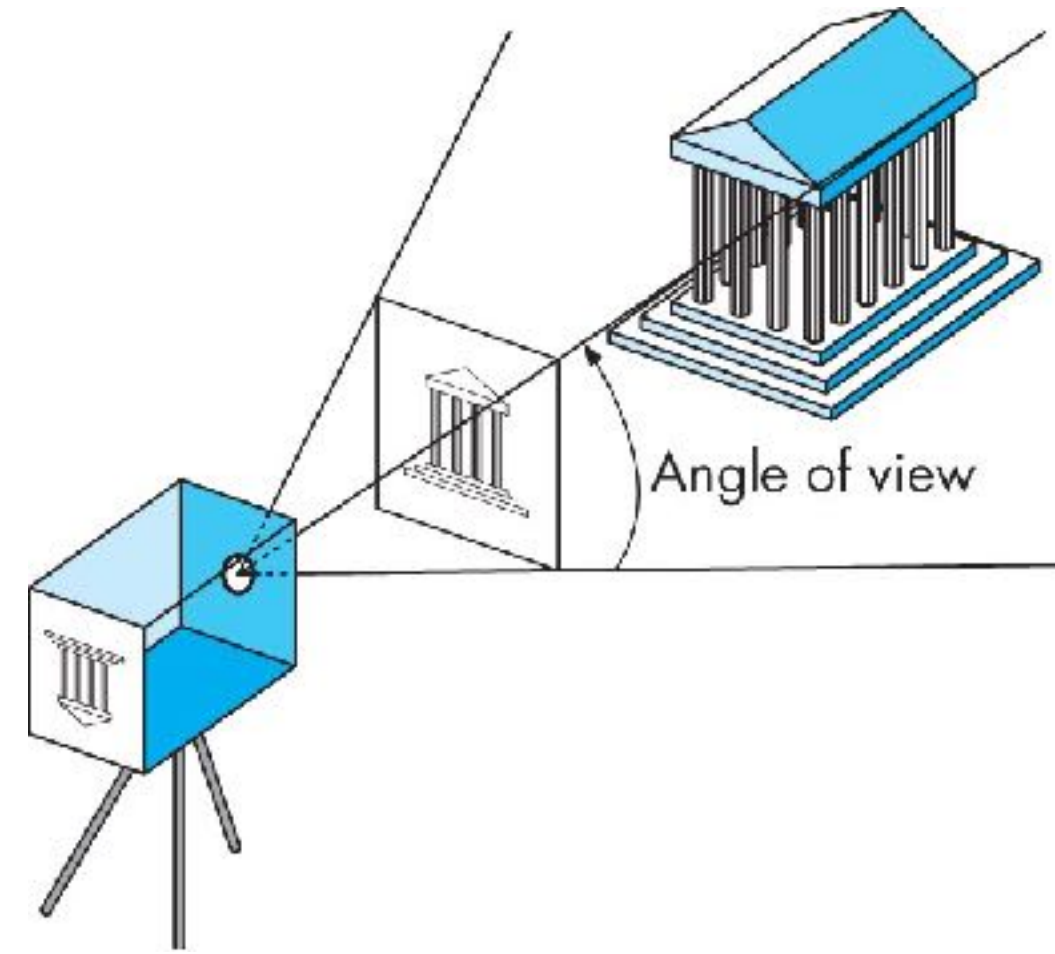
# Today: Putting it all together



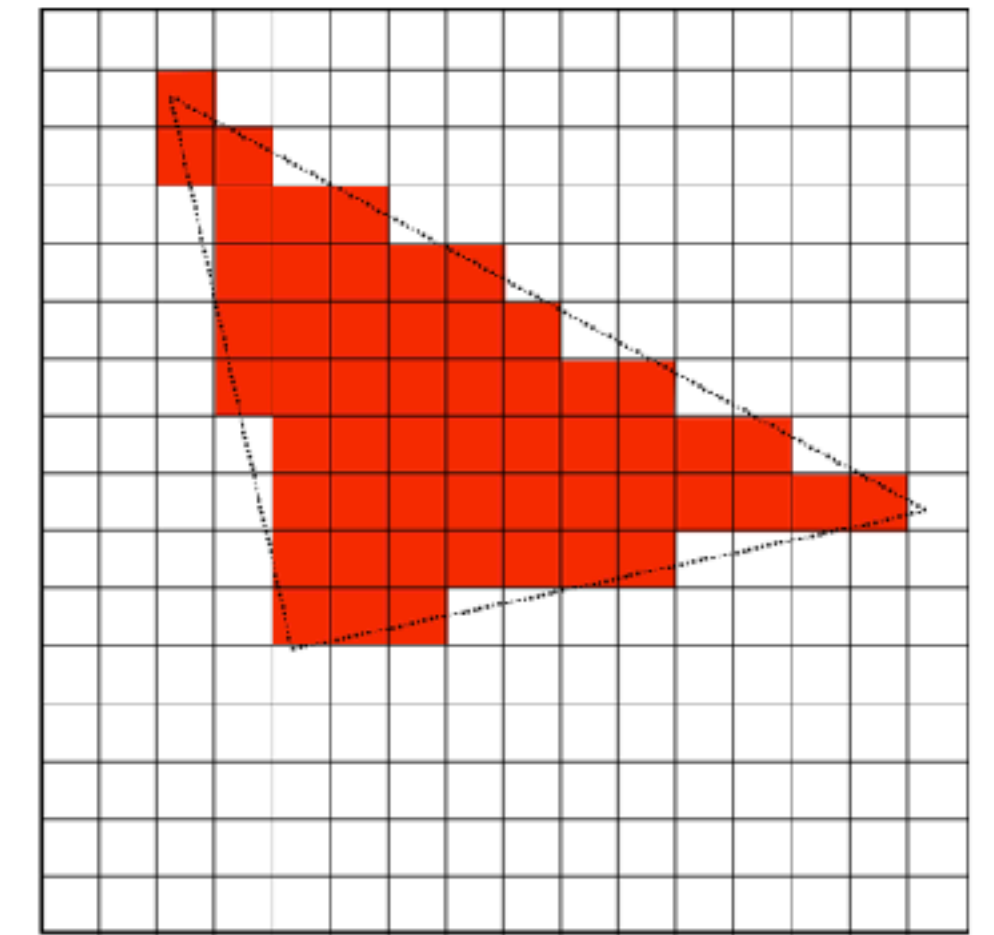




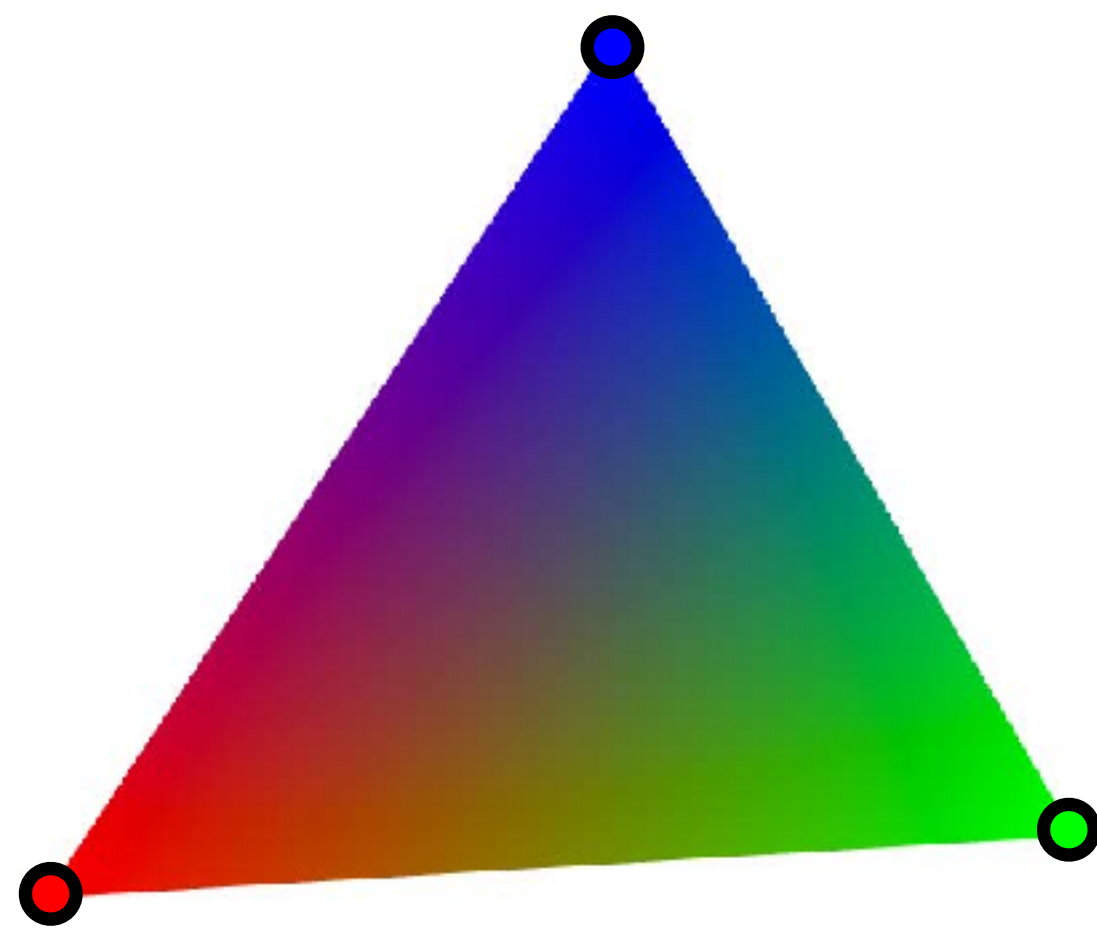
Transformations



Projection



Rasterization



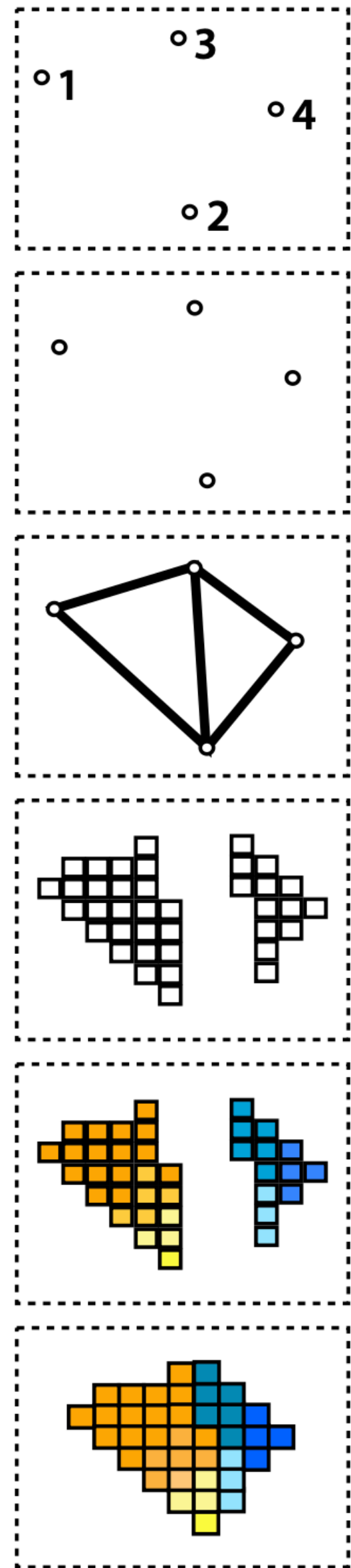
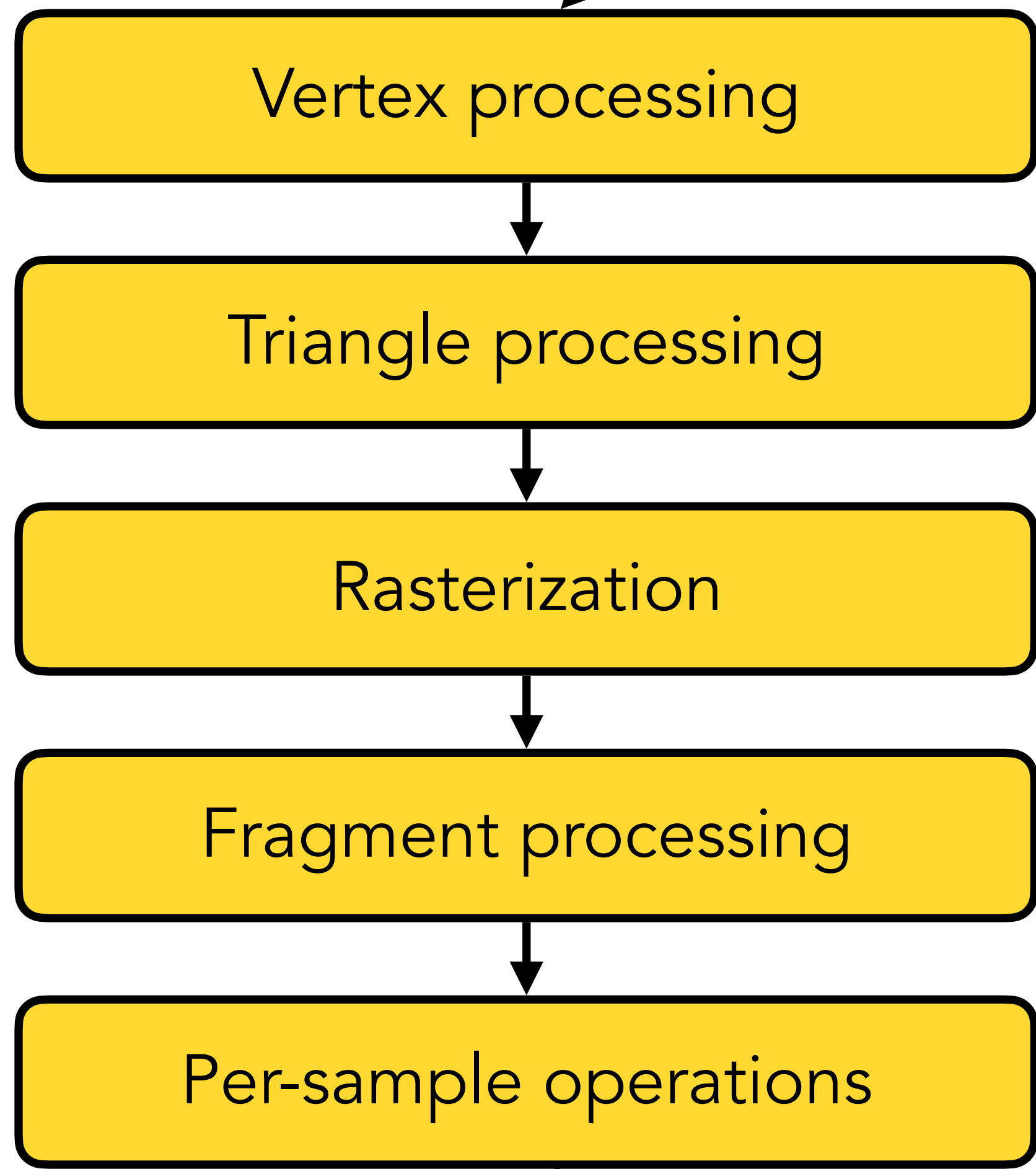
Interpolation



Texture mapping



Visibility



Input: vertices in 3D space

Vertices in NDC

Triangles in screen space

Fragments

Shaded fragments

Output: image in framebuffer

# Inputs to the pipeline

For each object, we have two streams:

- Vertices with various **attributes** (position, colour, texture coordinates, etc.)
- Indices of triangles (or other primitives)

Why? Each vertex is shared between many primitives

We also have **uniform** data, common to all vertices/triangles of an object:

- Transformation matrices, texture images, etc.



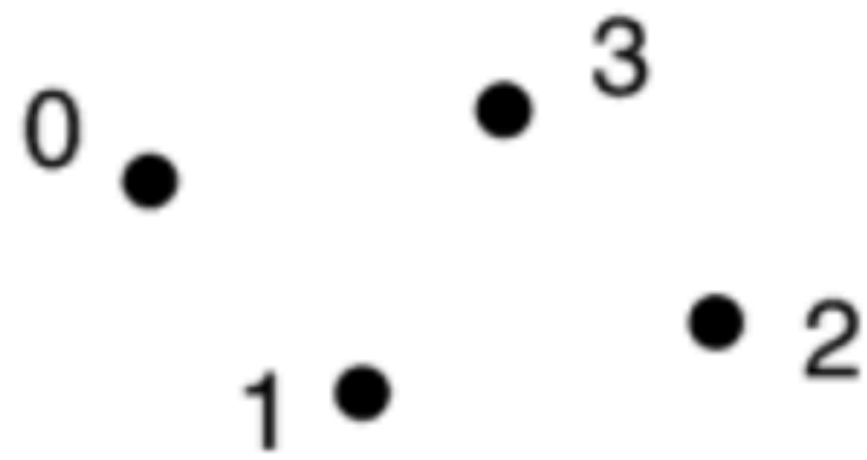
## VERTICES

A: ( 1, 1, 1) E: ( 1, 1, -1)  
B: (-1, 1, 1) F: (-1, 1, -1)  
C: ( 1, -1, 1) G: ( 1, -1, -1)  
D: (-1, -1, 1) H: (-1, -1, -1)

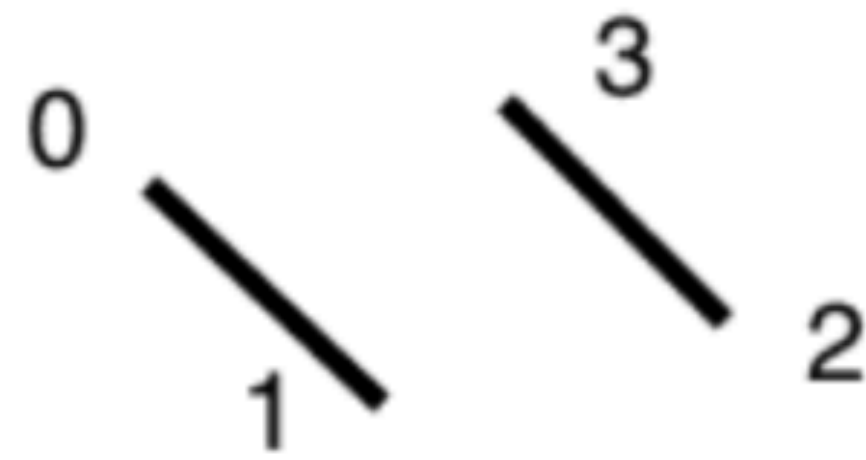
## TRIANGLES

EHF, GFH, FGB, CBG,  
GHC, DCH, ABD, CDB,  
HED, ADE, EFA, BAF

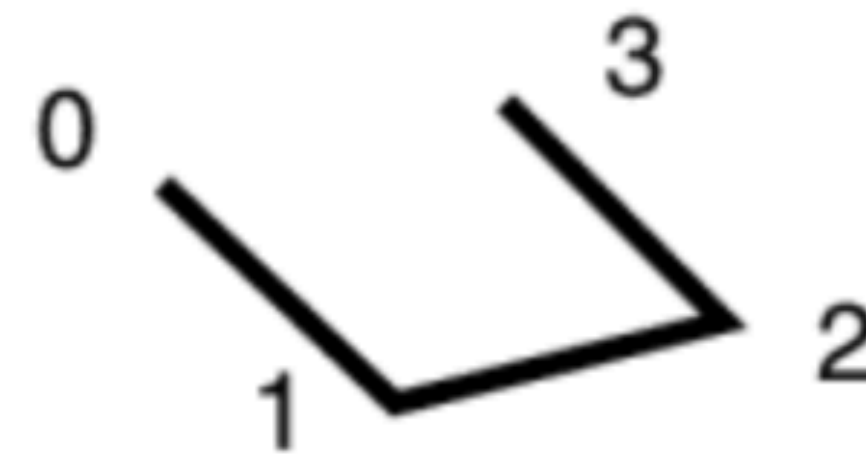
# Primitives



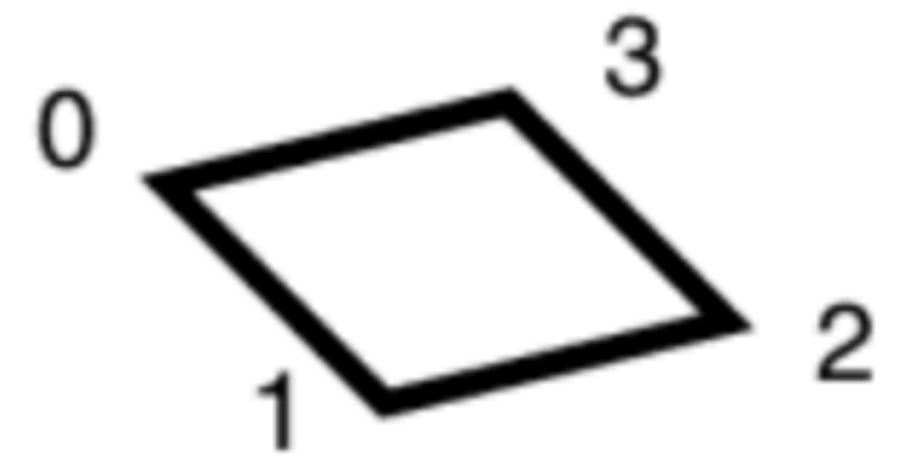
GL\_POINTS



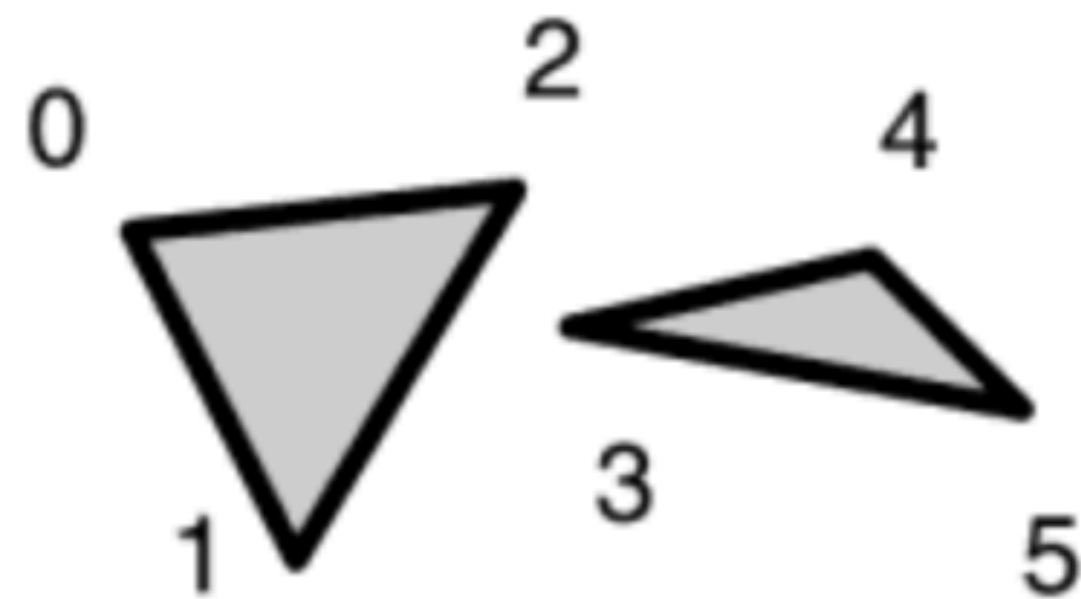
GL\_LINES



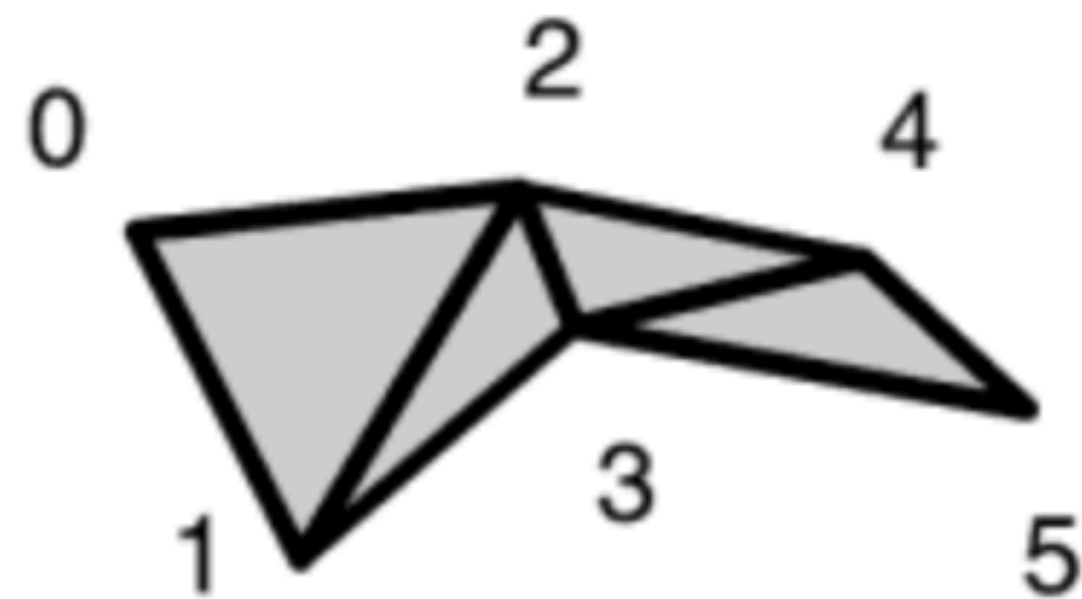
GL\_LINE\_STRIP



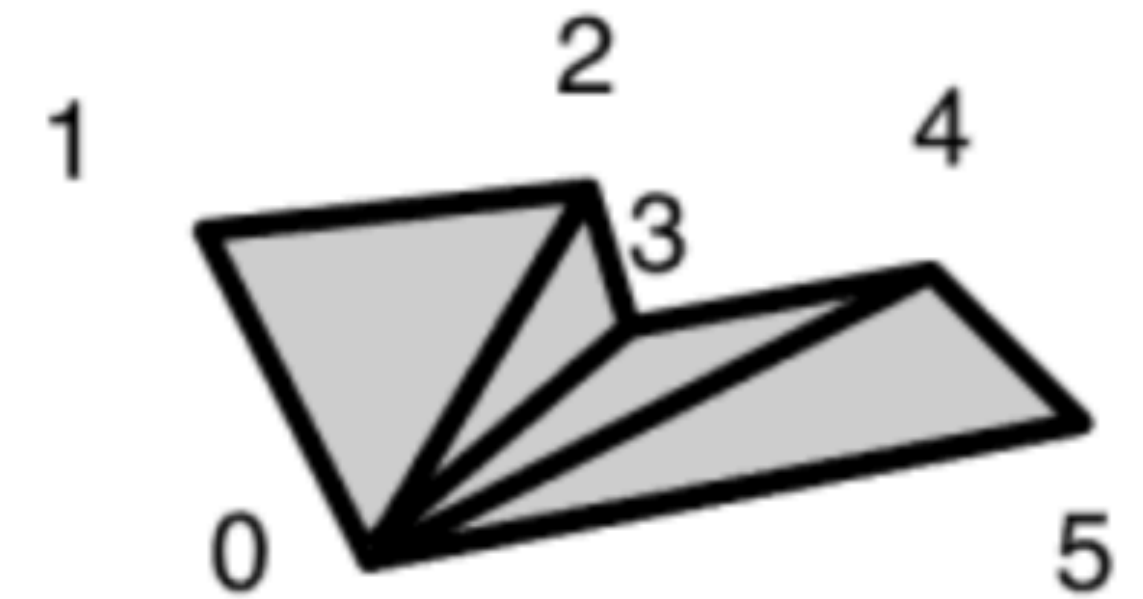
GL\_LINE\_LOOP



GL\_TRIANGLES



GL\_TRIANGLE\_STRIP



GL\_TRIANGLE\_FAN



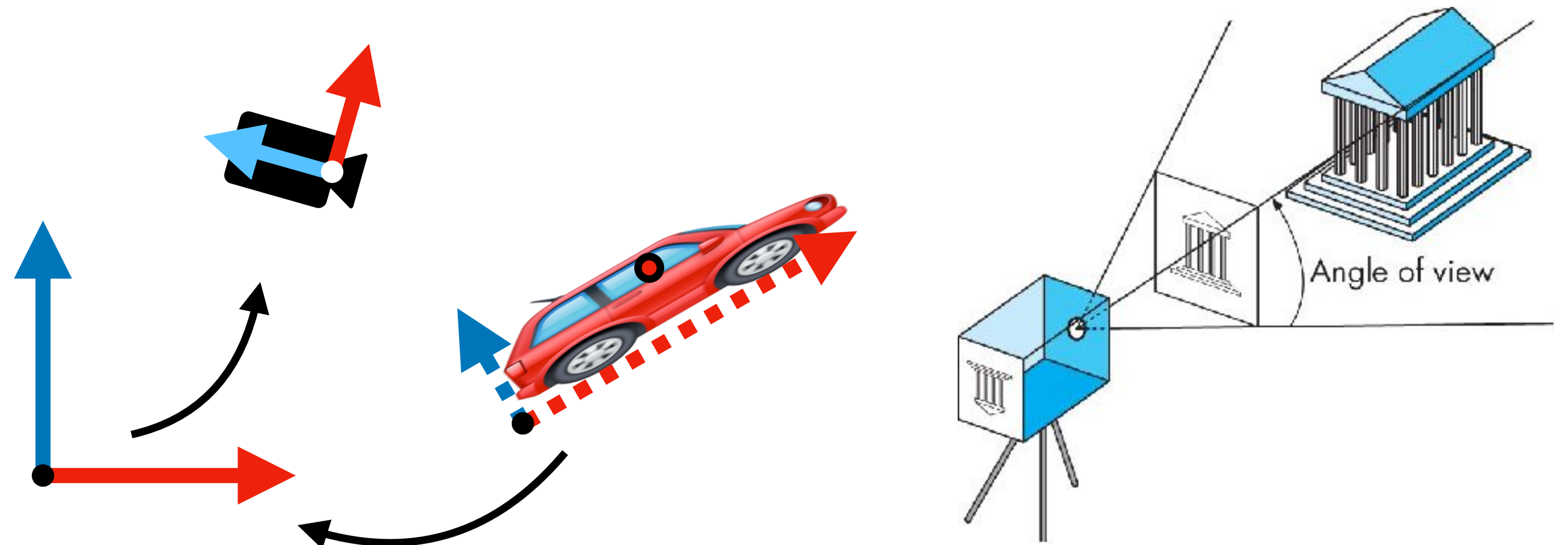
# Vertex processing

Every vertex is subject to the same operations:

- Modelling transformation: object space  $\rightarrow$  world space
- Viewing transformation: world space  $\rightarrow$  camera space
- Projection transformation: camera space  $\rightarrow$  normalized device coordinates

This stage is programmable, done by programmer-specified **vertex shader**

**Output:** transformed position in NDC (before division)

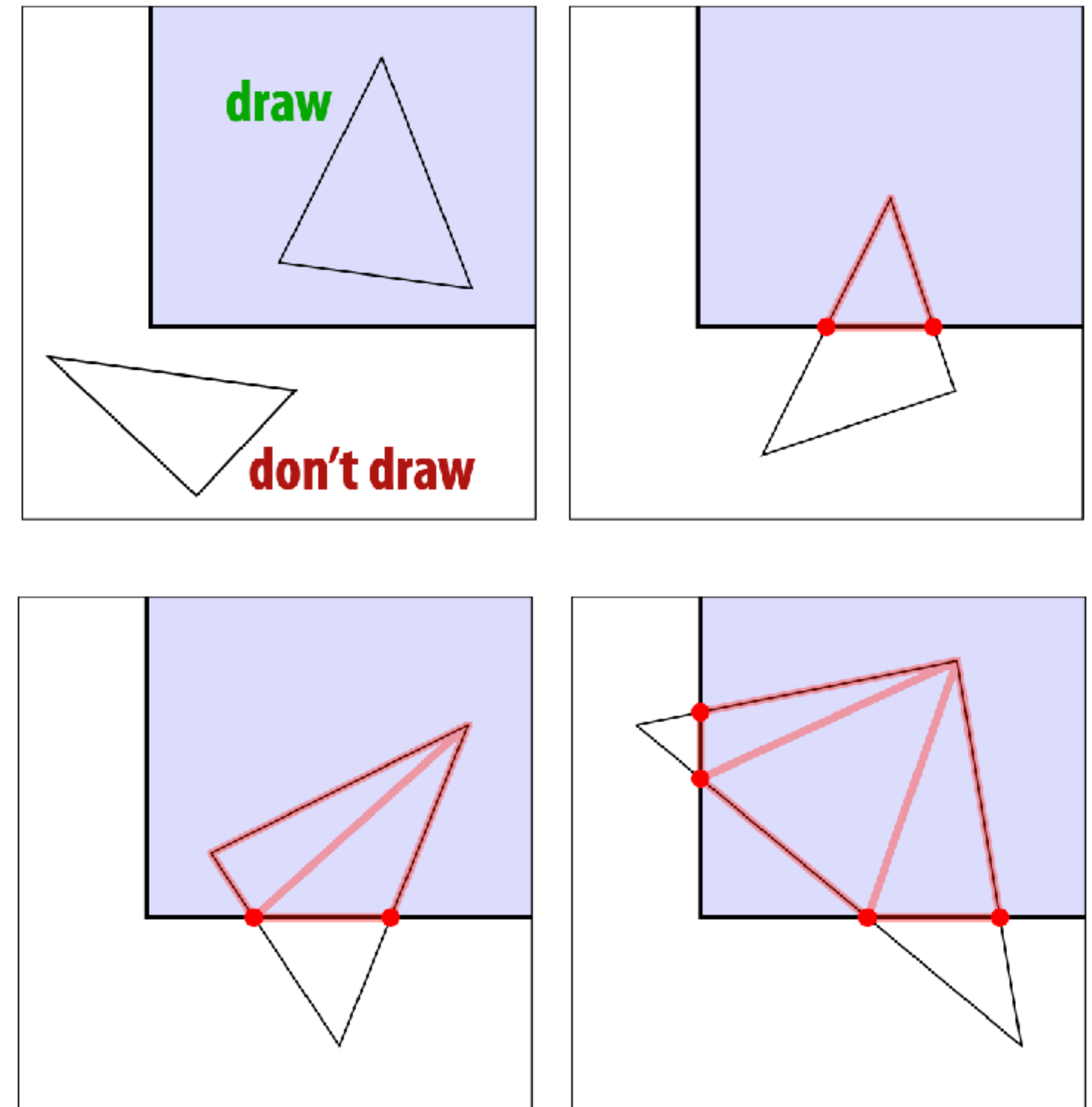


# Triangle processing

For each triangle:

- Get transformed positions of corresponding vertices
- Clip against the canonical view volume  $[-1, 1]^3$
- Divide by  $w$  and transform to pixel coordinates

**Output:** clipped triangle(s) in screen space





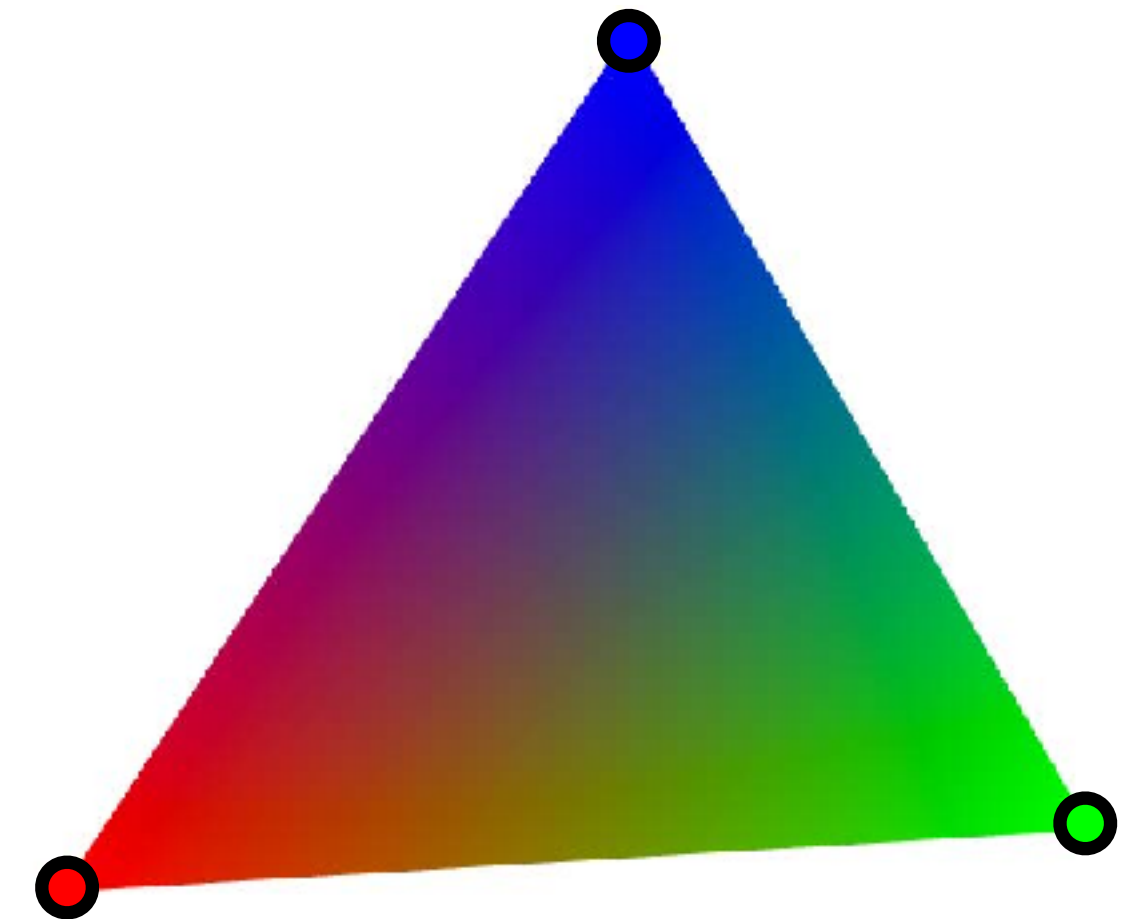
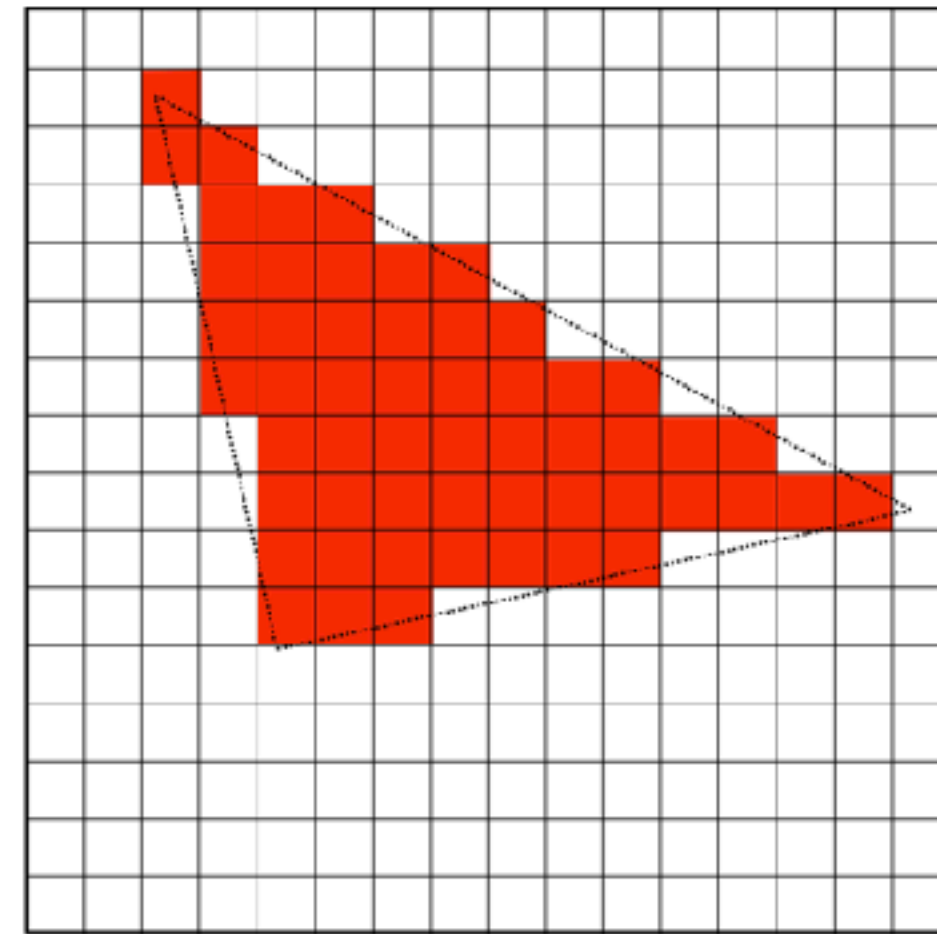
# Rasterization

For each triangle, we will produce a set of sample points that it covers.

But also: interpolate the vertex attributes (colour, texture coordinates, etc.) to each covered sample.

We will need these in the next stage!

**Output:** stream of **fragments**, i.e. sample-sized pieces of triangle with interpolated attributes



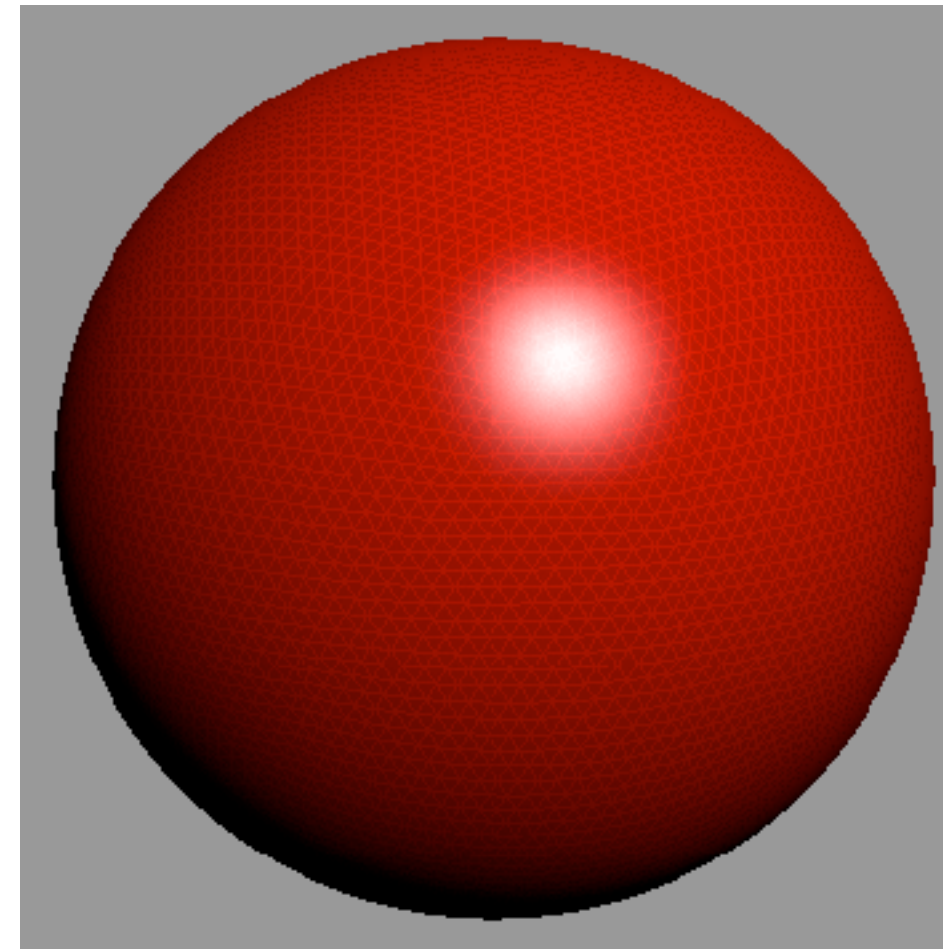
# Fragment processing

We may want to do some computation to decide the colour of a fragment, e.g.

- Texture lookup
- Lighting computation (next class)

This stage is also programmable: **fragment shader**

**Output:** fragment colour as a 4-tuple: red, green, blue, alpha (opacity)



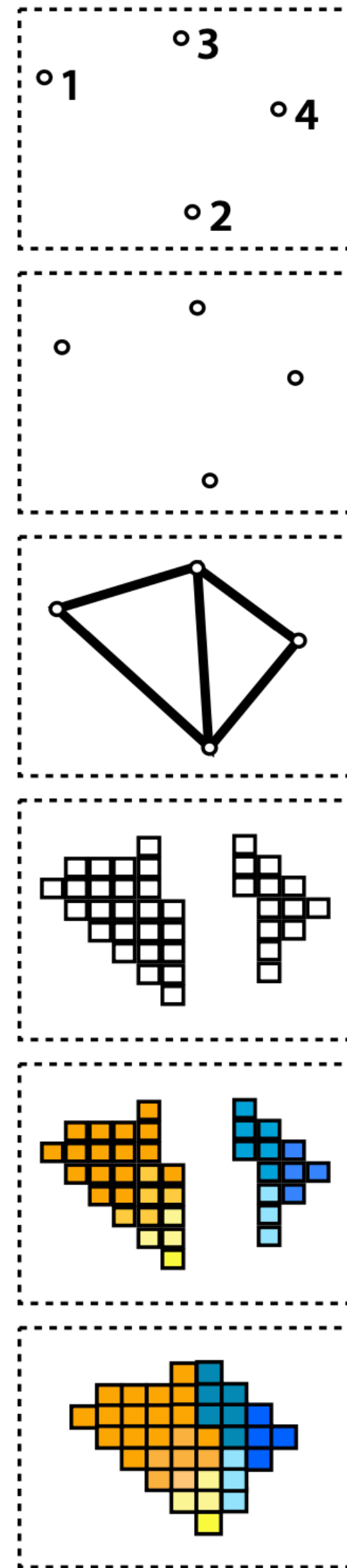
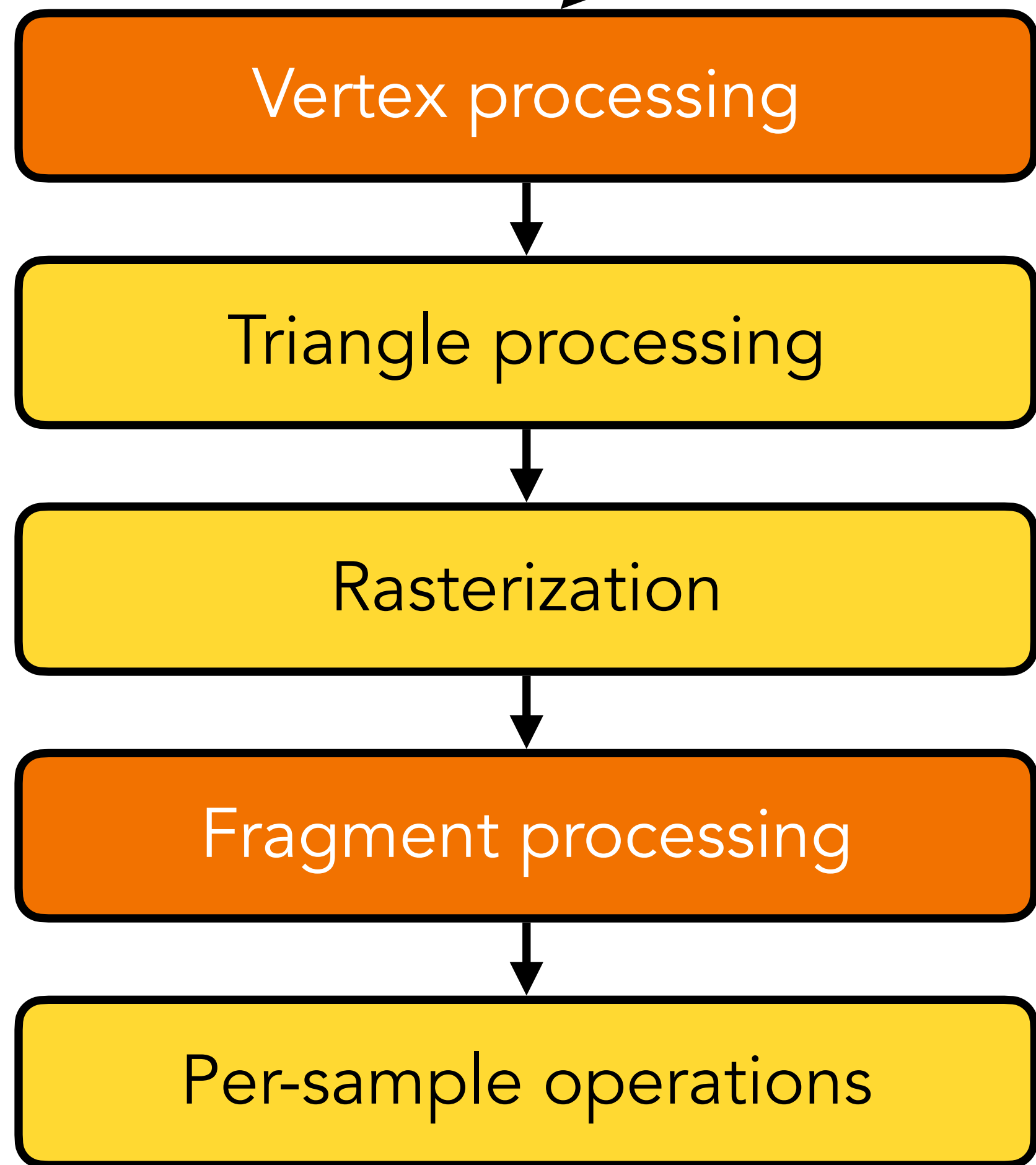


# Per-sample operations

- Test each sample's depth vs. z-buffer
- Blend with existing colour in framebuffer using alpha



Once all this is done for all objects in the scene, the framebuffer contains the final rendered image.



Input: vertices in 3D space  
(with attributes)

Vertices in NDC  
(before division)

Clipped triangles  
in screen space

Fragments  
(with interpolated attributes)

Shaded fragments  
(with RGBA colour and depth)

Output: image in framebuffer



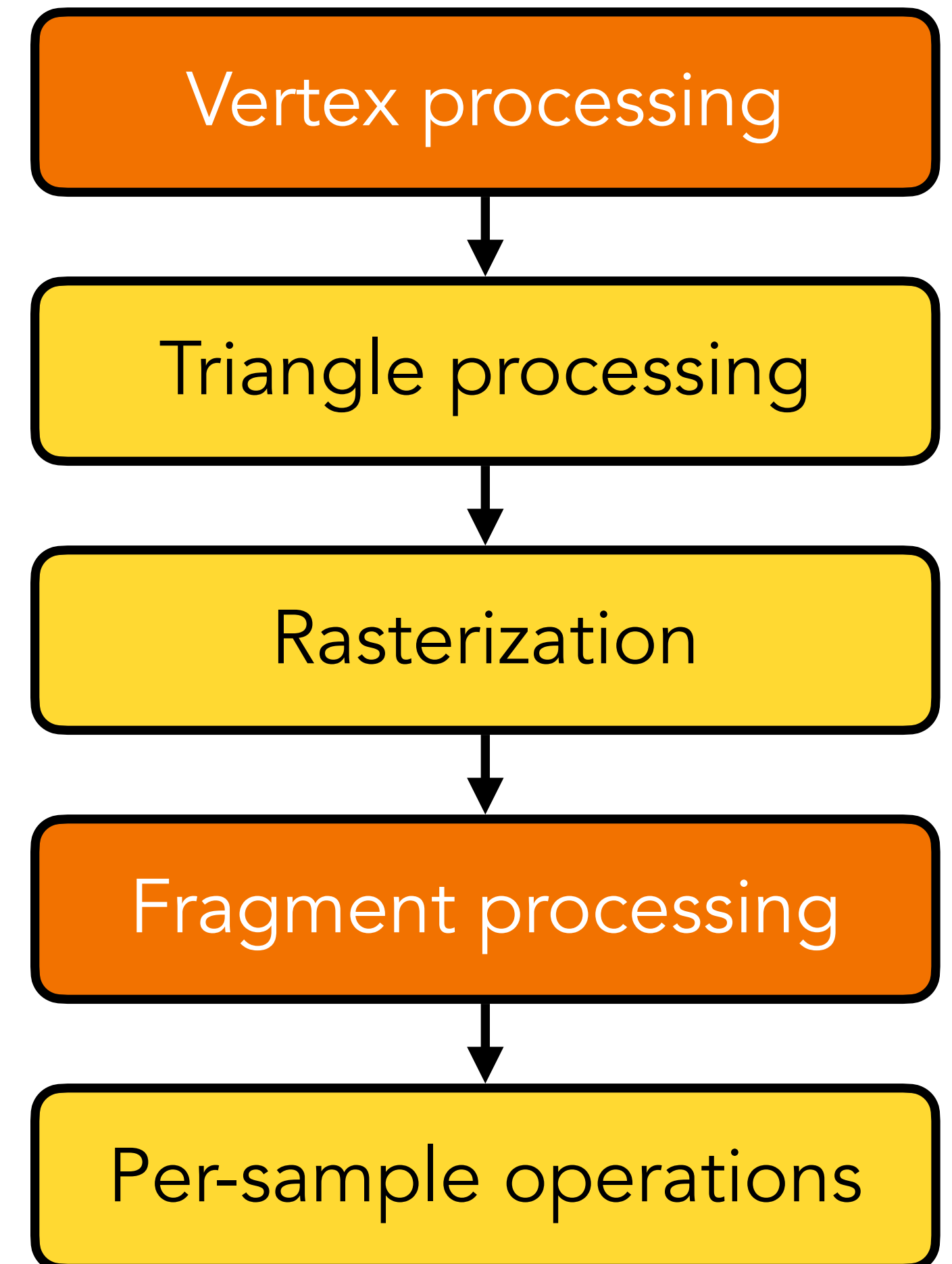
# Programmer's view

Initialization:

- Compile vertex and fragment shaders
- Send uniform variables (transformation matrices, texture images, etc.) to GPU
- For each object: send vertex attributes, triangle indices

Per frame, for each object:

- Update uniform variables
- Request draw



# Assignment 1

You will implement most of this...

Initialization:

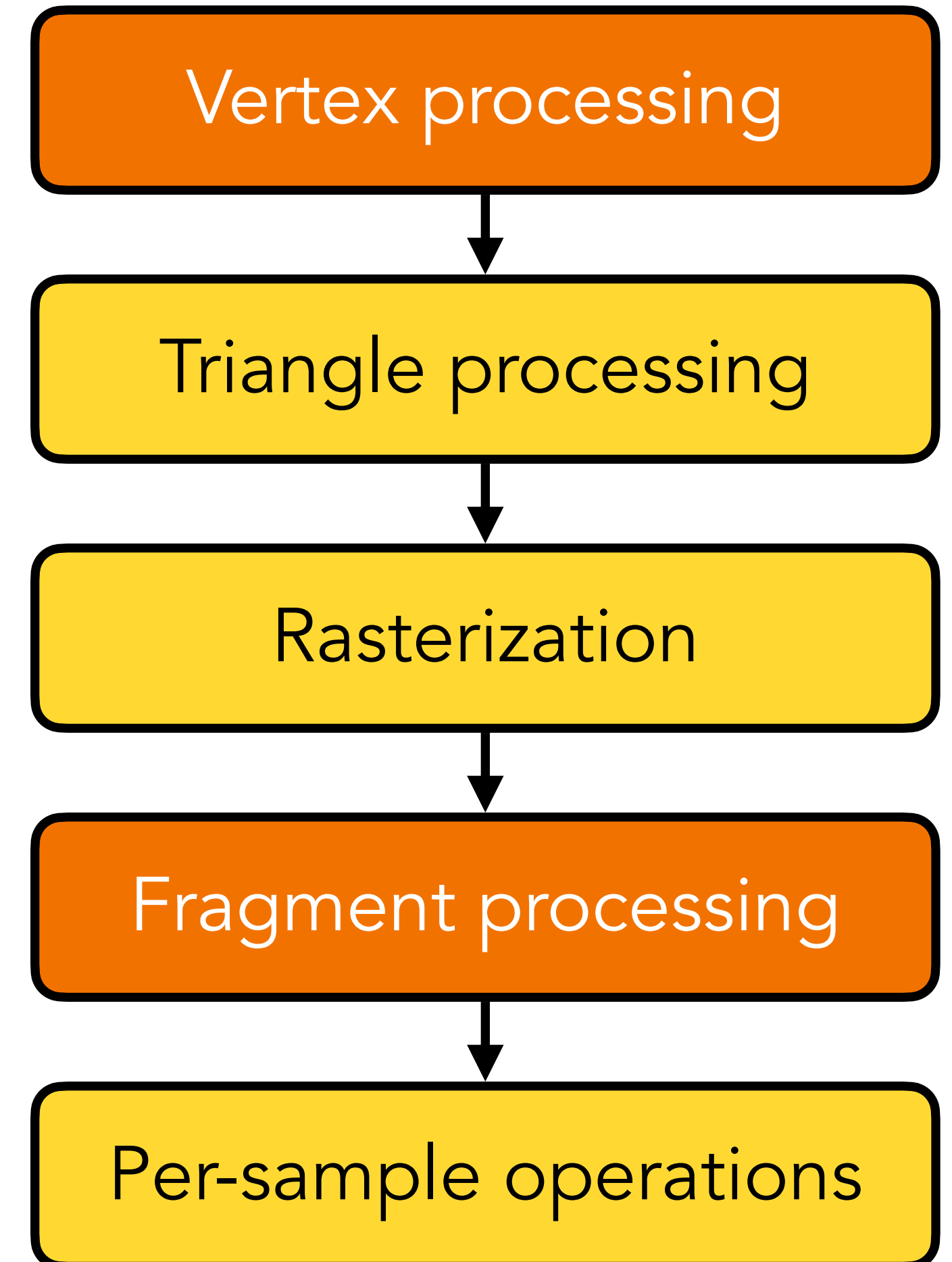
- Compile vertex and fragment shaders
- Send uniform variables (transformation matrices, texture images, etc.) to GPU
- For each object: send vertex attributes, triangle indices

Per frame, for each object:

- Update uniform variables
- Request draw

...not this!

(Well, you will do a little of this too)





# Assignment 1

Implement a software rasterization library that plays the role of the GPU, so that the example programs we provide can run

- Call programmer-defined vertex and fragment shaders
- Implement screen-space transformation, rasterization, barycentric interpolation, bilinear texture filtering
- Add support for supersampling, z-buffering
- **Optional:** clipping, mipmapping

# Shaders

~~The vertex shader applies modelling, viewing, projection transformations to compute the NDC position~~

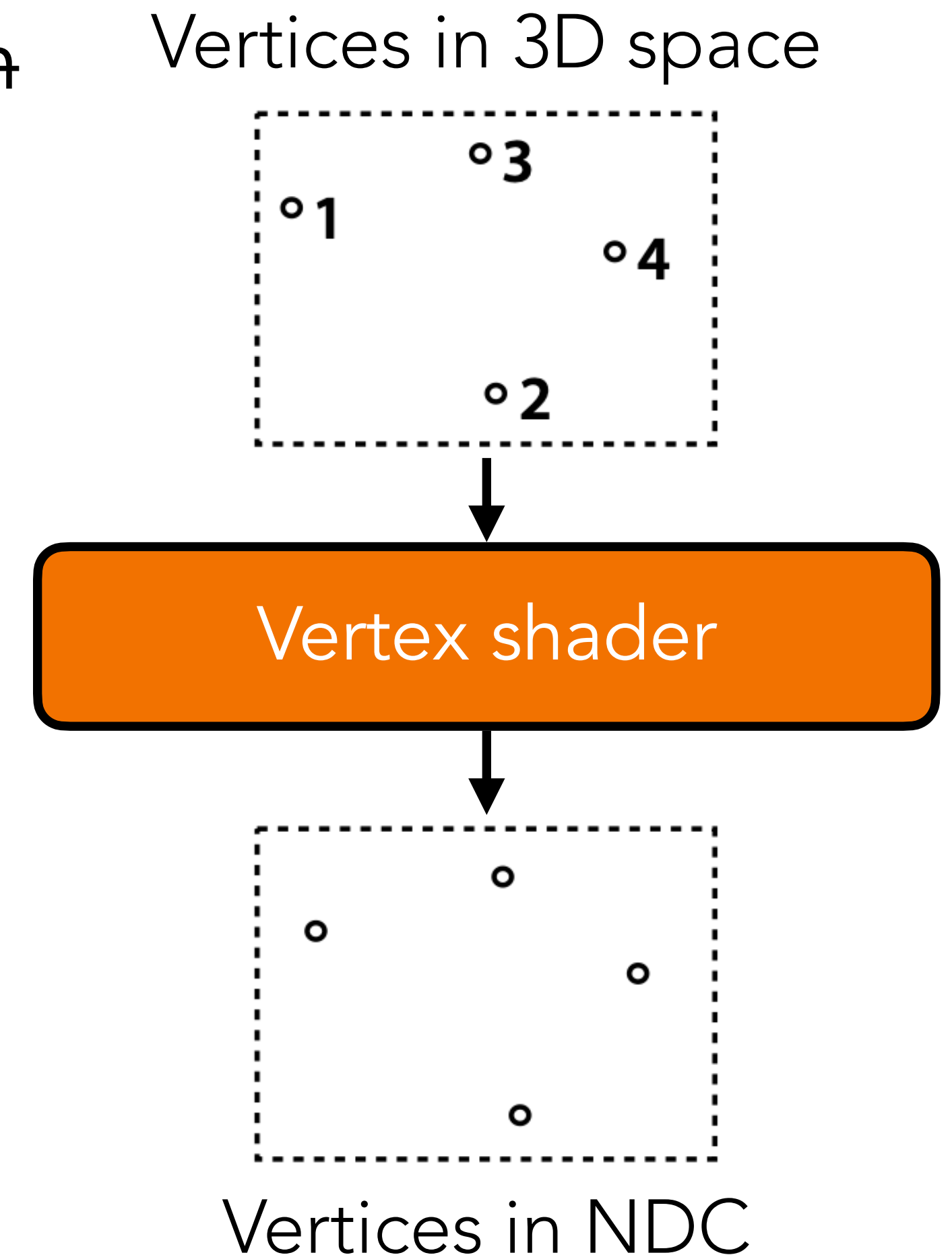
The vertex shader is an arbitrary function that can do whatever you want to compute the NDC position!

Runs on each vertex **independently**

- Can't pass information to other vertices
- Can't have side-effects (e.g. no writing to global memory, no print statements)

**Inputs:** attributes of current vertex, uniform variables

**Outputs:** vertex position in NDC, other attributes to interpolate to fragments





The fragment shader is another arbitrary function.

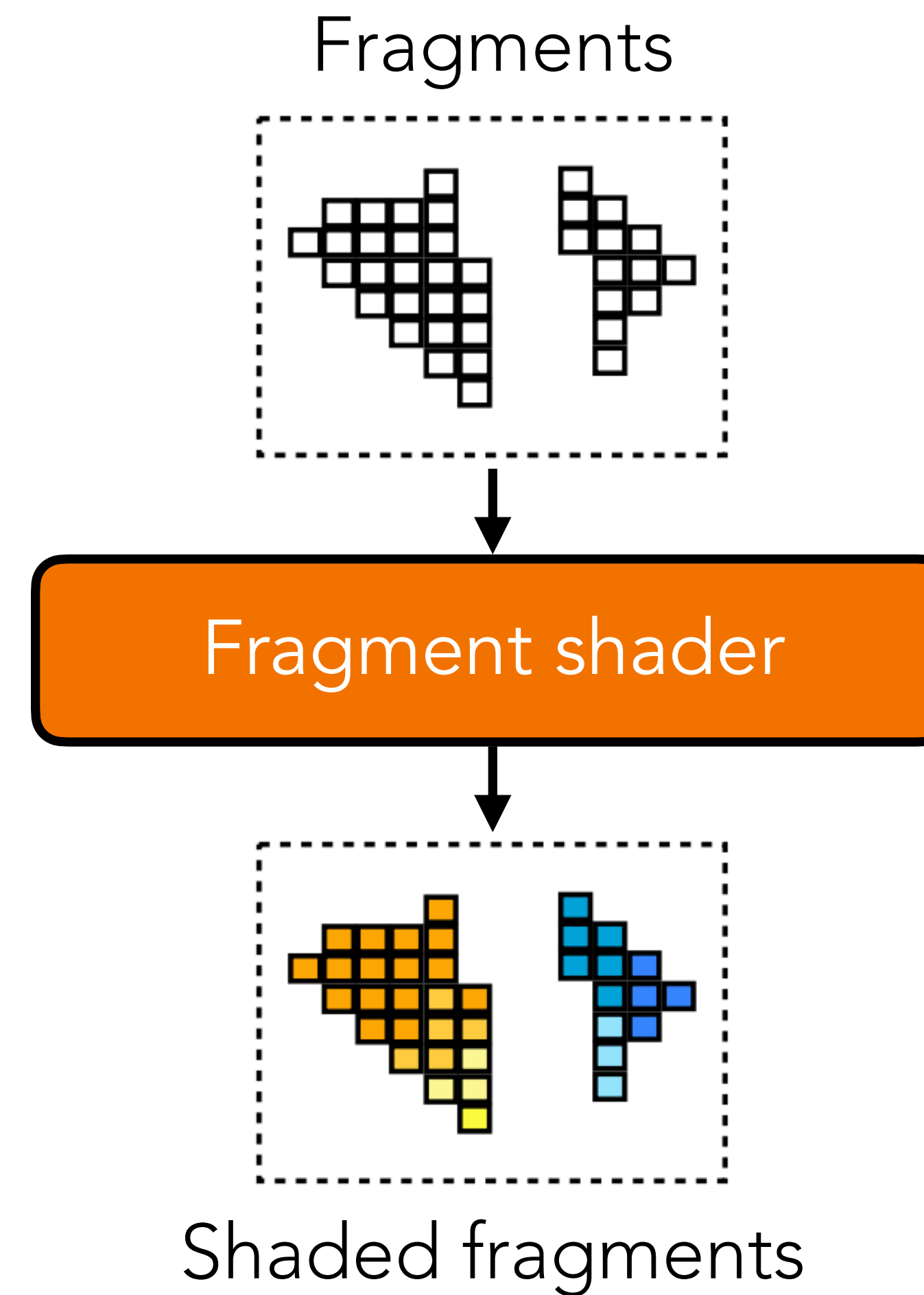
It can do anything (e.g. texture lookup, lighting computation, etc.) to compute the fragment colour.

Again, runs on each fragment independently

**Inputs:** attributes interpolated from vertex shader output, uniform variables

**Outputs:** fragment colour (RGBA),  
optional: modified fragment depth

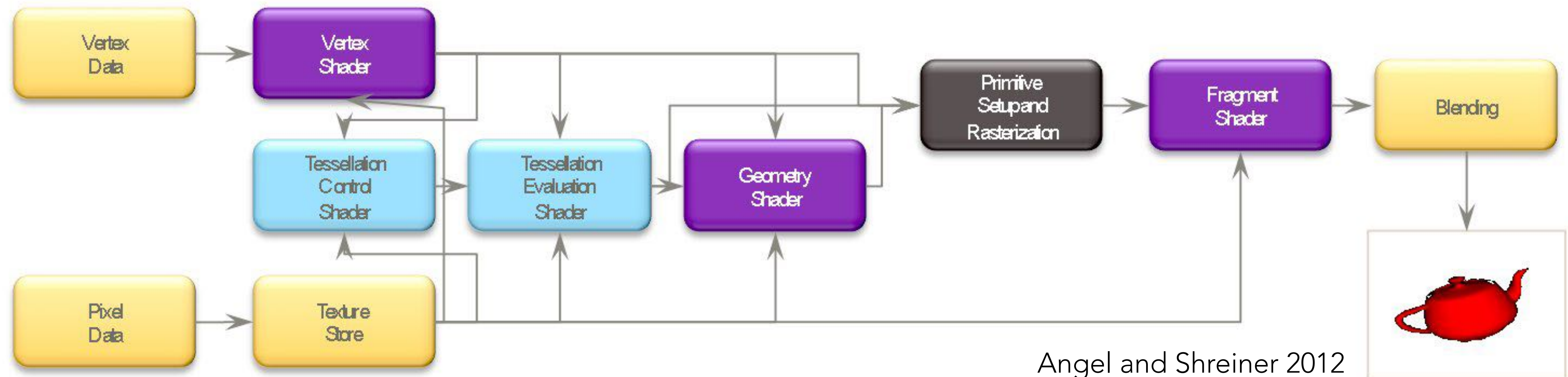
Fragment shader can change fragment depth but not fragment position! (Why?)



# Other programmable stages

Modern GPUs have a few more stages we won't cover:

- Tessellation shaders: subdivide primitives into smaller pieces
- Geometry shader: create new geometry from given primitives





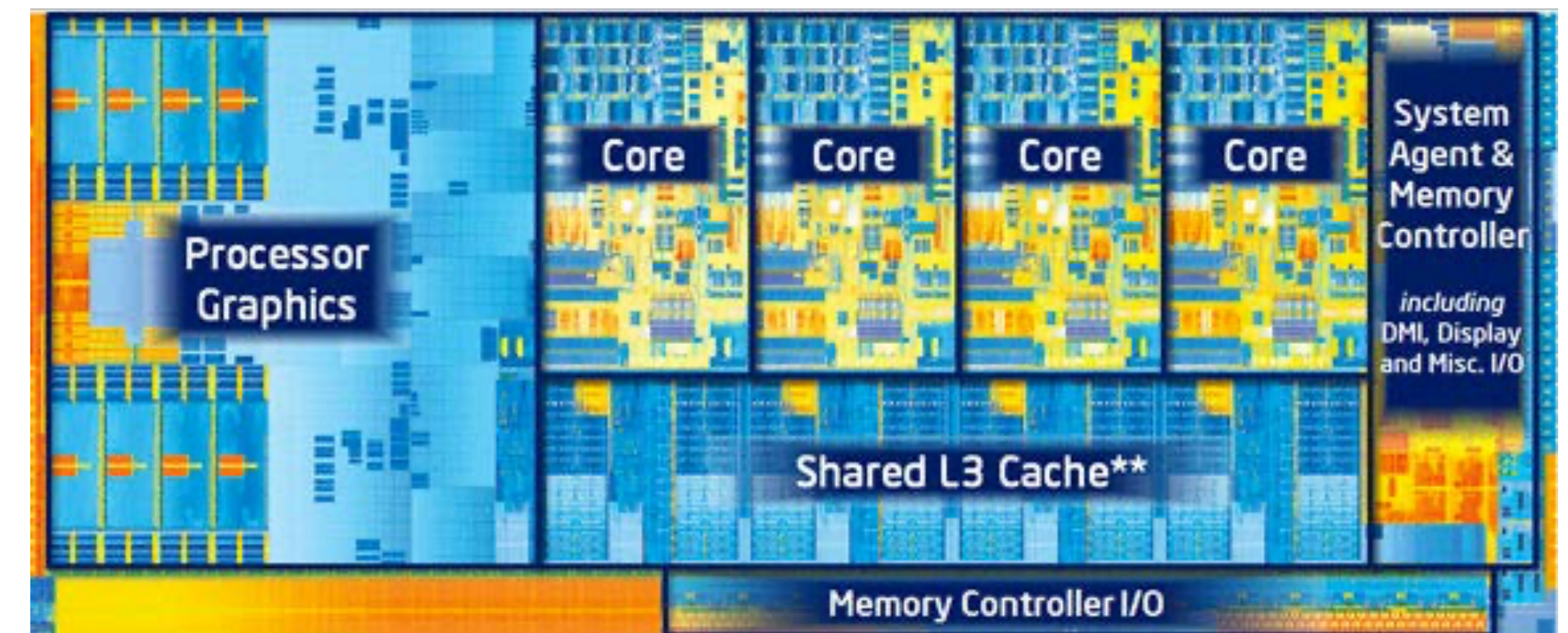
# GPUs

Modern graphics processing units (GPUs) provide a highly parallelized implementation of the rasterization pipeline

- Many SIMD cores for running vertex and fragment shaders in parallel
- Lots of fixed-function hardware for non-programmable stages (clipping, rasterization, texture sampling, z-buffering, etc.)

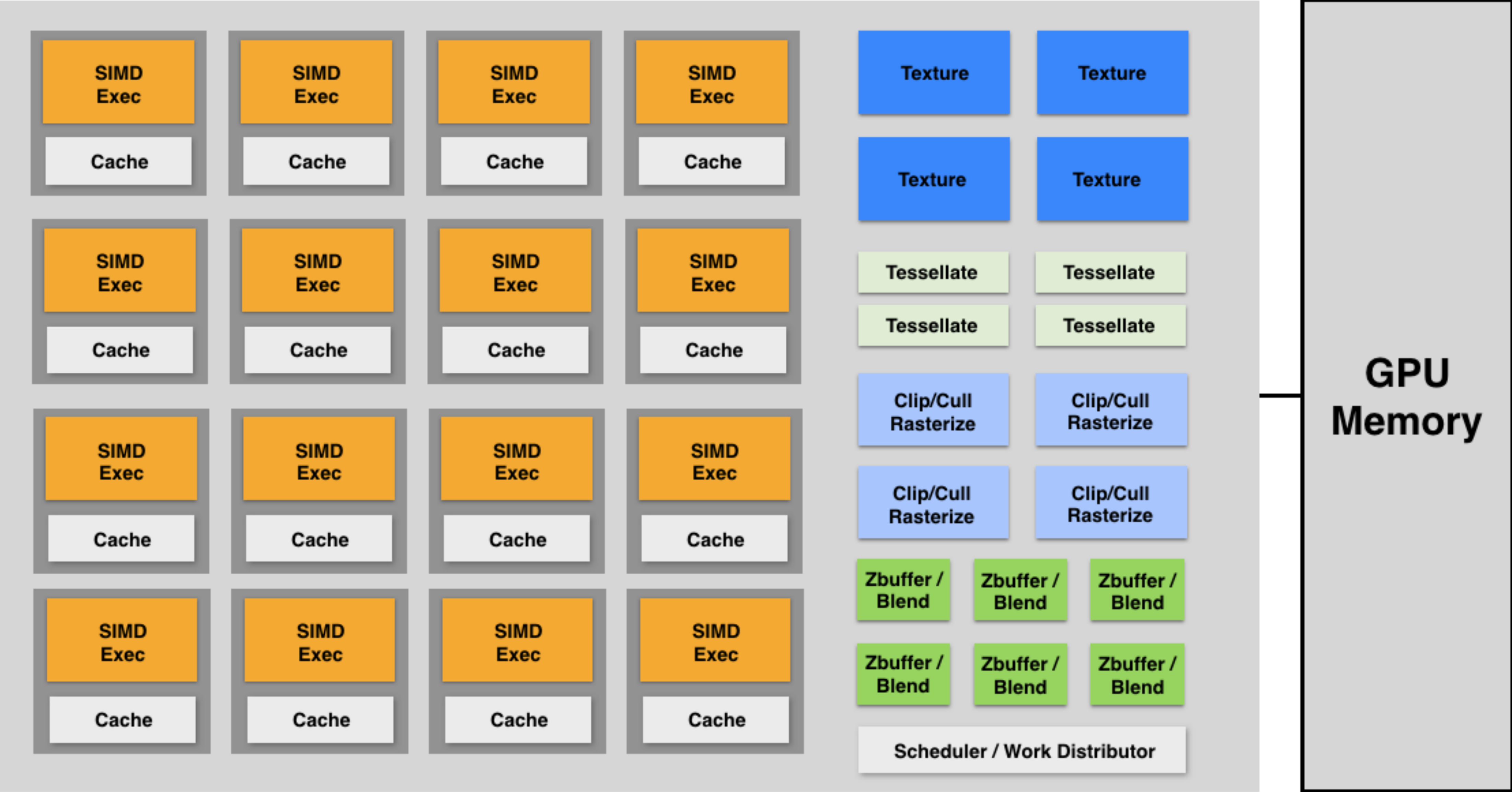


Discrete GPU card



Integrated GPU (part of CPU die)





# Homework problems

1. Figure out a way to draw a **pixel-perfect** disk with radius  $r$  centered at a point  $(x,y)$  in 2D.

**Hint:** Send a single quad (4 vertices and 2 triangles), and do the work in the fragment shader.

2. Figure out a way to draw a pixel-perfect disk with radius  $r$  in **pixels** centered at the **projected location** of a 3D point  $(x,y,z)$ .

**Hint:** Set all 4 vertices' position to  $(x,y,z)$ , but use an extra attribute to move them to the right corners in the vertex shader.