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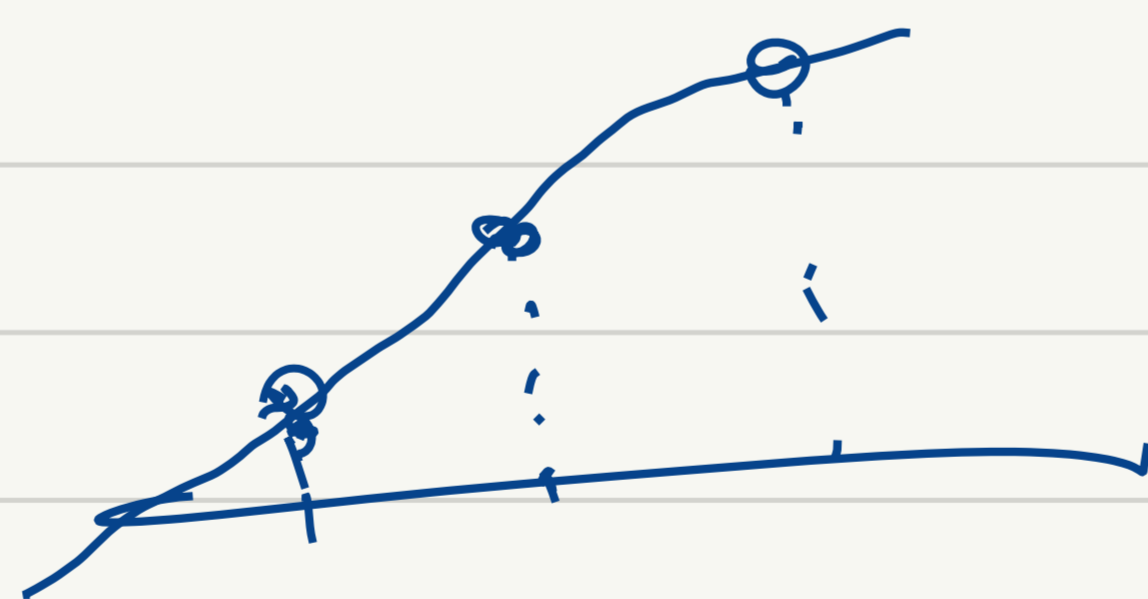
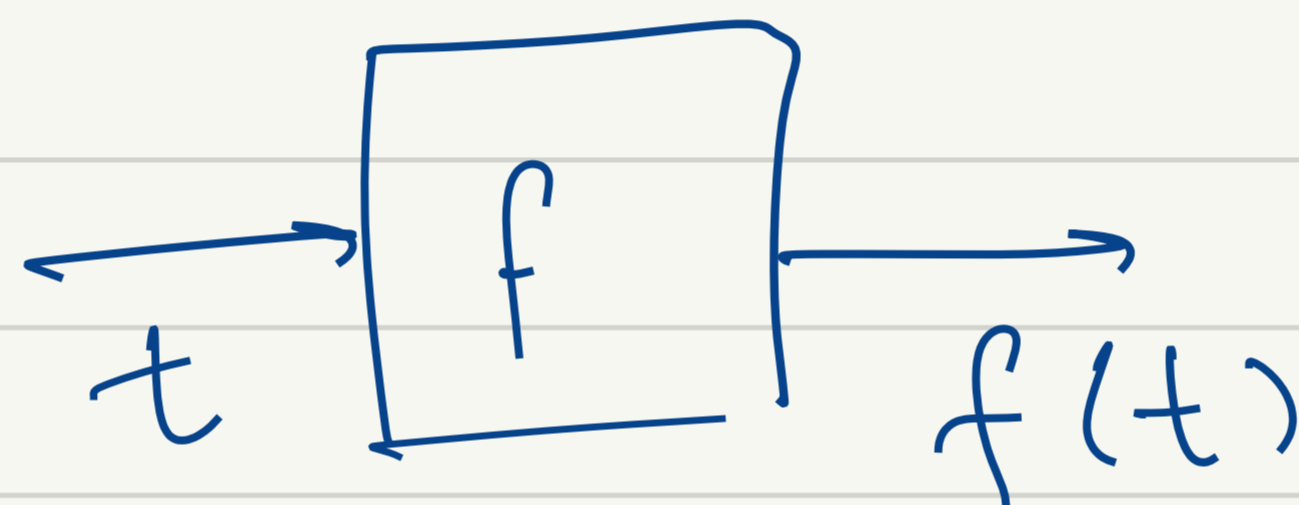
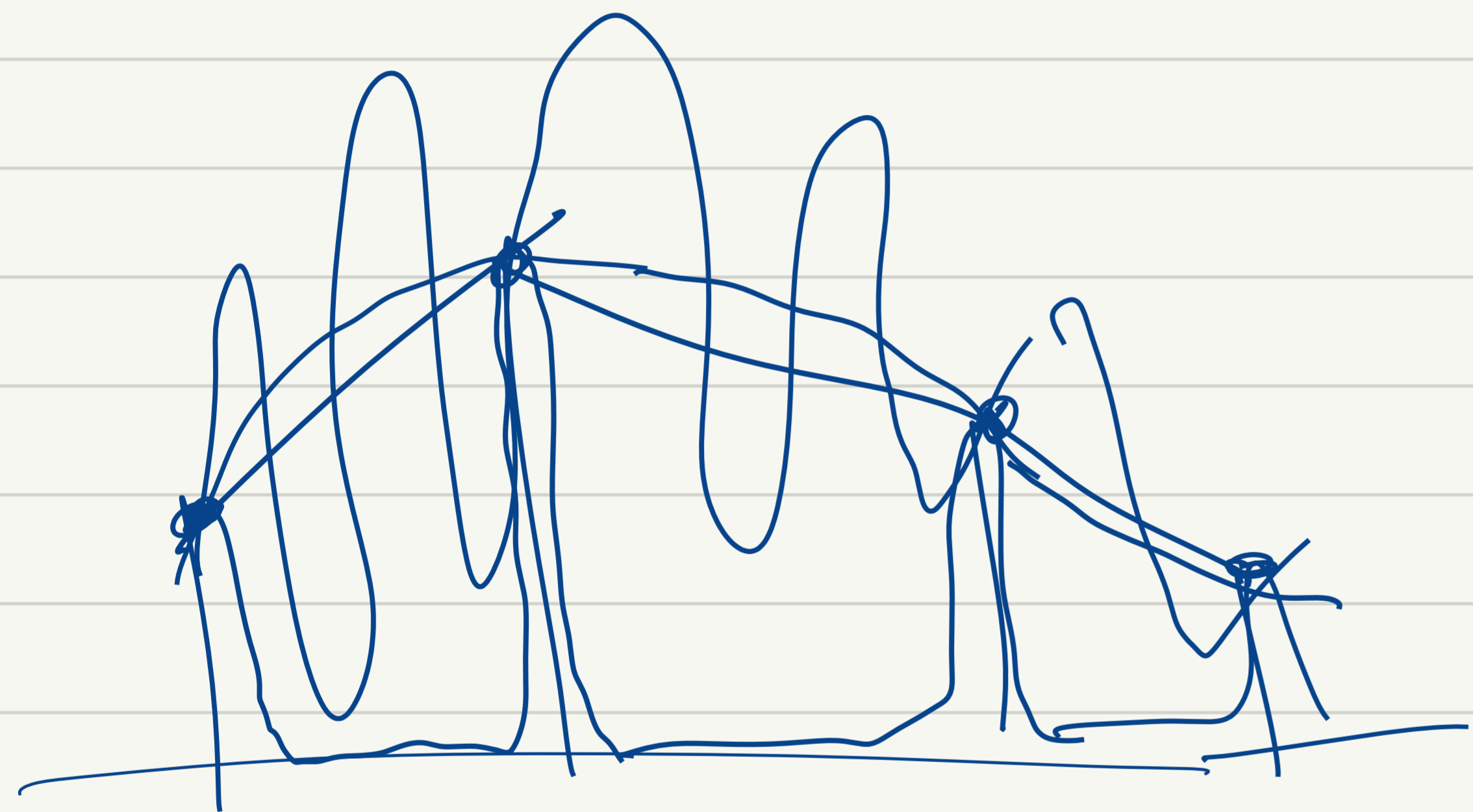
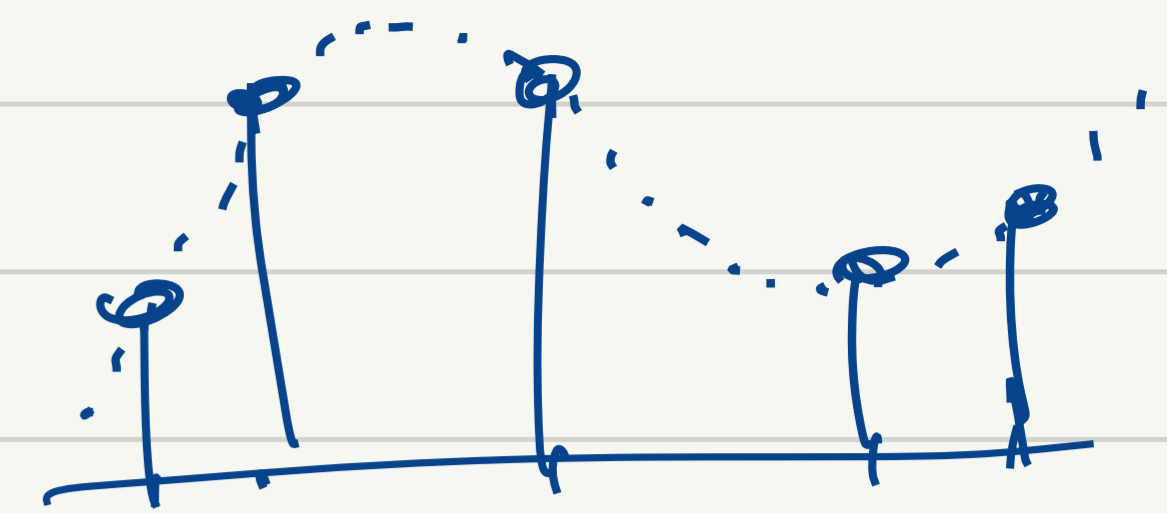
- A4 updated

- Deadline: Mon, 21 March

## Interpolation

$(t_1, y_1), (t_2, y_2), \dots$

find  $\tilde{f}$  s.t.  $\tilde{f}(t_i) = y_i$  for all  $i$



$$\tilde{f} \approx f$$

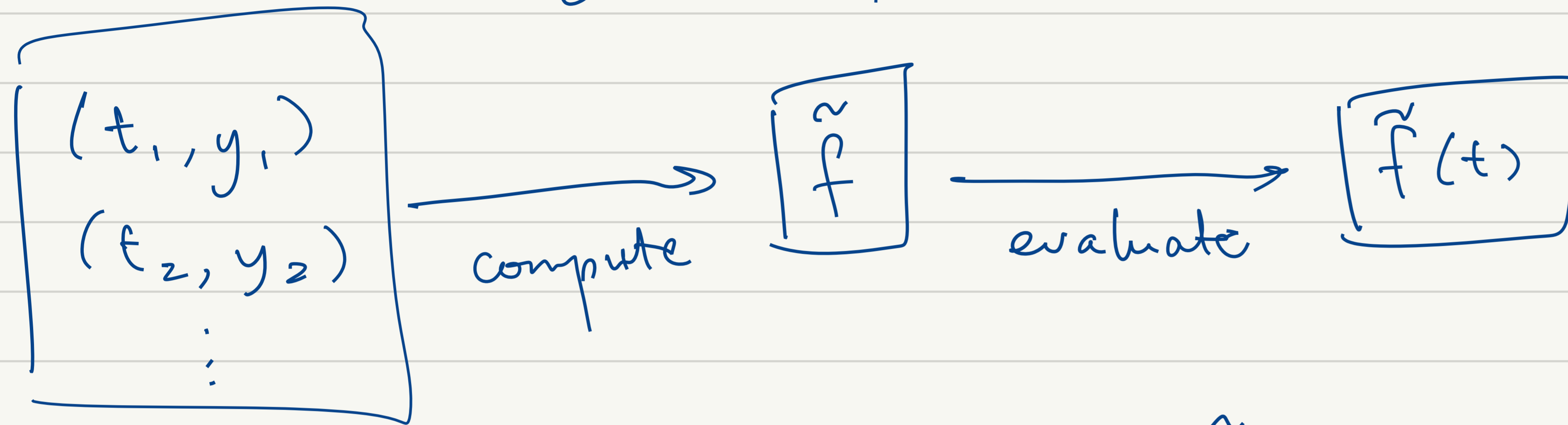
interpolating  
function

or interpolant

① what is a good choice of  $t_i$ ?

② what is a good choice of function?

$\tilde{f}$  should be easy to compute and easy to evaluate

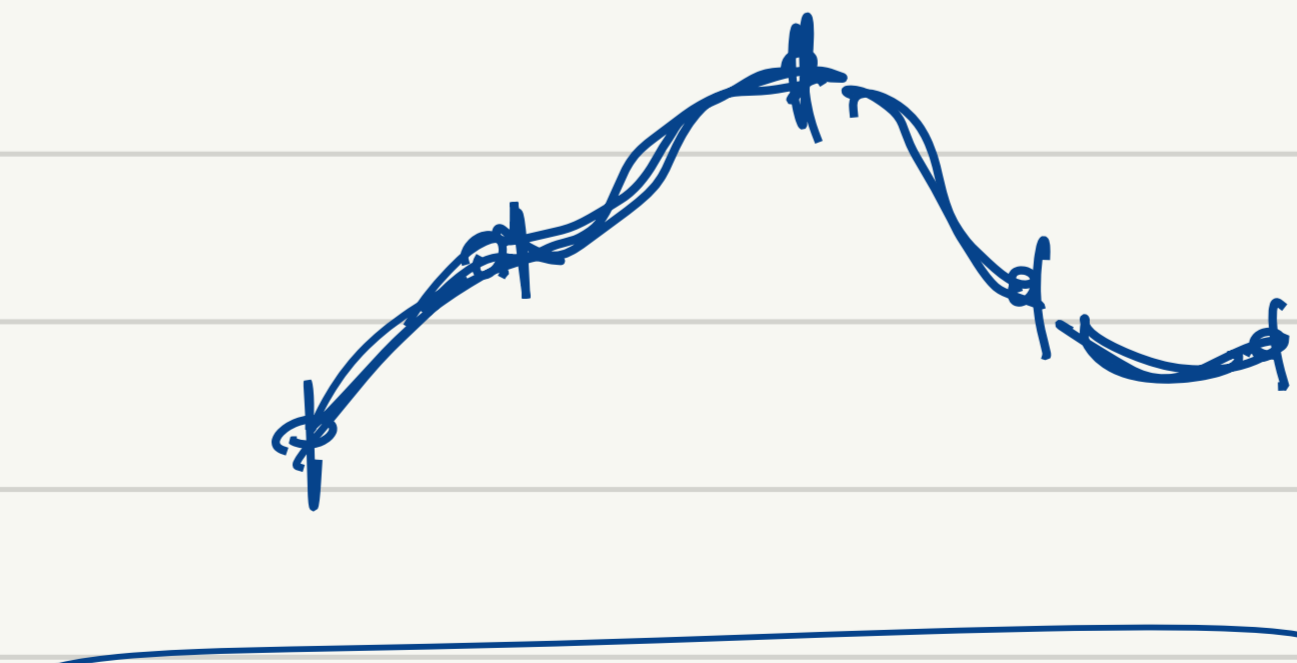


$\in \mathbb{R} \times \mathbb{R}$

Many choices of  $\tilde{f}$

- ① polynomial
- ② piecewise polynomial
- ③ trigonometric
- ④ rational fns

$$\frac{p(x)}{q(x)}$$



$$\left[ \begin{array}{l} f: \mathbb{R} \rightarrow \mathbb{R} \\ \text{(1D interp.)} \end{array} \right.$$

$$f: \mathbb{R} \rightarrow \mathbb{R}^n$$

$\equiv n \times 1D \text{ interp}$

$$\left[ \begin{array}{l} f: \mathbb{R}^n \rightarrow \mathbb{R} \\ \text{multivariate} \\ \text{interp.} \end{array} \right.$$

out of scope

## Basis function interpolation

choose a set of basis functions  $\phi_1, \phi_2, \dots, \phi_n : \mathbb{R} \rightarrow \mathbb{R}$

Choose  $\hat{f}$  as linear combination

$$\hat{f} = \alpha_1 \phi_1 + \alpha_2 \phi_2 + \dots + \alpha_n \phi_n \quad \Leftrightarrow \quad \hat{f}(t) = \alpha_1 \phi_1(t) + \dots$$

$m$  data points  $(t_1, y_1), \dots, (t_m, y_m)$

$$y_i = \hat{f}(t_i) = \sum_{j=1}^n \alpha_j \phi_j(t_i) : \quad m \text{ linear eqs. in } n \text{ unknowns}$$

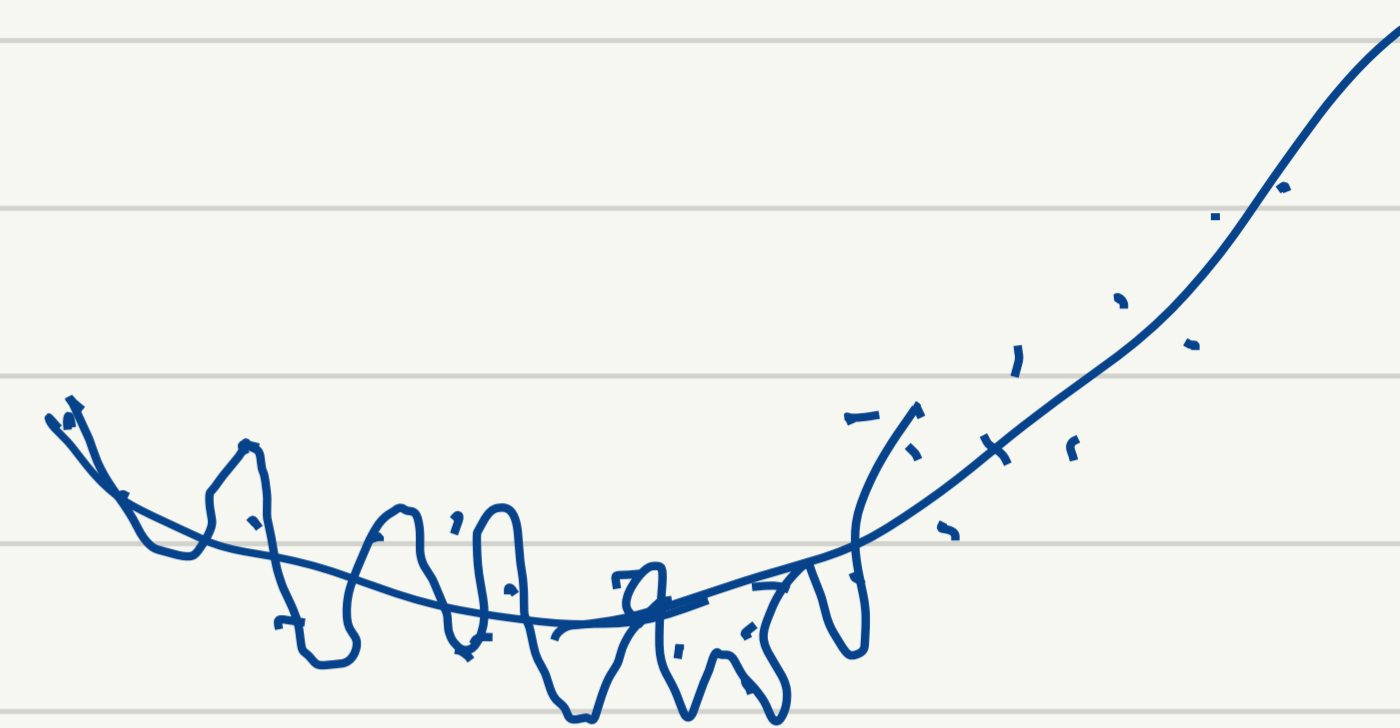
$$y = Ax \quad \text{where} \quad a_{ij} = \phi_j(t_i)$$

If  $n = m$  and  $A$  is full rank  
 $\Rightarrow$  sol. exists & is unique

usually true for most basis fns

If  $n < m$ : least-squares

If  $n > m$ : under-determined



Conditioning depend on  $\kappa(A)$  which depends on  $\phi_j(t_i)$

depends on both  $\phi_j$  and  $t_i$

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Polynomial interpolation:  $n$  data points,  $f$  is polynomial of degree  $n-1$

Monomial basis:  $\phi_1(t) = 1$ ,  $\phi_2(t) = t$ ,  $\phi_3(t) = t^2$ , ...,  $\phi_j(t) = t^{j-1}$

$$p(t) = x_1 + x_2 t + x_3 t^2 + \dots + x_n t^{n-1}$$

$$= x_1 + t(x_2 + t(x_3 + \dots (t \cdot x_n) \dots))$$

Horner's rule

$\Rightarrow$  evaluate in  $O(n)$  time

$$a_{ij} = t_i^{j-1}$$

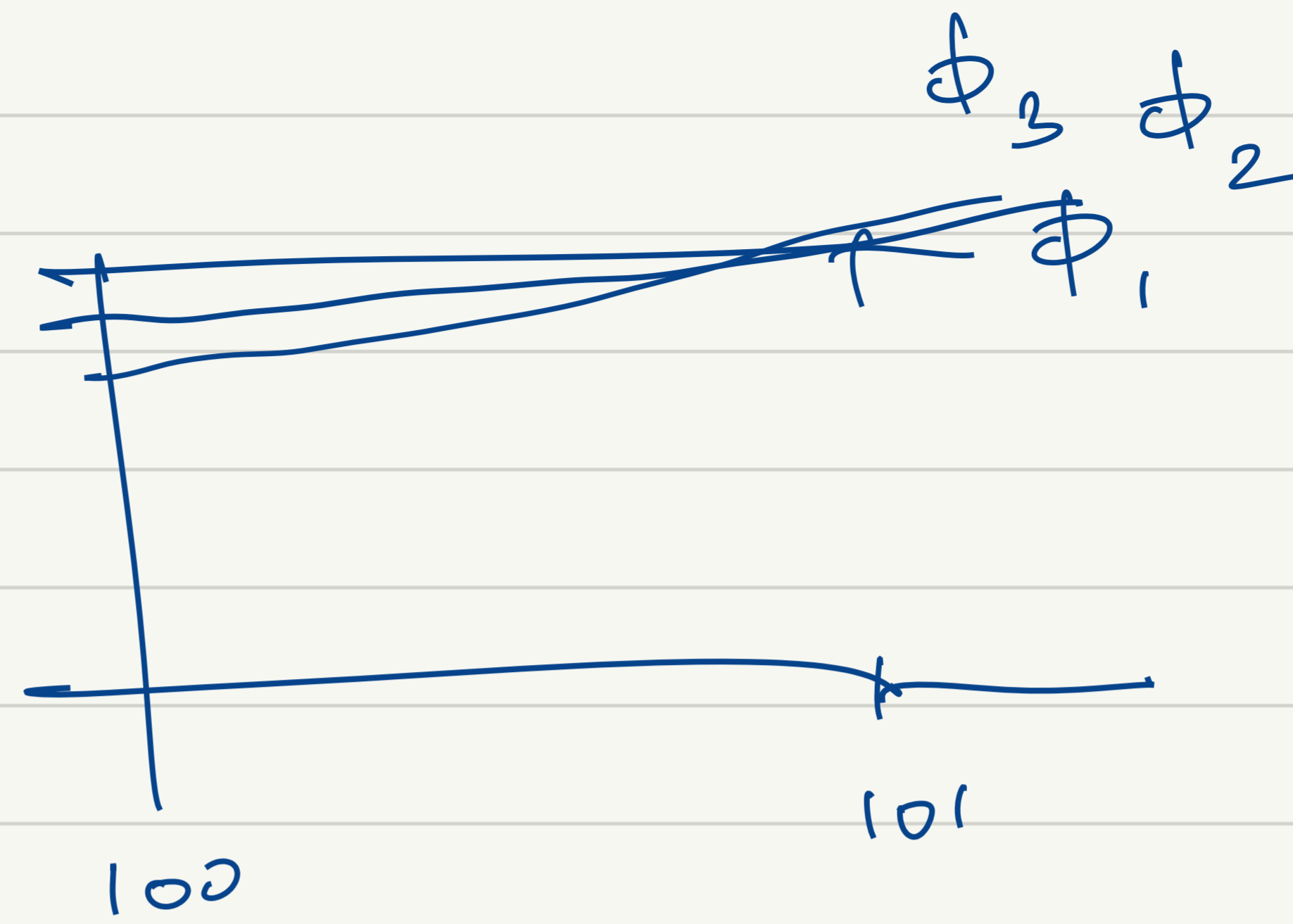
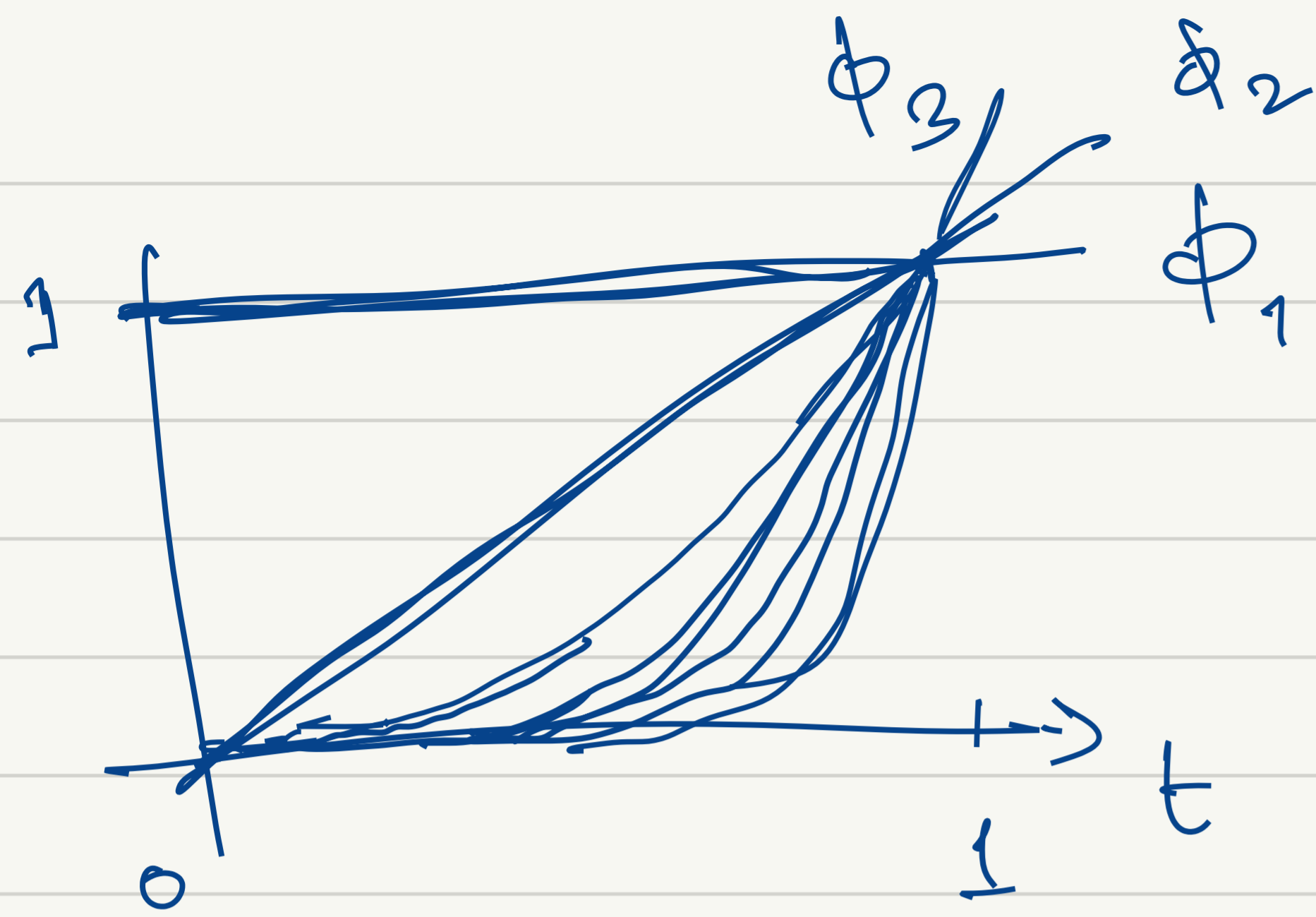
$$A = \begin{bmatrix} 1 & t_1 & t_1^2 & \dots & t_1^{n-1} \\ 1 & t_2 & t_2^2 & \dots & t_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & t_n & t_n^2 & \dots & t_n^{n-1} \end{bmatrix}$$

Vandermonde matrix

nonsingular as long as  $t_i \neq t_j$   
for  $i \neq j$

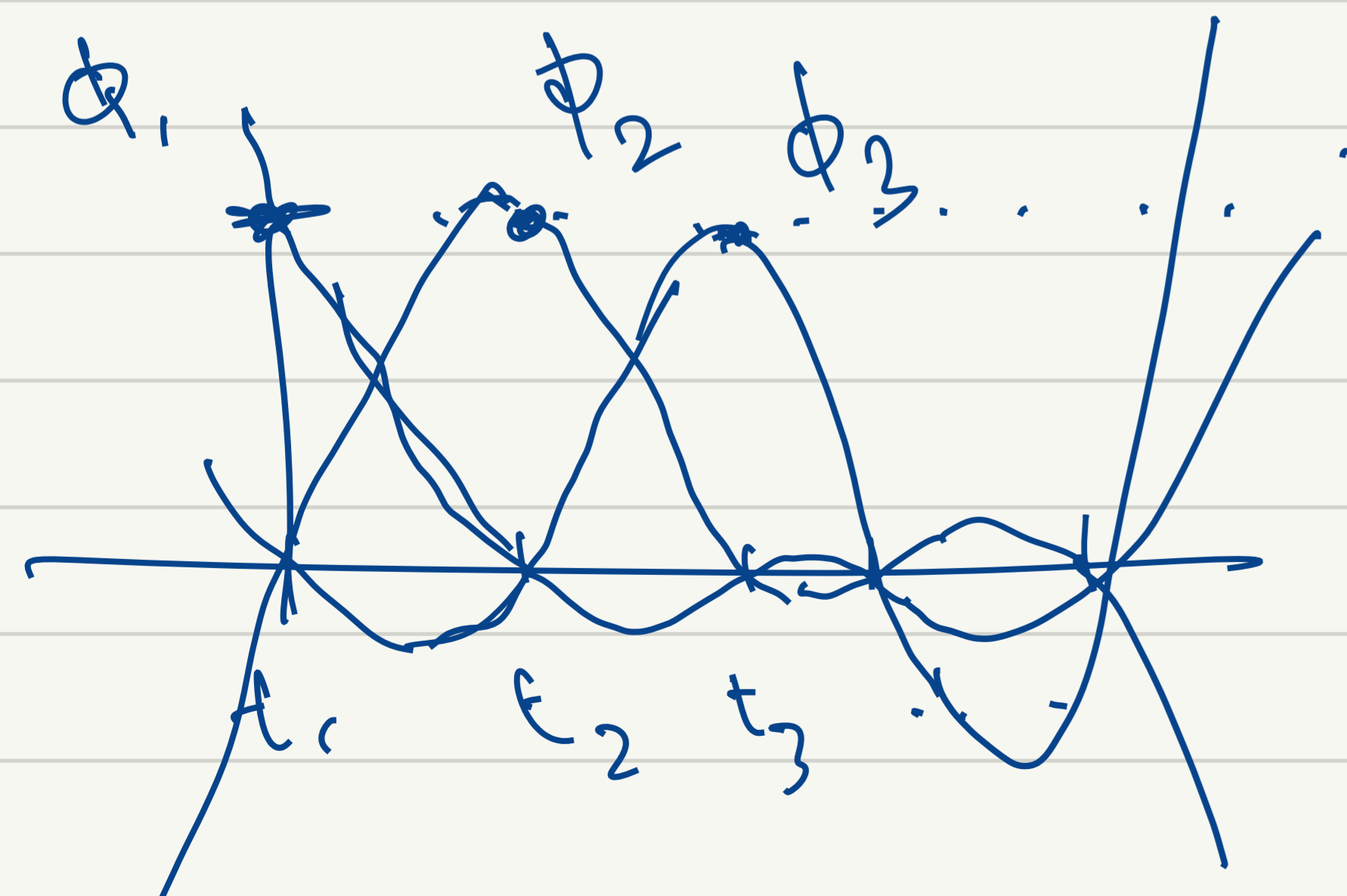
To compute  $p$ , solve  $Ax = y$  :  $O(n^3)$  time

$A$  is very badly conditioned for large  $n$ !



$\kappa(A)$  is at least exponential in  $n$

Lagrange basis



$$\phi_i(t_j) = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

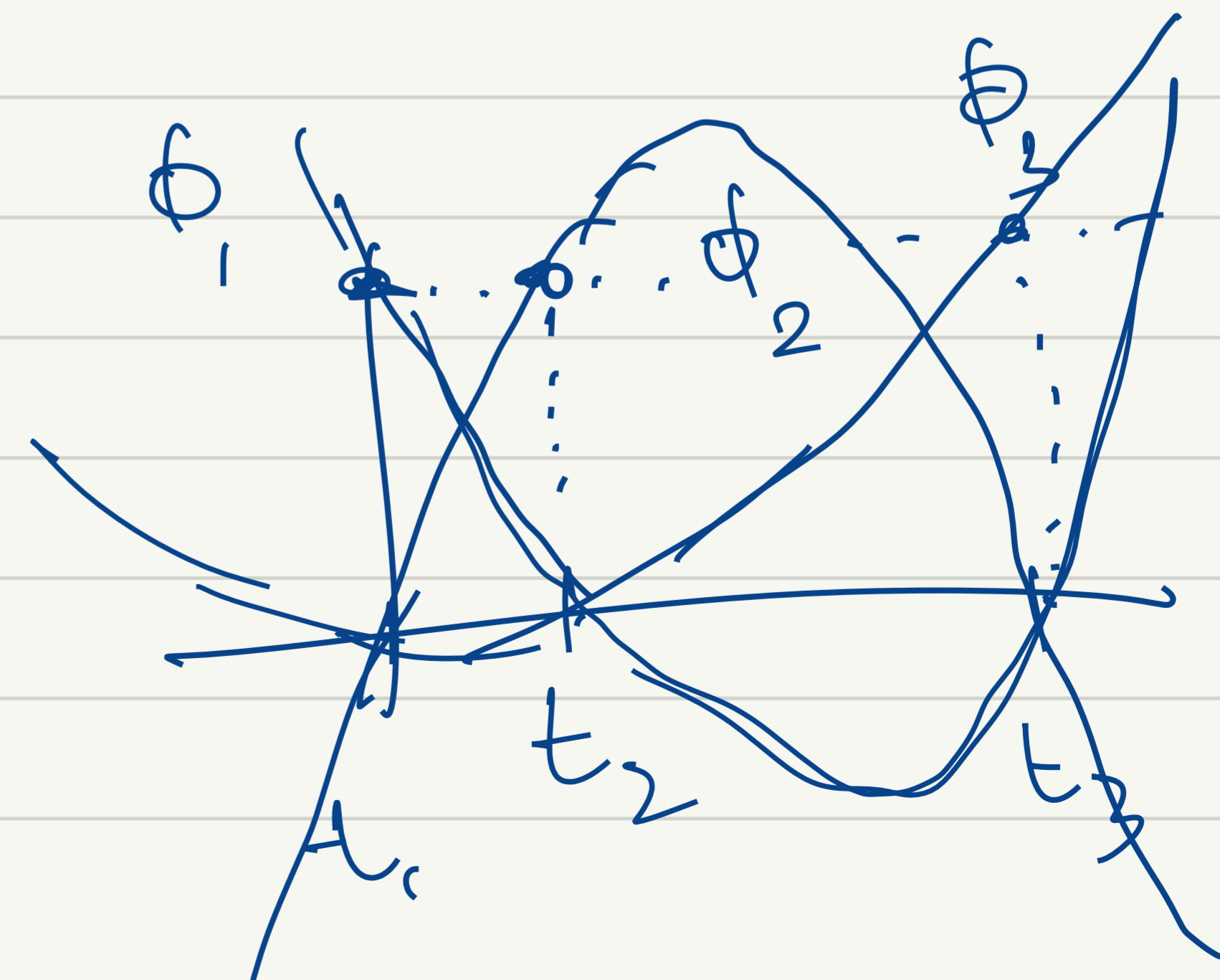
$$a_{ij} = \phi_i(t_j) \Rightarrow A = I$$

$$p(t) = \sum y_i \phi_i(t)$$

$$\phi_j(t_i) = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

$$\phi_j(t) = \frac{\prod_{i \neq j} (t - t_i)}{\prod_{i \neq j} (t_j - t_i)} \Rightarrow \text{Lagrange basis}$$

$$p(t) = y_1 \phi_1(t) + \dots + y_n \phi_n(t) \quad : \quad O(n^2) \text{ time to evaluate}$$



# Newton basis

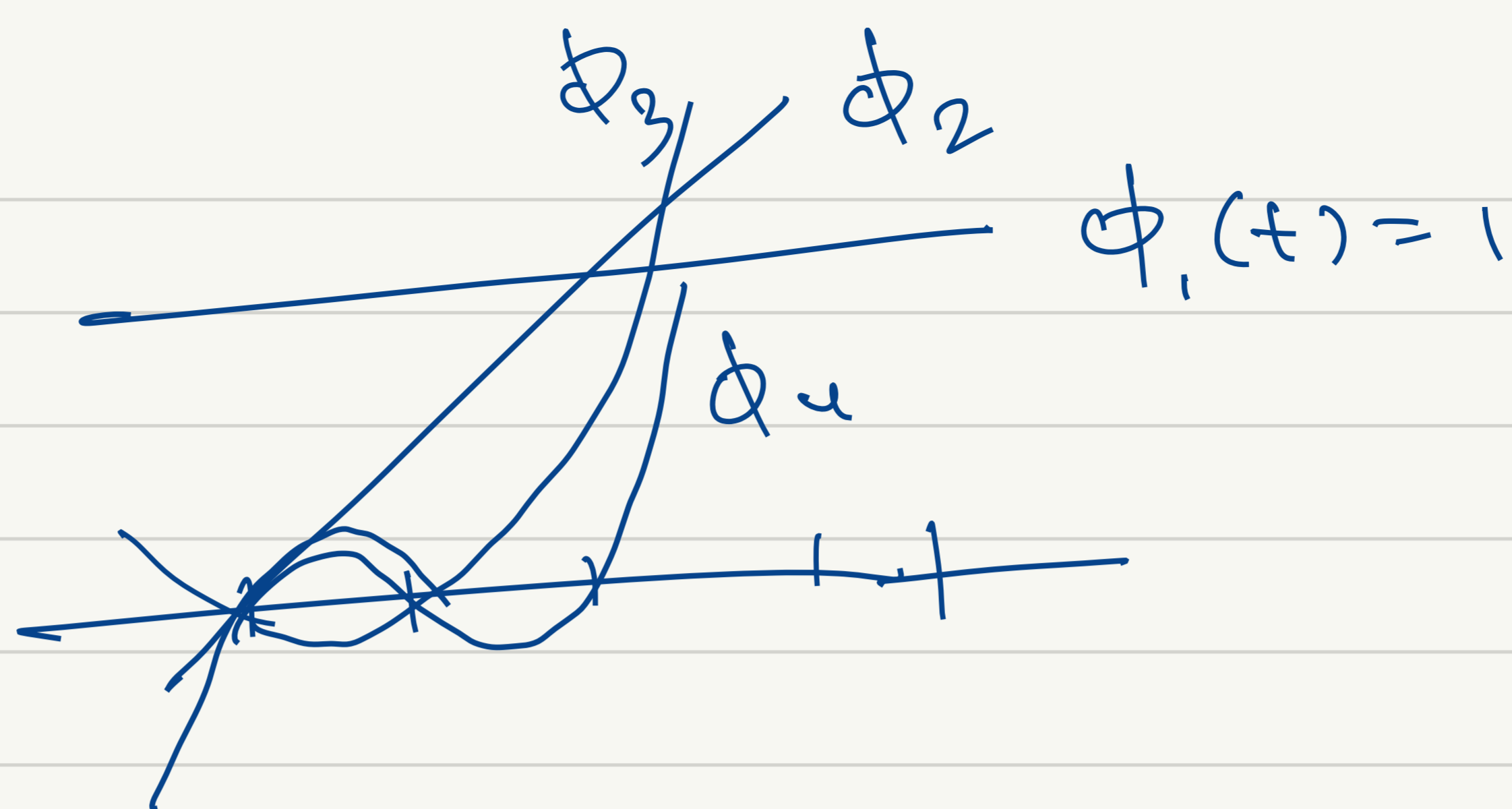
$$\phi_j(t_i) \text{ if } i < j$$

$$\phi_1(t) = 1$$

$$\phi_2(t) = t - t_1$$

$$\phi_3(t) = (t - t_1)(t - t_2)$$

$$\vdots$$
$$\phi_j(t) = \prod_{i < j} (t - t_i)$$



$$A = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 1 & t_2 - t_1 & 0 & \dots & 0 \\ 1 & t_3 - t_1 & * & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & t_n - t_1 & * & \dots & * \end{bmatrix}$$

$\phi_1(t_i) \quad \phi_2(t_i) \quad \phi_3(t_i) \quad \dots \quad \phi_n(t_i)$

Computing  $p$  via  $Ax = y$  takes  $O(n^2)$  time

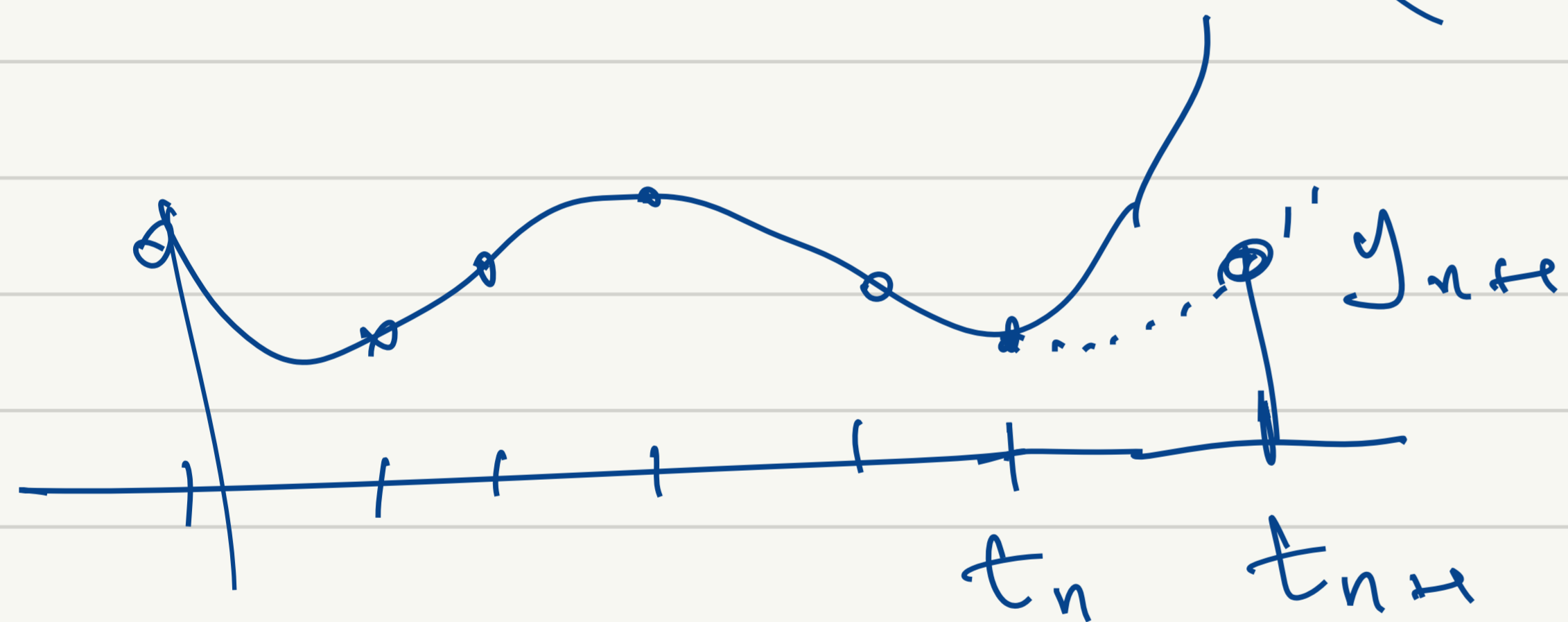


$$p(t) = x_1 \phi_1(t) + x_2 \phi_2(t) + x_3 \phi_3(t) + \dots + x_n \phi_n(t)$$

$$= x_1 + x_2 \underbrace{(t-t_1)} + x_3 \underbrace{(t-t_1)} \underbrace{(t-t_2)} + \dots + x_n \underbrace{(t-t_1)} \underbrace{(t-t_2)} \dots \underbrace{(t-t_{n-1})}$$

$$= x_1 + (t-t_1) \left( x_2 + (t-t_2) \left( x_3 + \dots \left( x_n (t-t_{n-1}) \dots \right) \right) \right)$$

evaluate in  $O(n)$  time



$$\phi_{n+1}(t) = (t-t_1) \dots (t-t_n)$$

Just compute  $x_{n+1}$

# Bounds on polynomial interpolation

$p$  exactly matches  $f$  at  $t_i$

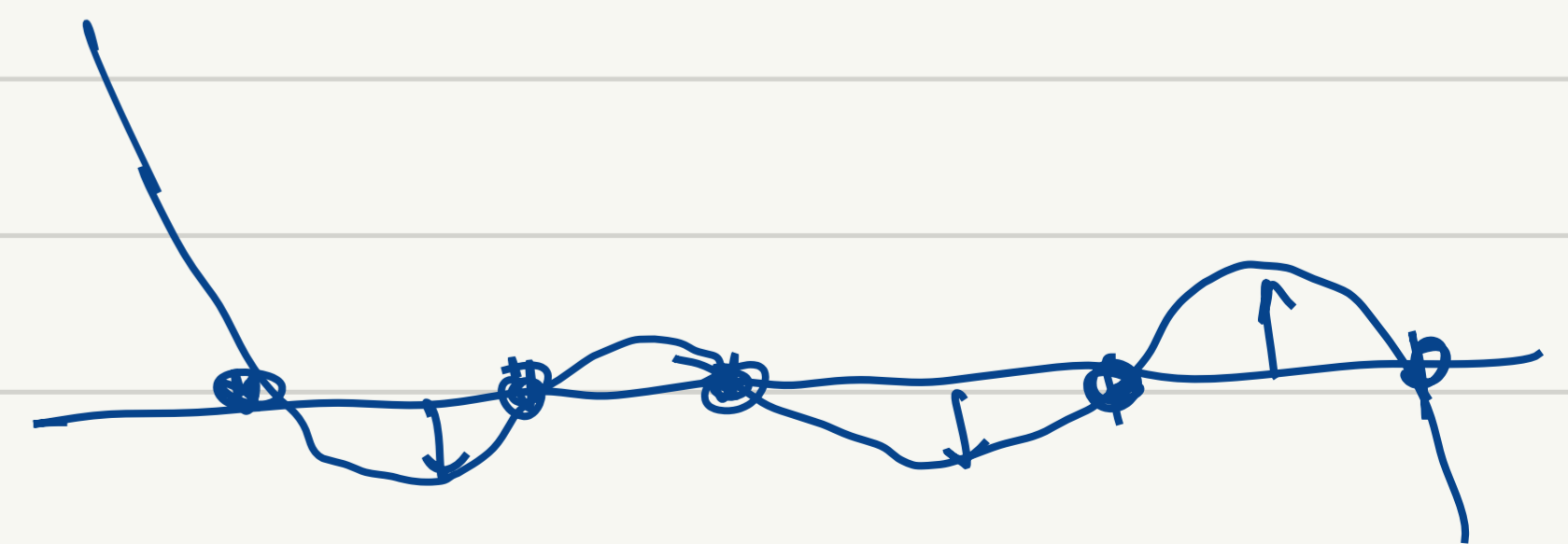
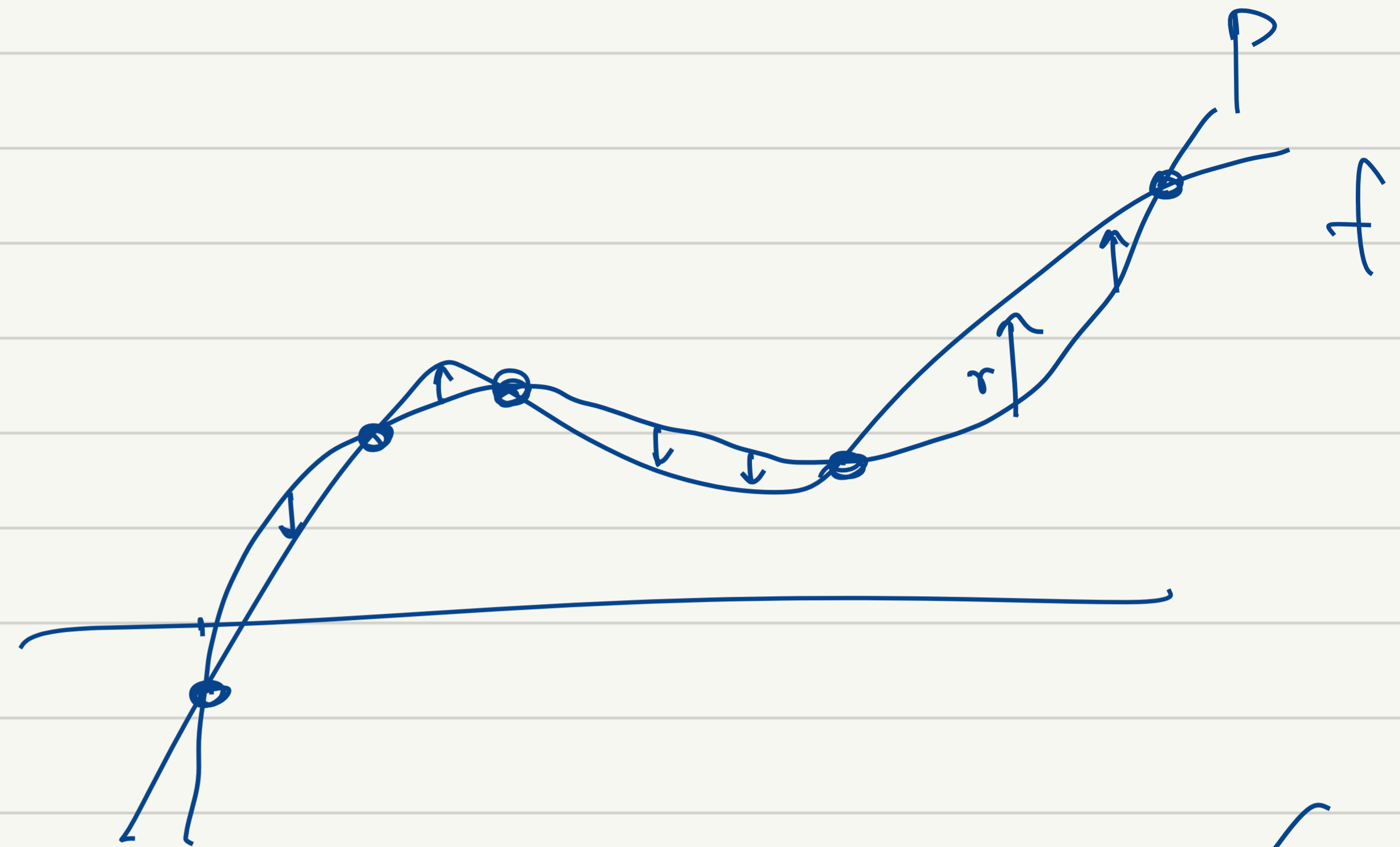
How close is it elsewhere?

Define residual  $f^n$   $r = f - p$

$r = 0$  at  $t_1, t_2, \dots, t_n$

Suppose  $|f^{(n)}(t)| \leq M_n$  for all  $t \in [t_1, t_n]$

$$|r^{(n)}(t)| = |f^{(n)}(t) - \underbrace{p^{(n)}(t)}_{\text{degree } n-1}| = |f^{(n)}(t)| \leq M_n$$



$$\left. \begin{aligned} \text{Assume } |f^{(n)}| \leq M_n &\Rightarrow |r^{(n)}(t)| \leq M_n \\ r^{(n)}(t_i) &= 0 \end{aligned} \right\}$$

How big can  $|r(t)|$  be?

Thm: for any  $t \in [t_1, t_n]$ , there exists  $\theta \in [t_1, t_n]$

$$\text{s.t. } r(t) = \frac{r^{(n)}(\theta)}{n!} \underbrace{(t-t_1) \cdots (t-t_n)}_{w(t)}$$

$$\Rightarrow |r(t)| \leq \frac{M_n}{n!} |w(t)|$$

If equally spaced points  $|t_1 - t_2| = |t_2 - t_3| = \dots = h$

$$\text{then } |w(t)| \leq \frac{h^n (n-1)!}{4} \Rightarrow$$

$$|r(t)| \leq \frac{h^n M_n}{4n}$$

