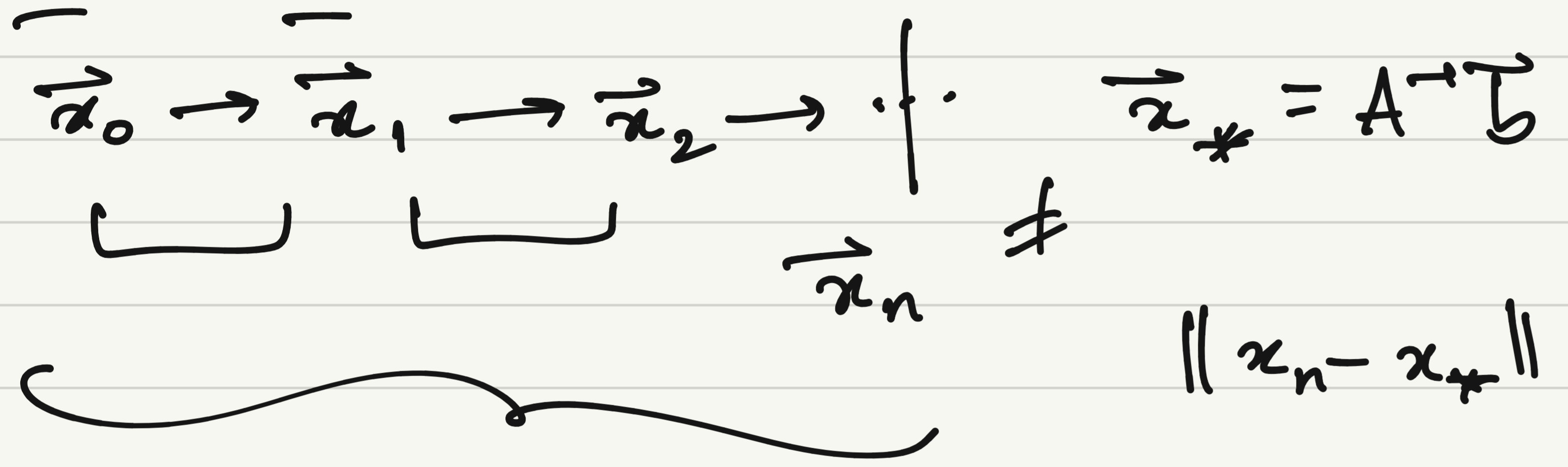


Iterative methods

$$A \vec{x} = \vec{b}$$



Direct methods

$O(m)$ iters
 $O(m^2)$ flops per iter
 $\rightarrow O(m^3)$ flops

$$\| \vec{b} - A \vec{x}_n \|$$

structure

Sparse

non-sparse = dense

$$\# \text{nonzeros}(A) \ll m^2$$

if $O(m)$ nonzeros : can compute $A \vec{x}$ in $O(m)$ flops

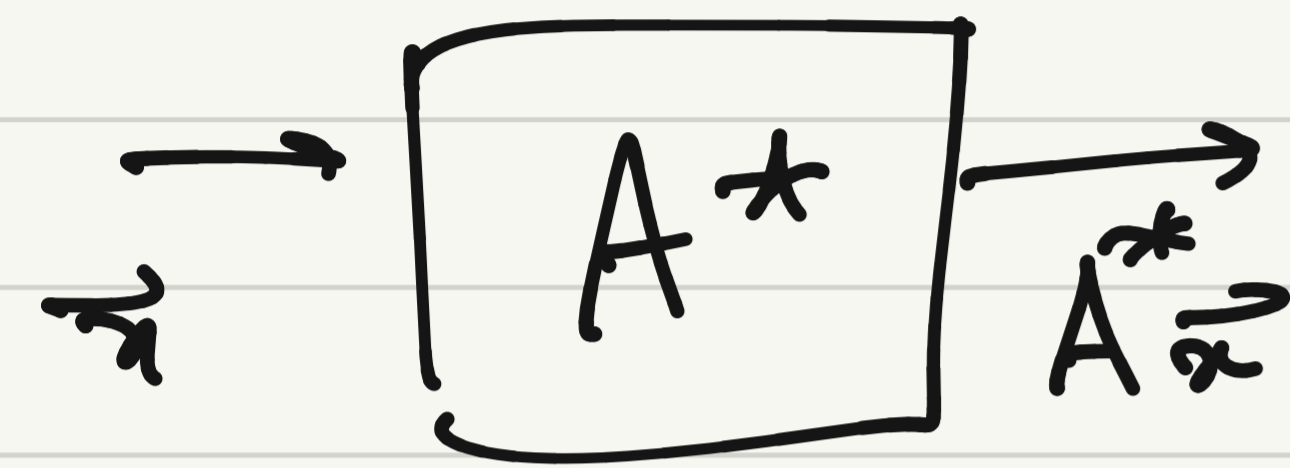
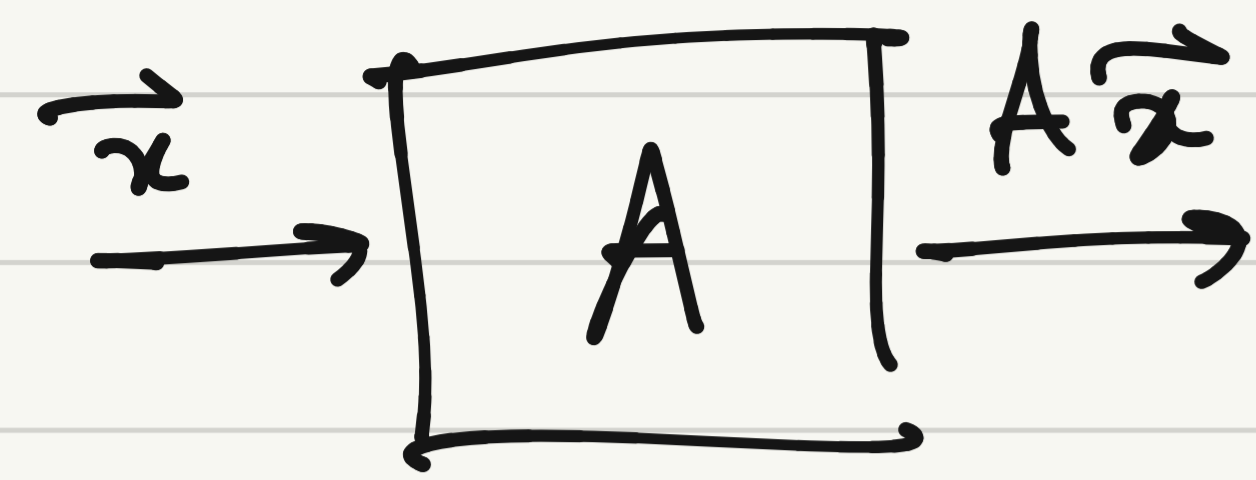
low rank

$$A = \begin{bmatrix} \text{T} \\ \text{U} \end{bmatrix} \begin{bmatrix} \text{W} \\ \text{V} \end{bmatrix}$$

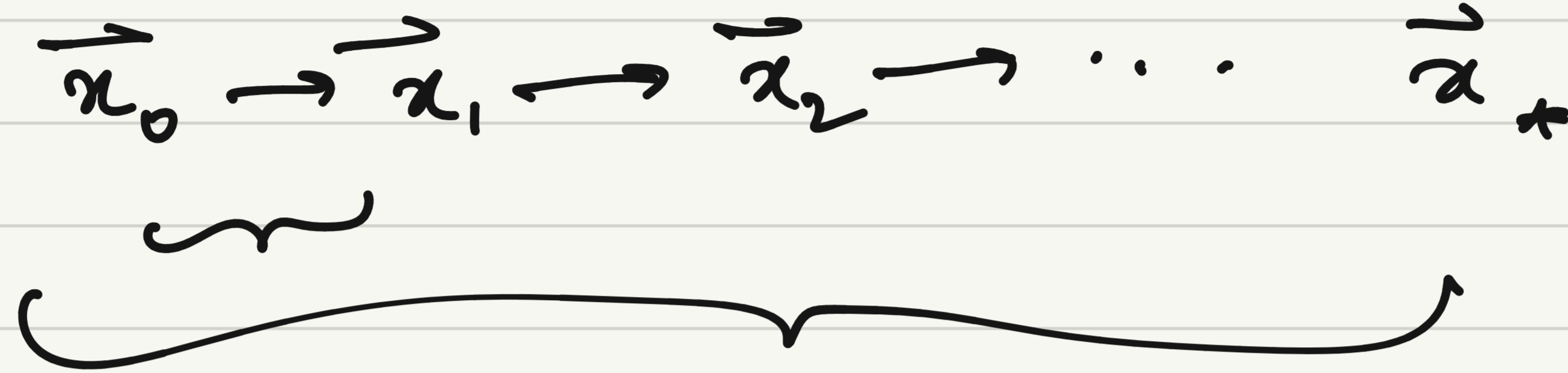
$$\text{rank}(A) = r \ll m$$

$$O(rm) \text{ flops}$$

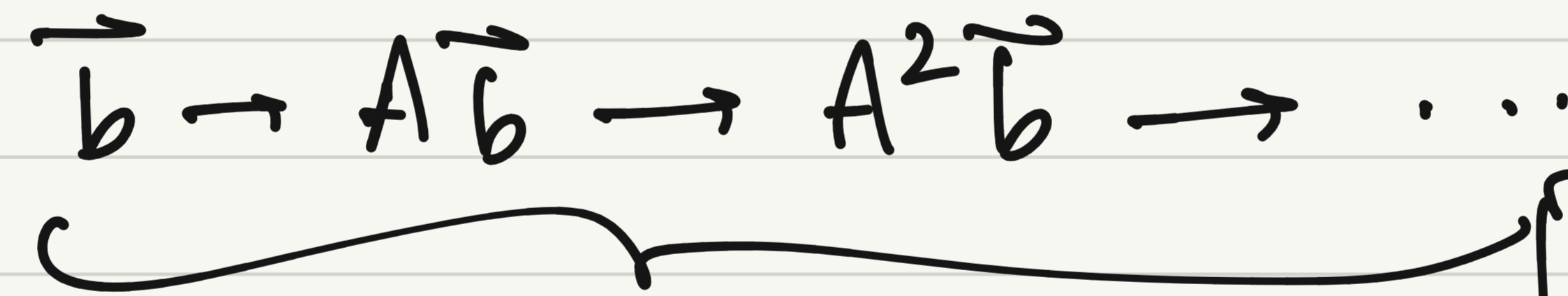
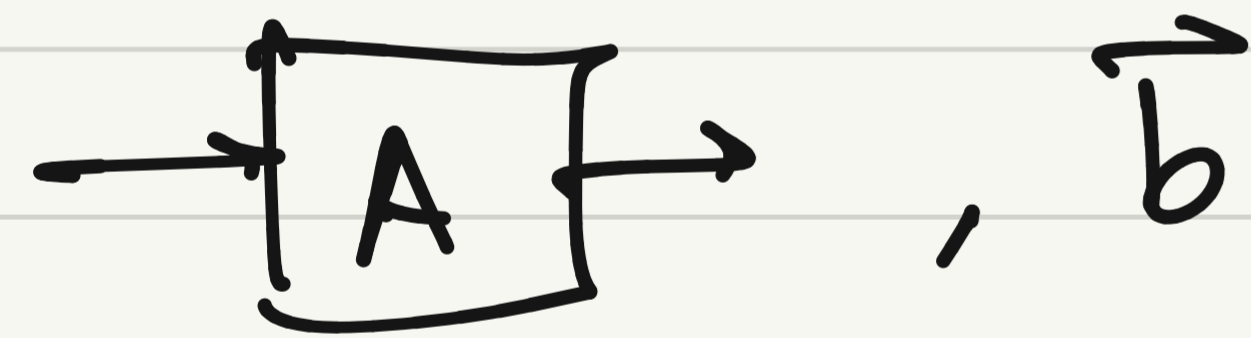
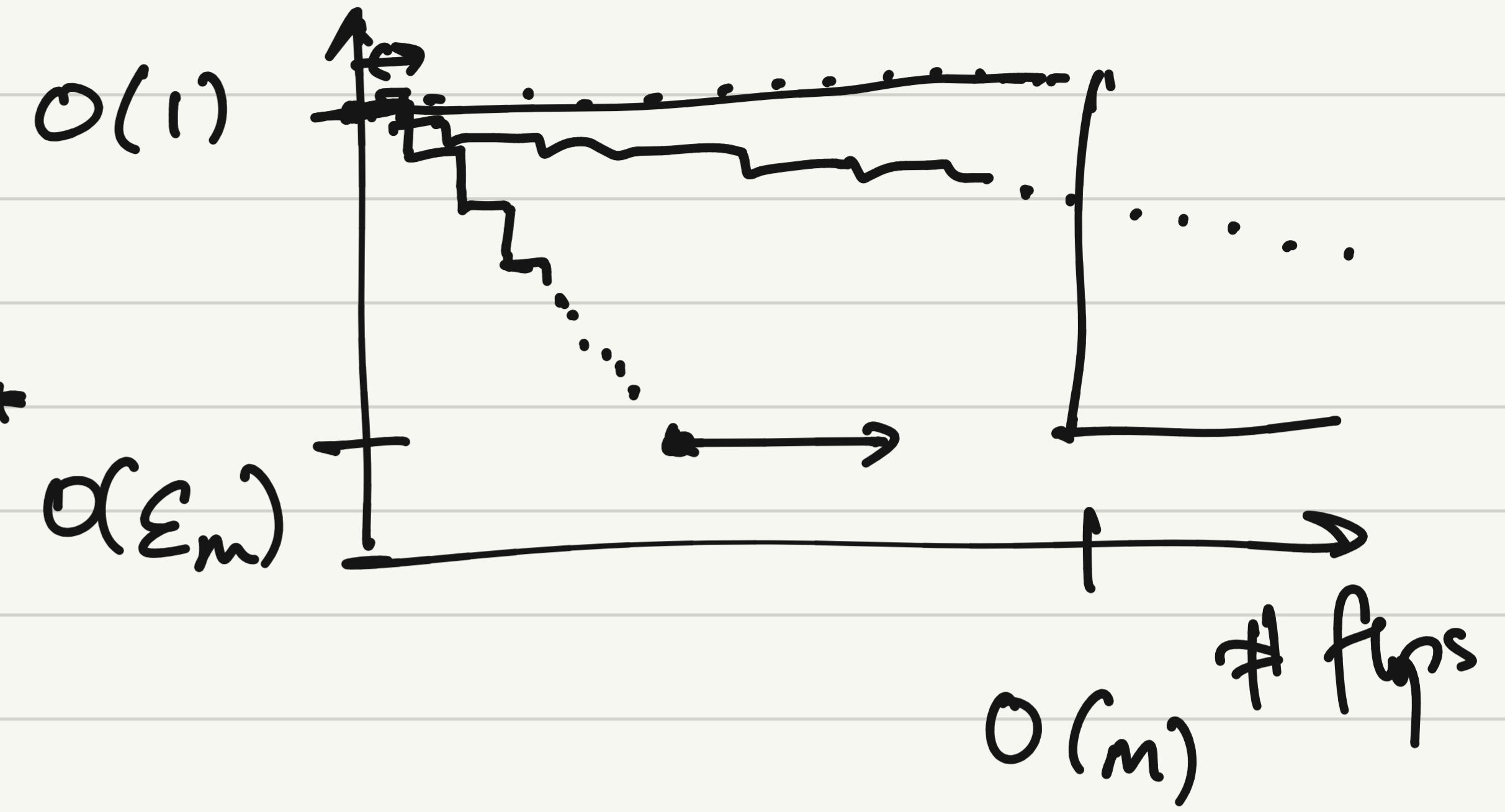
sparse + low rank



$f: \mathbb{R}^m \rightarrow \mathbb{R}^m$, linear



residual $\|b - Ax\| / \|b\|$

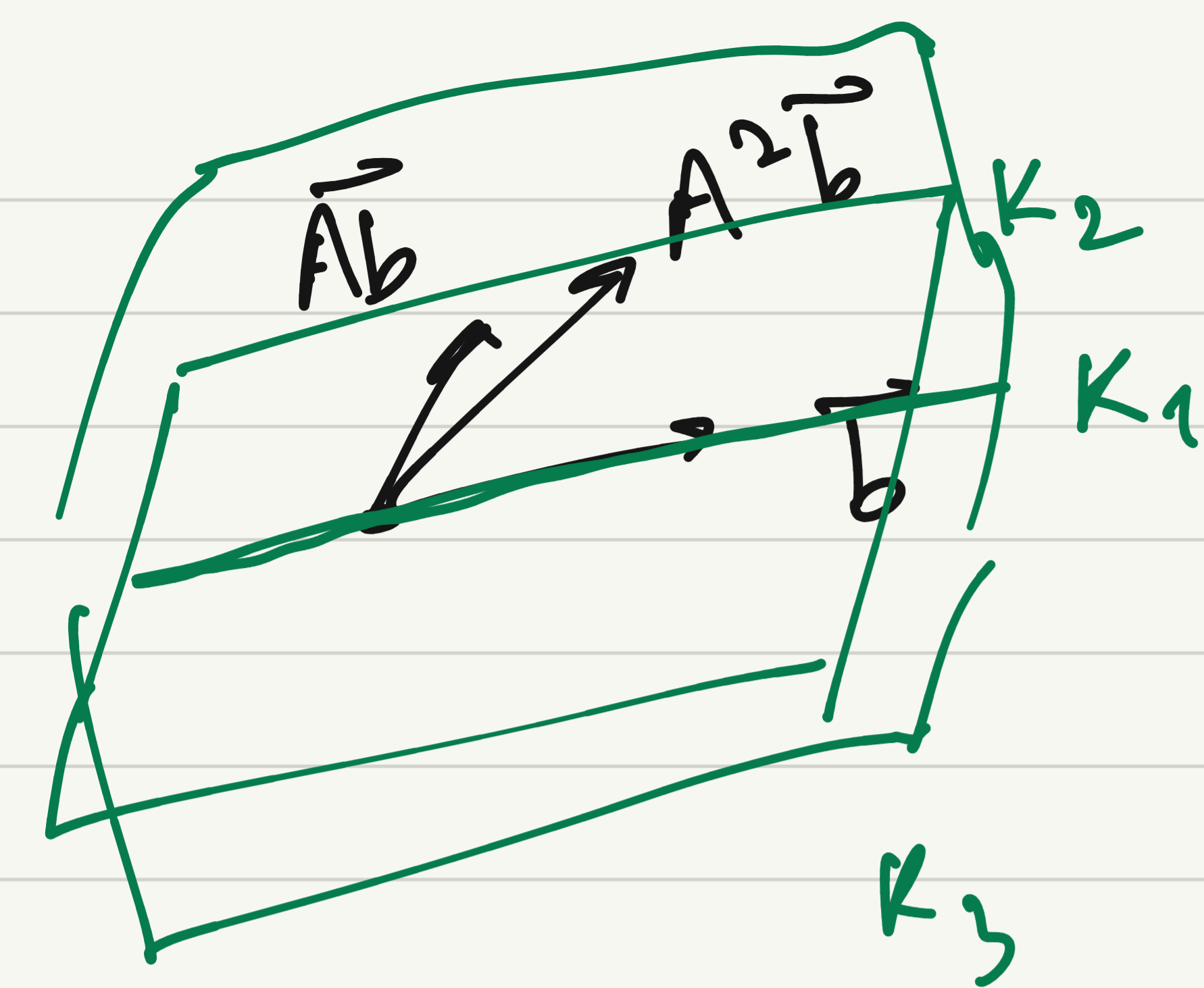


Krylov sequence

$$\mathcal{K}_1 = \langle b \rangle, \quad \mathcal{K}_2 = \langle b, Ab \rangle, \quad \mathcal{K}_3 = \langle b, Ab, A^2b \rangle, \quad \dots$$

$$\mathcal{K}_n = \langle b, Ab, \dots, A^{n-1}b \rangle$$

Krylov subspaces



$$A\vec{x} = \vec{b}$$

$$\min \|\vec{b} - A\vec{x}\|_2 \text{ for } \vec{x} \in K_n = \langle \vec{b}, A\vec{b}, \dots, A^{n-1}\vec{b} \rangle$$

$$\vec{x} = c_0 \vec{b} + c_1 A\vec{b} + \dots + c_{n-1} A^{n-1}\vec{b}$$

$\vec{v}_1, \dots, \vec{v}_m$ eigenvectors of A $|\lambda_1| > |\lambda_2| > \dots > |\lambda_m|$

$$\vec{b} = s_1 \vec{v}_1 + \dots + s_m \vec{v}_m \Rightarrow A^n \vec{b} = s_1 \lambda_1^n \vec{v}_1 + \dots + s_m \lambda_m^n \vec{v}_m$$

$$\approx s_1 \lambda_1^n \vec{v}_1$$

Do Gram-Schmidt on $\vec{b}, A\vec{b}, A^2\vec{b}, \dots$

\Rightarrow Arnoldi iterations

Arnoldi iter

start with $\vec{q}_1 = \vec{b} / \|\vec{b}\|$

for $n = 1, 2, 3, \dots$

$\vec{v}_{n+1} = A \vec{q}_n$
project \vec{v}_{n+1} onto $\langle \vec{q}_1, \dots, \vec{q}_n \rangle^\perp$
set $\vec{q}_{n+1} = \vec{v}_{n+1} / \|\vec{v}_{n+1}\|$

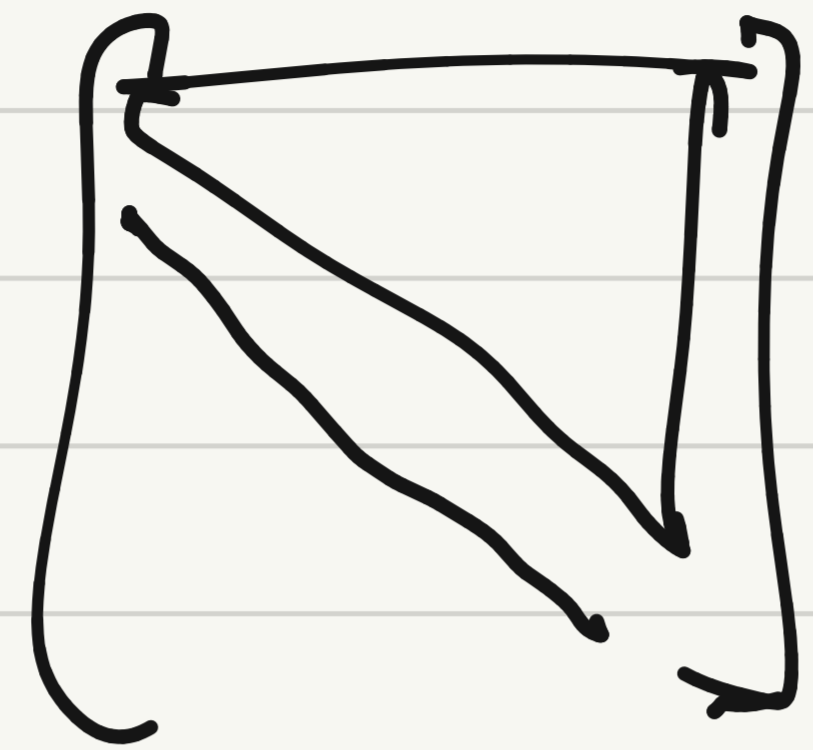
$$A \vec{q}_n \in \langle \vec{q}_1, \dots, \vec{q}_{n+1} \rangle \\ = h_{1n} \vec{q}_1 + \dots + h_{nn} \vec{q}_n + h_{n+1,n} \vec{q}_{n+1}$$

$$A \begin{bmatrix} \vec{q}_1 \\ \vdots \\ \vec{q}_n \end{bmatrix} = \begin{bmatrix} \vec{q}_1 & \dots & \vec{q}_{n+1} \end{bmatrix} \begin{bmatrix} h_{1n} \\ \vdots \\ h_{nn} \\ h_{n+1,n} \end{bmatrix}$$

$$A \begin{bmatrix} \vec{q}_1 & \dots & \vec{q}_n \end{bmatrix} = \begin{bmatrix} \vec{q}_1 & \dots & \vec{q}_n & \vec{q}_{n+1} \end{bmatrix} \begin{bmatrix} h_{11} & h_{12} & \dots & h_{1n} \\ h_{21} & h_{22} & \dots & h_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & h_{nn} \\ \vdots & \vdots & \vdots & h_{n+1,n} \end{bmatrix} \begin{matrix} \\ \\ \\ \\ \end{matrix}$$

$Q_n \in \mathbb{C}^{m \times n}$ $Q_{n+1} \in \mathbb{C}^{m \times (n+1)}$ $H_n \in \mathbb{C}^{(n+1) \times n}$

$$AQ_n = Q_{n+1} H_n$$



Upper Hessenberg

$$\min \|\vec{b} - A\vec{x}\|_2 \text{ s.t. } \vec{x} \in K_n$$

$$= \langle \vec{b}, A\vec{b}, \dots, A^{n-1}\vec{b} \rangle$$

$$= \langle \vec{q}_1, \vec{q}_2, \dots, \vec{q}_n \rangle$$

$$\begin{aligned} n=1 &\rightarrow \vec{x}_1 \\ n=2 &\rightarrow \begin{bmatrix} \vec{x}_1 \\ \vec{x}_2 \\ \vdots \end{bmatrix} \end{aligned}$$

$$\vec{x} = Q_n \vec{y}$$

$$\min \|\vec{b} - AQ_n \vec{y}\|_2 \text{ over all } \vec{y} \in \mathbb{C}^n$$

$$\vec{b} \in \text{range}(Q_{n+1})$$

$$= \|\vec{b} - Q_{n+1} H_n \vec{y}\|_2 = \|\underbrace{Q_{n+1}^* \vec{b}}_{\|\vec{b}\| \vec{e}_1} - \tilde{H}_n \vec{y}\|_2 = \|\underbrace{\|\vec{b}\| \vec{e}_1 - \tilde{H}_n \vec{y}}\|_2$$

$$\min \|\vec{b} - A\vec{x}\|_2 \quad \text{s.t. } \vec{x} \in K_n$$

$$\Leftrightarrow \min \underbrace{\| \tilde{H}_n \vec{y} - \|\vec{b}\| \vec{e}_1 \|_2}_{(n+1) \times n} \quad \text{over all } \vec{y} \in \mathbb{C}^n$$

compute QR of $\tilde{H}_n \rightarrow$ solve for $\vec{y}_n \rightarrow \vec{x}_n = Q_n \vec{y}_n$

GMRES (generalized minimum residual method)

for $n = 1, 2, 3, \dots$

do Arnoldi to get $Q_n, \tilde{H}_n \leftarrow O(mn)$

solve $\min \|\cdot - \cdot\| \leftarrow O(n^3)$

cost increases every iteration!

using Hessenberg $qr(\tilde{H}_n) : O(n^2)$

$qr(\tilde{H}_{n+1}) \rightarrow qr(\tilde{H}_n) : O(n)$

n iters $\rightarrow \vec{x}_n$

$$\vec{x}_* = \vec{x}_n + \Delta \vec{x} \Rightarrow \text{solve } A \Delta \vec{x} = \underbrace{\vec{b} - A \vec{x}_n}$$

Convergence of GMRES

$\vec{x}_1, \vec{x}_2, \vec{x}_3, \dots$

$$\vec{r}_n = \vec{b} - A \vec{x}_n, \quad \|\vec{r}_n\| \stackrel{?}{\rightarrow} 0$$

1. $\|\vec{r}_{n+1}\| \leq \|\vec{r}_n\|$

2. $\|\vec{r}_n\| = 0$ for some $n \leq m$

$$K_m = \mathbb{C}^m$$

$$A \vec{q}_n \in \langle \vec{q}_1, \dots, \vec{q}_n \rangle \quad : \quad \boxed{\text{breakdown}}$$

find upper bound for $\|\vec{r}_n\|$ for any $n < m$?

$$\text{then } \vec{x}_* \in \langle \vec{q}_1, \dots, \vec{q}_n \rangle$$

Krylov subspaces \leftrightarrow polynomial approximation \leftrightarrow eigenvalues of A

$\min \|\dots\|$ over all $\vec{x} \in K_n$

$$\text{Any } \vec{x} \in K_n : \vec{x} = c_0 \vec{b} + c_1 A \vec{b} + \dots + c_{n-1} A^{n-1} \vec{b}$$

$$= \underbrace{(c_0 I + c_1 A + \dots + c_{n-1} A^{n-1})}_{q(A)} \vec{b}$$

$$= q(A) \vec{b}$$

$$q(z) = c_0 + c_1 z + \dots + c_{n-1} z^{n-1}$$

$\min \|\vec{r}_n\|$

$$\vec{r} = \vec{b} - A \vec{x} = \vec{b} - A q(A) \vec{b} = \underbrace{(I - A q(A))}_{p(A)} \vec{b}$$

$$\min \|\vec{r}_n\|_2 \Leftrightarrow \min \|p(A) \vec{b}\|_2$$

$$\|\vec{r}_n\|_2 = \inf \|p(A) \vec{b}\|_2 \leq \|\vec{b}\|_2 \inf \|p(A)\|_2$$

$p(z) = 1 - z q(z)$
degree- n poly.
with const. term 1.

Q. for which matrices does GMRES converge quickly?

A. When \exists poly. p s.t. $\|p(A)\|_2$ is small

Next: for which matrices does such poly exist??