

COL865: Special Topics in Computer Applications

# **Physics-Based Animation**

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## **13 – Fluid simulation on grids**

# Review

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Navier-Stokes equations for fluid velocity  $\mathbf{u}(\mathbf{x}, t)$ :

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = \rho^{-1} (-\nabla p + \mu \nabla^2 \mathbf{u} + \mathbf{f}_{\text{ext}})$$

$$\nabla \cdot \mathbf{u} = 0$$

Solve on grid via *splitting*:

- **Advection**:  $\mathbf{u}^{(1)} = \text{advect}(\mathbf{u}^n, \mathbf{u}^n, \Delta t)$
- **Body forces**:  $\mathbf{u}^{(2)} = \mathbf{u}^{(1)} + \mathbf{f}_{\text{ext}} \Delta t$
- **Viscosity**:  $\mathbf{u}^{(3)} = \mathbf{u}^{(2)} + \nu \nabla^2 \mathbf{u} \Delta t$
- **Pressure**:  $\mathbf{u}^{n+1} = \mathbf{u}^{(3)} - \nabla p \Delta t$  so that  $\nabla \cdot \mathbf{u}^{n+1} = 0$

# **Advection**

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# Advection

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Advection of passive scalar  $c$   
by velocity field  $\mathbf{u}$ :

$$\partial c / \partial t + \mathbf{u} \cdot \nabla c = 0$$

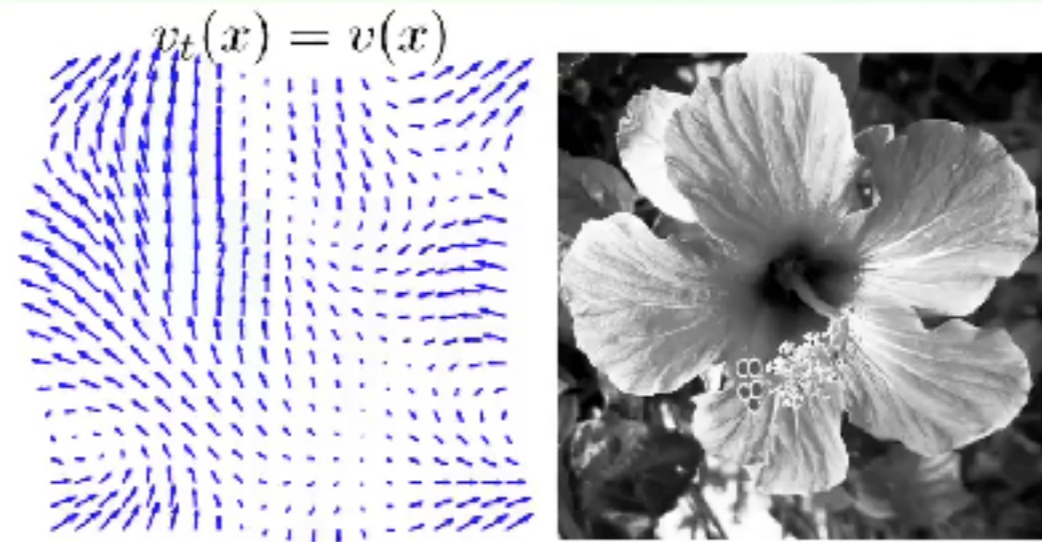
Given  $c^n = c(\mathbf{x}, t^n)$ , solve for  
 $c^{n+1} = c(\mathbf{x}, t^{n+1})$

$$c^{n+1} = \text{advect}(c^n, \mathbf{u}, \Delta t)$$

Lagrangian:  $\dot{x}(t) = v_t(x(t))$

Eulerian:  $\frac{\partial f_t(x)}{\partial t} = \text{div}(v_t(x) f_t(x))$

*Theorem:*  $f_t(x(0)) = f_0(x(t))$



[Peyré 2018]

# Finite differences

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$$\partial c / \partial t + \mathbf{u} \cdot \nabla c = 0$$

Directly discretize  $\partial c / \partial t$ ,  $\nabla c$  with standard FD formulas

- Upwinding, Lax-Friedrichs, Lax-Wendroff, ... [Trefethen Ch. 3.2]

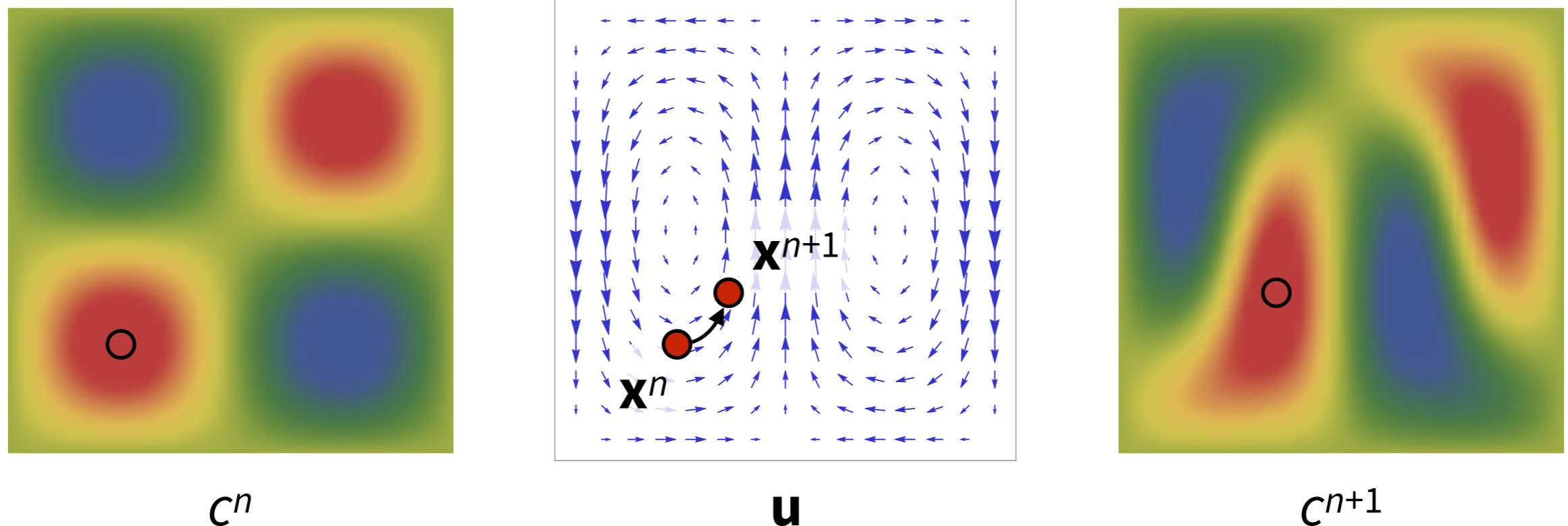
Explicit schemes limited by CFL condition:

$$\Delta t \leq a \Delta x / \|\mathbf{u}\| \text{ for some constant } a$$

# Semi-Lagrangian advection

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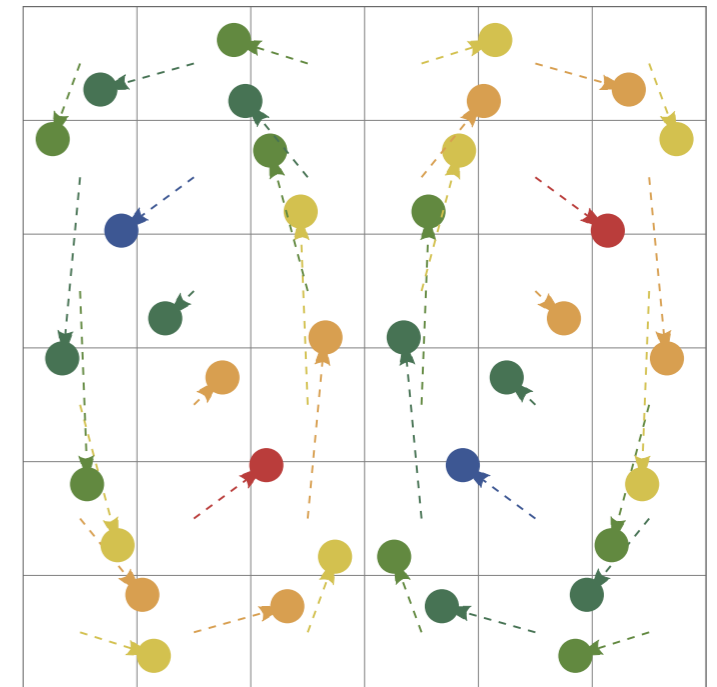
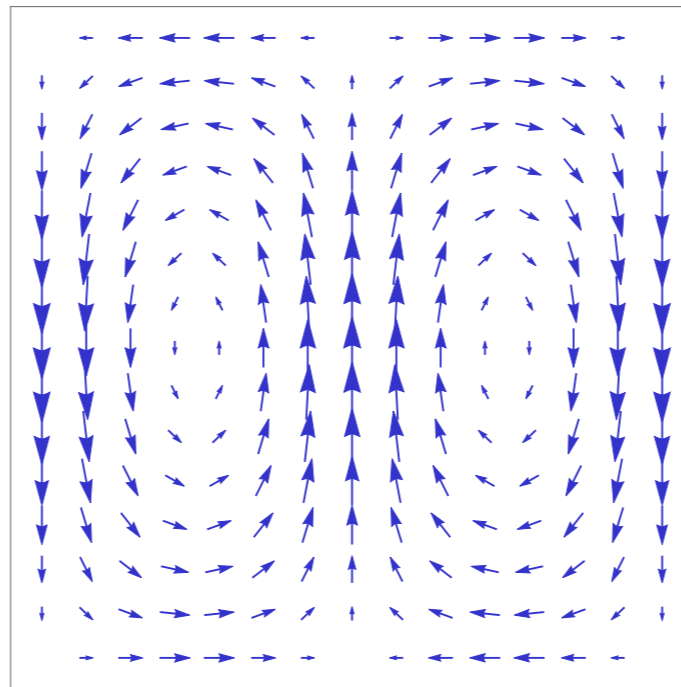
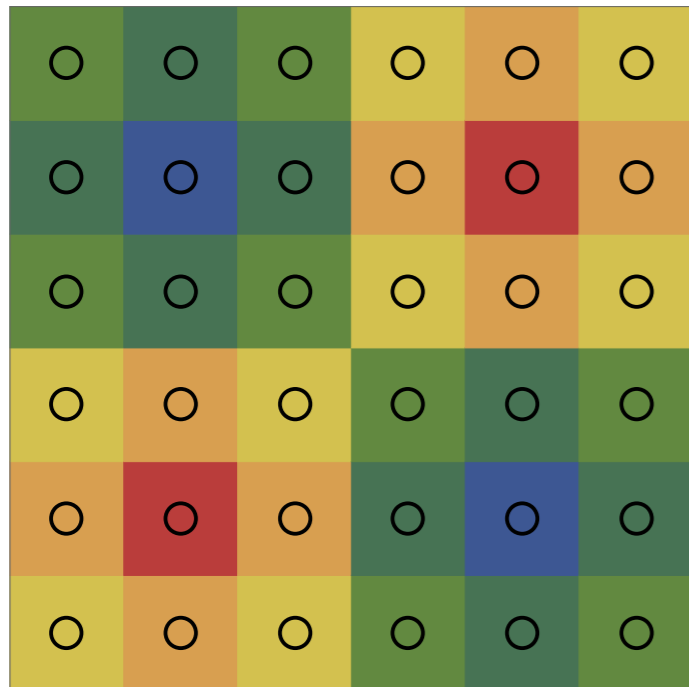
Particle view of advection:



Particle moves through velocity field:  $d\mathbf{x}_i/dt = \mathbf{u}(\mathbf{x}_i)$

$$c(\mathbf{x}_i^{n+1}, t^{n+1}) = c(\mathbf{x}_i^n, t^n)$$

# Semi-Lagrangian advection

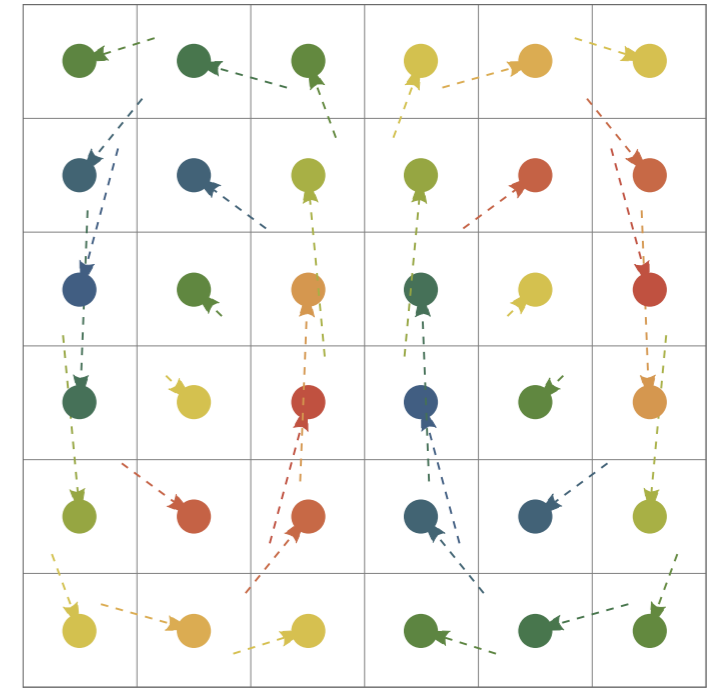
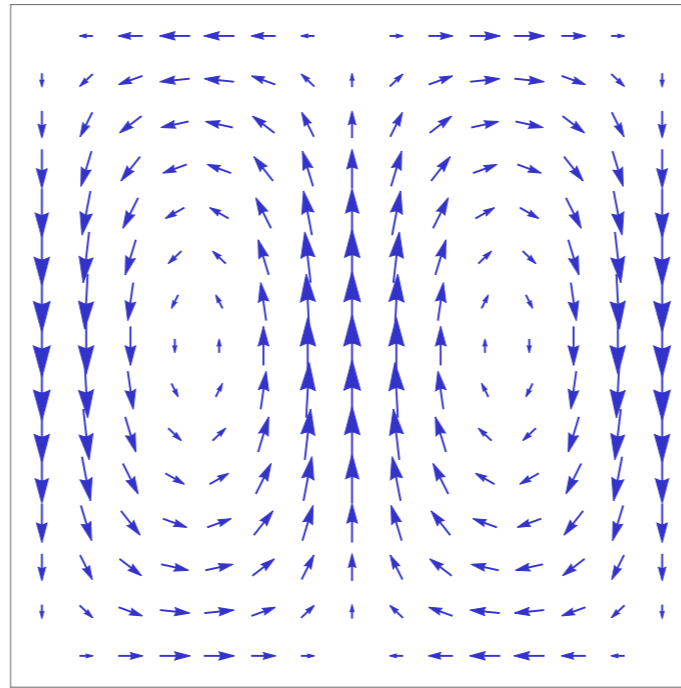
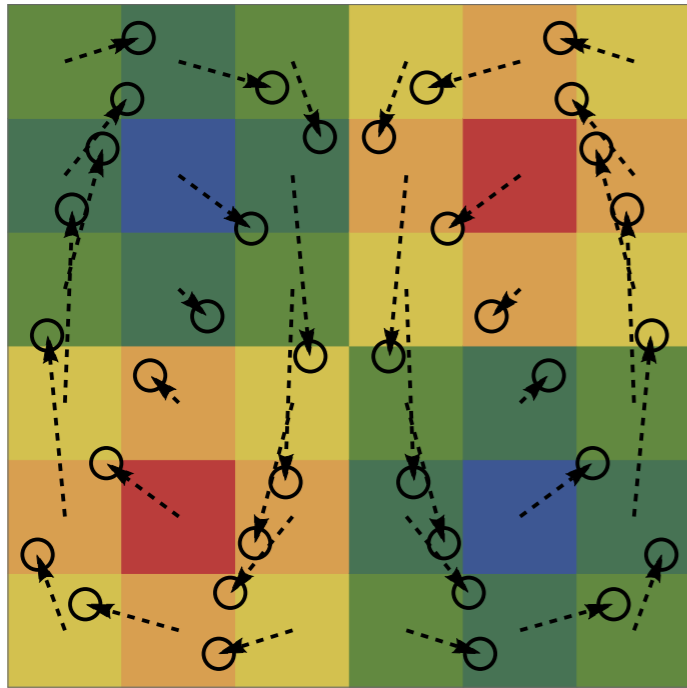


Idea:

1. For each grid node of  $c^n$ , create a particle
2. Trace particles forward with  $d\mathbf{x}_i/dt = \mathbf{u}(\mathbf{x}_i)$  over  $\Delta t$

But particles don't land on grid nodes of  $c^{n+1}$

# Semi-Lagrangian advection



Simple fix [Stam 1999]:

1. For each grid node of  $c^{n+1}$ , create a particle
2. Trace particles **backwards** over  $-\Delta t$ , look up (interpolated) value in  $c^n$ , write into  $c^{n+1}$



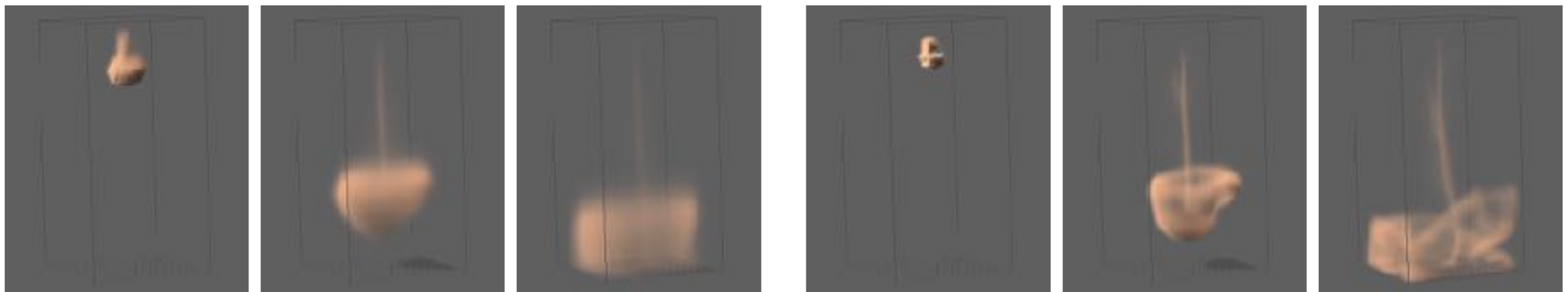
# Semi-Lagrangian advection

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***Advantage:*** Unconditionally stable

***Limitation:*** Numerical diffusion

- Monotone cubic interpolation [Fedkiw et al. 2001, App. B]
- Higher-order correction schemes [Kim et al. 2005, Selle et al. 2006]



[Fedkiw et al. 2001]

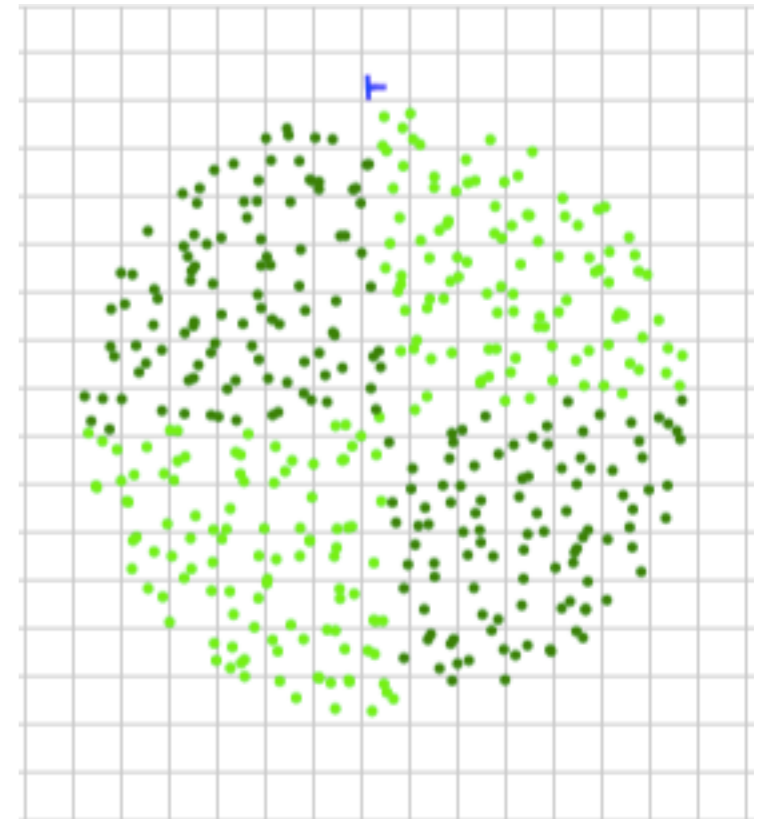
# Particle advection

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Keep  $c$  stored on particles that persist across time steps [Zhu and Bridson 2005]

1. Trace particles forward with  $d\mathbf{x}_i/dt = \mathbf{u}_{\text{grid}}(\mathbf{x}_i)$  as usual
2. Transfer  $c_i$  values to grid nodes: weighted average using grid interpolation weights

Diffusion doesn't accumulate over time steps



[Jiang et al. 2015]

# Particle advection

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$$\mathbf{u}^{(1)} = \text{advect}(\mathbf{u}^n, \mathbf{u}^n, \Delta t)$$

- Move particles using  $\mathbf{u}_{\text{grid}}$
- Transfer particle  $\mathbf{u}_i$  to grid

$$\mathbf{u}^{(2)} = \mathbf{u}^{(1)} + \mathbf{f}_{\text{ext}} \Delta t$$

$$\mathbf{u}^{(3)} = \mathbf{u}^{(2)} + \nu \nabla^2 \mathbf{u} \Delta t$$

$$\mathbf{u}^{n+1} = \mathbf{u}^{(3)} - \nabla p \Delta t, \quad \nabla \cdot \mathbf{u}^{n+1} = 0$$

At next time step,  $\mathbf{u}$  on grid will have changed

- **Particle-in-cell (PIC):**  
First transfer values  $\mathbf{u}_i = \mathbf{u}(\mathbf{x}_i)$ 
  - Problem: diffusion
- **Fluid implicit particle (FLIP):**  
Only transfer **change** in  $\mathbf{u}$   
(i.e. effect of forces)

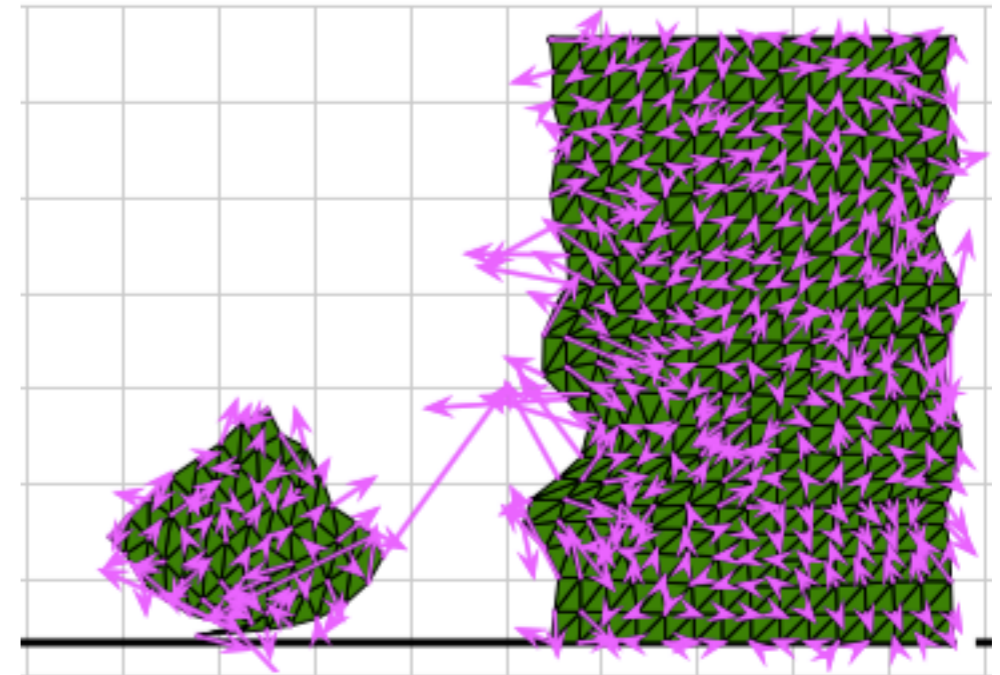
See Zhu and Bridson [2005] for details

# Particle advection

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Pure FLIP is unstable

- **Fix:** Blend with small amount (1%-5%) of PIC
- **Better fix:** Use APIC [Jiang et al. 2015], PolyPIC [Fu et al. 2017]



[Jiang et al. 2015]

# Pressure

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# Pressure

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- $\mathbf{u}^{(1)} = \text{advect}(\mathbf{u}^n, \mathbf{u}^n, \Delta t)$
- $\mathbf{u}^{(2)} = \mathbf{u}^{(1)} + \mathbf{f}_{\text{ext}} \Delta t$
- $\mathbf{u}^{(3)} = \mathbf{u}^{(2)} + \nu \nabla^2 \mathbf{u} \Delta t$

After these steps, we have intermediate velocity  $\tilde{\mathbf{u}} = \mathbf{u}^{(3)}$

$$\begin{aligned}\mathbf{u}^{n+1} &= \tilde{\mathbf{u}} - \nabla p \Delta t, \\ \nabla \cdot \mathbf{u}^{n+1} &= 0\end{aligned}$$

“Project out” the divergence in  $\tilde{\mathbf{u}}$

# Pressure as decomposition

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## *Helmholtz-Hodge decomposition:*

Decompose  $\tilde{\mathbf{u}}$  into divergence-free and curl-free components

$\tilde{\mathbf{u}}$

=

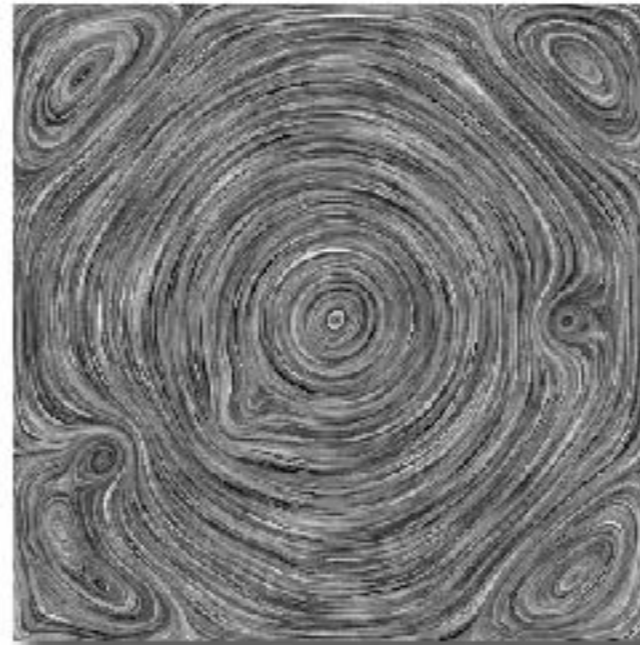
$\mathbf{u}^{n+1}$

+

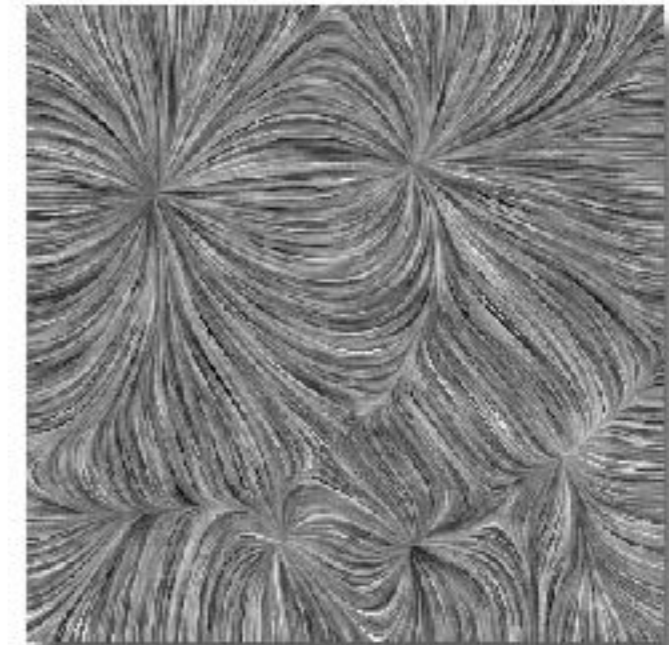
$\nabla p$



=



+



[Tong et al. 2003]

# Pressure as projection

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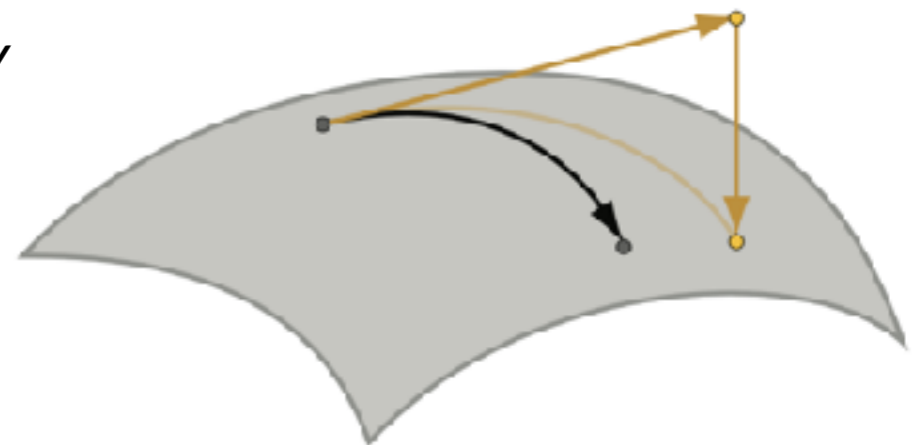
Given  $\tilde{\mathbf{u}}$ , find “nearest” vector  $\mathbf{u}^{n+1}$  in divergence-free subspace

$$\mathbf{u}^{n+1} = \arg \min_{\nabla \cdot \mathbf{u} = 0} \iiint \rho \|\mathbf{u} - \tilde{\mathbf{u}}\|^2 dV$$

Orthogonal projection

⇒ always reduces energy  $\iiint \rho \|\mathbf{u}\|^2 dV$

⇒ unconditionally stable



[Elcott et al. 2007]



# Computing the pressure

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Just plug it in:

$$\mathbf{u}^{n+1} = \tilde{\mathbf{u}} - \nabla p \Delta t,$$

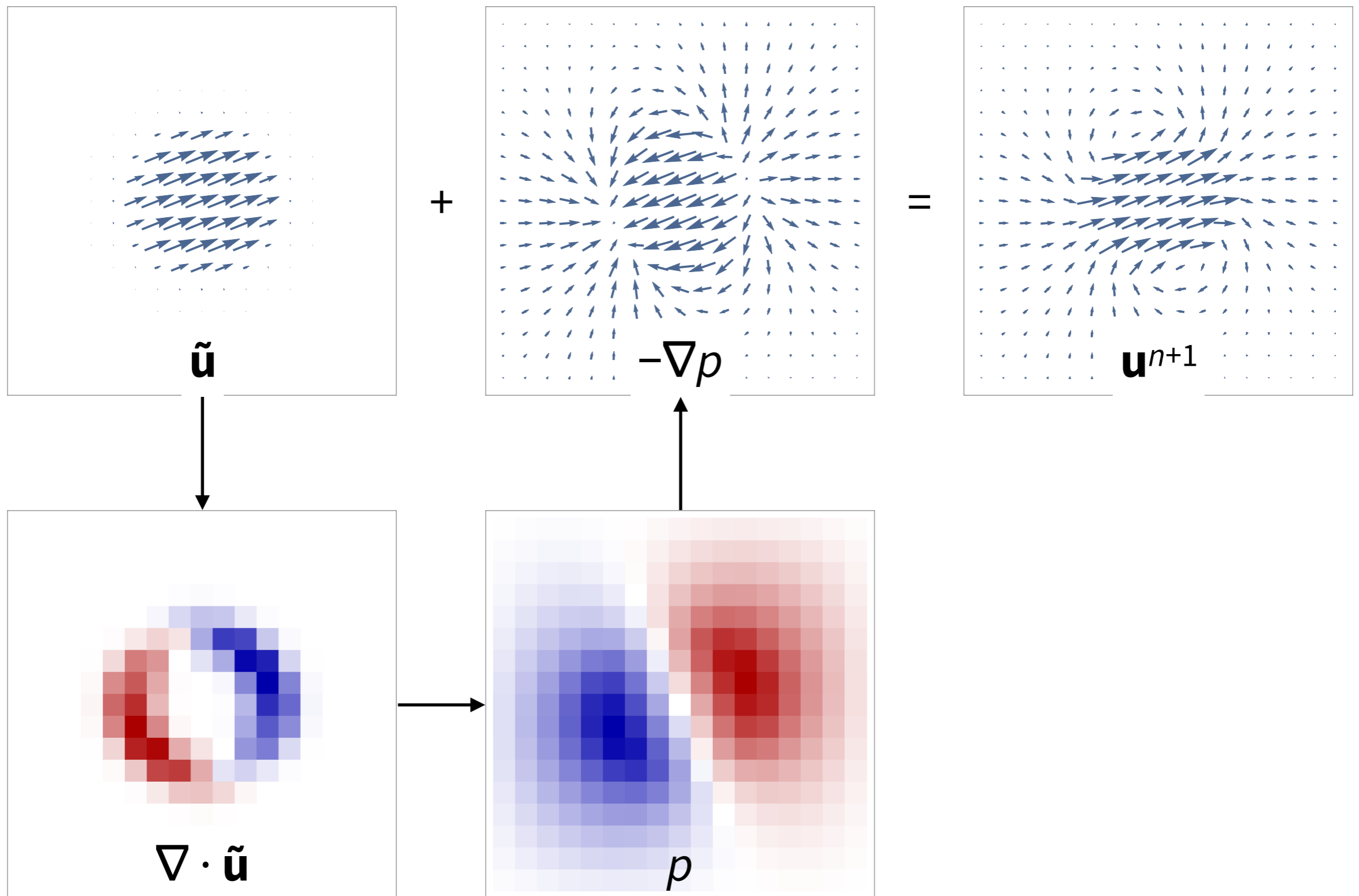
$$\nabla \cdot \mathbf{u}^{n+1} = 0$$

$$\Rightarrow \nabla \cdot \tilde{\mathbf{u}} - \nabla^2 p \Delta t = 0$$

1. Compute  $\nabla \cdot \tilde{\mathbf{u}}$
2. Solve PDE:  $\nabla^2 p \Delta t = \nabla \cdot \tilde{\mathbf{u}}$  for  $p$
3. Apply force  $\nabla p \Delta t$  to get  $\mathbf{u}^{n+1}$

Finding scalar field with specified Laplacian: ***Poisson problem***

# Pressure projection

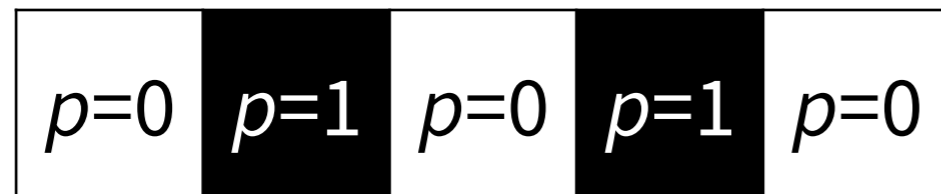


# Spatial discretization

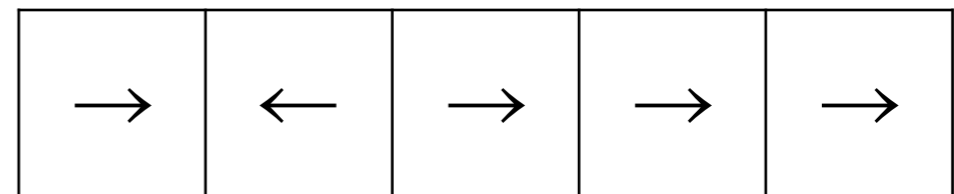
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Issues discretizing grad, div:

- Forward, backward diff: directional bias
- Centered diff: ***null space problem***

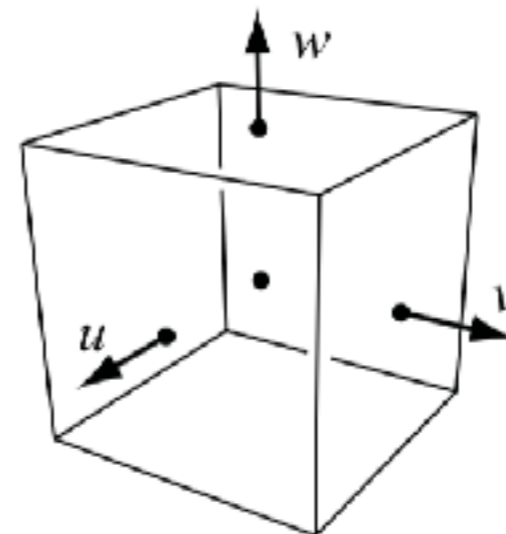


$$\nabla p = 0?!$$



$$\nabla \cdot \mathbf{u} = 0?!$$

Solution: ***Staggered grid***, a.k.a. ***marker-and-cell (MAC) grid***



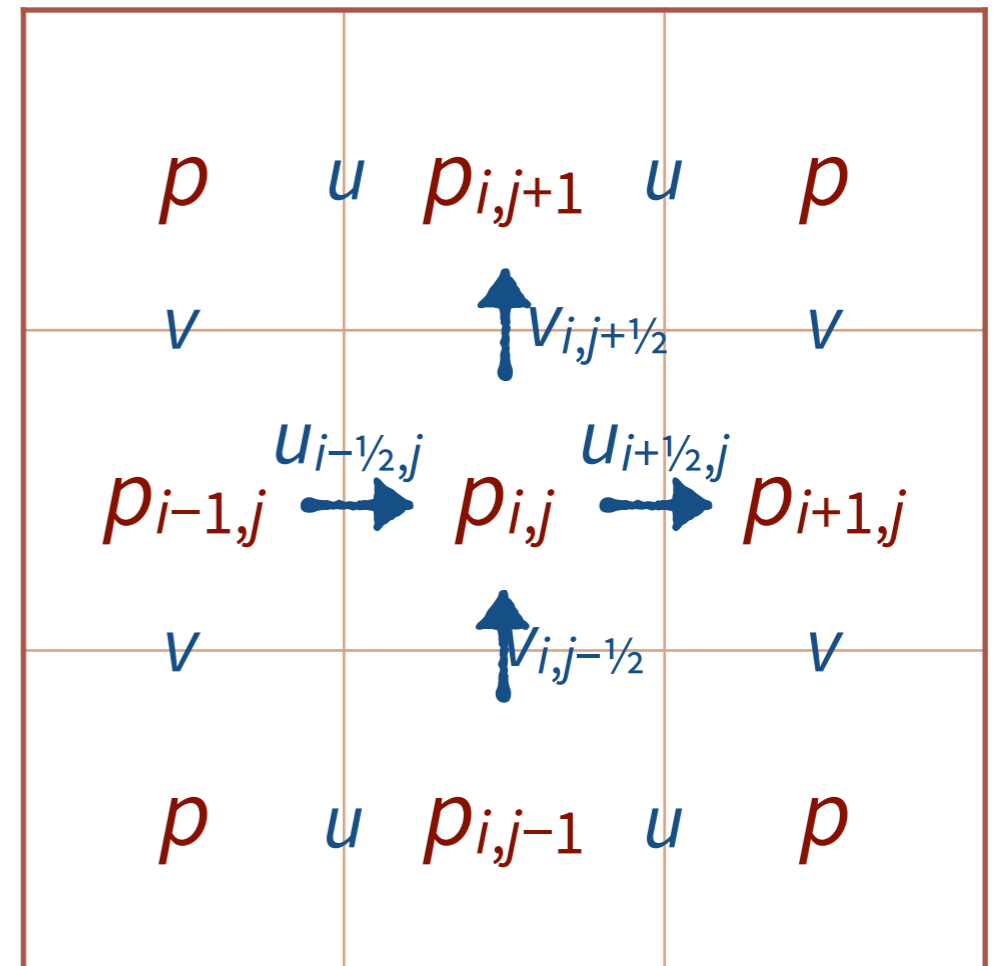
[Fedkiw et al. 2001]

# Staggered grids

Scalars at cell centers, vector components on perpendicular faces

Fits nicely with grad, div:

- Value of  $\nabla \cdot \mathbf{u}$  at cell center
- Components of  $\nabla p$  on faces



**Implementation note:** Be very careful about indexing!

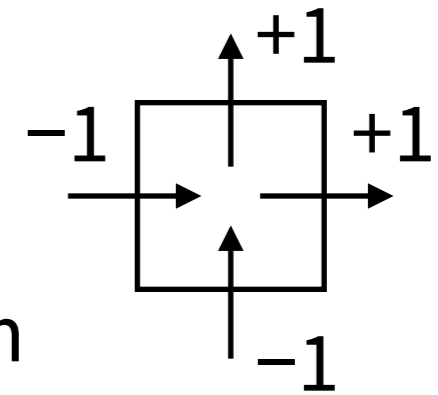
- 3 separate arrays:  $u_x(m+1, n, o)$ ,  $u_y(m, n+1, o)$ ,  $u_z(m, n, o+1)$

# Pressure projection on staggered grids

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1. Compute  $\nabla \cdot \tilde{\mathbf{u}}$

$$(\nabla \cdot \mathbf{u})_{i,j} \approx (u_{i+1/2,j} - u_{i-1/2,j})/\Delta x + (v_{i,j+1/2} - v_{i,j-1/2})/\Delta x$$

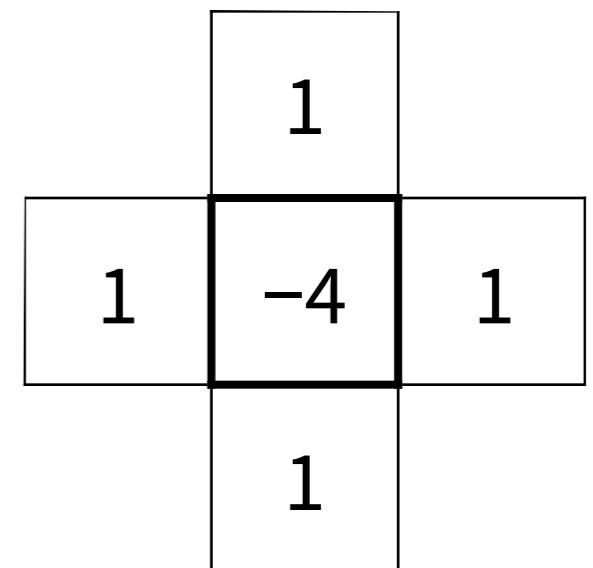


Looks like discrete version of divergence theorem

$$\iiint \nabla \cdot \mathbf{u} \, dV = \iint \mathbf{u} \cdot \mathbf{n} \, dA$$

2. Define Laplacian  $\nabla^2 p$  as usual:

$$(\nabla^2 p)_{i,j} \approx (p_{i-1,j} + p_{i+1,j} + p_{i,j-1} + p_{i,j+1} - 4 p_{i,j})/\Delta x^2$$



# Pressure boundary conditions

## ***Solid boundaries:***

- Fix  $\tilde{\mathbf{u}} \cdot \mathbf{n} = 0$  (no-through boundary condition)
- Pressure shouldn't change this, so  $\nabla p \cdot \mathbf{n} = 0$  (Neumann boundary)

$$p_{-1,j} = p_{0,j}$$

$$\begin{aligned}(\nabla^2 p)_{0,j} &\approx (p_{-1,j} + p_{1,j} + p_{0,j-1} + p_{0,j+1} - 4 p_{0,j}) / \Delta x^2 \\ &= (p_{1,j} + p_{0,j-1} + p_{0,j+1} - 3 p_{0,j}) / \Delta x^2\end{aligned}$$

***Free surfaces:***  $p = 0$  (next class)

