

# Algorithms for Fault-Tolerant Routing in Circuit Switched Networks\*

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## Abstract

In this paper we consider the  $k$  edge-disjoint paths problem ( $k$ -EDP), a generalization of the well known edge-disjoint paths problem. Given a graph  $G = (V, E)$  and a set of terminal pairs (or requests)  $T$ , the problem is to find a maximum subset of the pairs in  $T$  for which it is possible to select paths such that each pair is connected by  $k$  edge-disjoint paths and the paths for different pairs are mutually disjoint. To the best of our knowledge, no nontrivial result is known for this problem for  $k > 1$ . To measure the performance of our algorithms we use the recently introduced flow number  $F$  of a graph. This parameter is known to fulfill  $F = O(\Delta\alpha^{-1} \log n)$ , where  $\Delta$  is the maximum degree and  $\alpha$  is the edge expansion of  $G$ . We show that a simple, greedy online algorithm achieves a competitive ratio of  $O(k^3 \cdot F)$ , which naturally extends the best known bound of  $O(F)$  for  $k = 1$  to higher  $k$ . To achieve this competitive ratio, we introduce a new method of converting a system of  $k$  disjoint paths into a system of  $k$  length-bounded disjoint paths. We also show that any deterministic online algorithm has a competitive ratio of  $\Omega(k \cdot F)$ .

In addition, we study the  $k$  disjoint flows problem ( $k$ -DFP), which is a generalization of the previously studied unsplittable flow problem (UFP). The difference between the  $k$ -DFP and the  $k$ -EDP is that now we consider a graph with edge capacities and our requests are allowed to have arbitrary demands  $d_i$ . The aim is to find a subset of requests of maximum total demand for which it is possible to select flow paths such that all the capacity constraints are maintained and each selected request with demand  $d_i$  is connected by  $k$  disjoint paths, each of flow value  $d_i/k$ .

The  $k$ -EDP and  $k$ -DFP problems have important applications in fault-tolerant (virtual) circuit switching, which plays a key role in optical networks.

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# 1 Introduction

This paper was motivated by a talk given by Rakesh Sinha from Ciena Inc. at the DIMACS Workshop on Resource Management and Scheduling in Next Generation Networks, March 26-27, 2001. The speaker pointed out in his talk that standard problems such as the edge-disjoint paths problem and the unsplittable flow problem are insufficient for practical purposes: they do not allow a rapid adaptation to edge faults or heavy load conditions. Instead of having just one path for each request, it would be much more desirable to determine a collection of alternative independent paths for each accepted request that can flexibly be used to ensure rapid adaptability. The paths, however, should be chosen so that not too much bandwidth is wasted under normal conditions. Keeping this in mind, we introduce two optimization problems which have not been studied before, the best of our knowledge: the  $k$  edge-disjoint paths problem ( $k$ -EDP) and the  $k$  disjoint flows problem ( $k$ -DFP).

In the  $k$ -EDP we are given an undirected graph  $G = (V, E)$  and a set of terminal pairs (or requests)  $T$ . The problem is to find a maximum subset of the pairs in  $T$  such that each chosen pair can be connected by  $k$  disjoint paths and, moreover, the paths for different pairs are mutually disjoint.

Similarly, in the  $k$ -DFP we are given an undirected network  $G = (V, E)$  with edge capacities and a set of terminal pairs  $T$  with demands  $d_i$ ,  $1 \leq i \leq |T|$ . The problem is to find a subset of the pairs of maximum total demand such that each chosen pair can be connected by  $k$  disjoint paths, each path is carrying  $d_i/k$  units of flow and no capacity constraint is violated.

In order to demonstrate that the  $k$ -DFP can be used to achieve fault tolerance together with a high utilization of the network resources and rapid adaptability, consider a network  $G$  in which new edge faults may occur continuously but the total number of faulty edges at the same time is at most  $f$ . In this case, given a request with demand  $d$ , the strategy is to reserve  $k + f$  disjoint flow paths for it, for some  $k \geq 1$ , with total demand  $(1 + f/k)d$ . As long as at most  $f$  edge faults appear at the same time, it will still be possible to ship a demand of  $d$  along the remaining paths. Furthermore, under fault-free conditions, only a fraction  $f/k$  of the reserved bandwidth is wasted, which can be made as small as required by setting  $k$  sufficiently large, within the constraints placed by the properties of the network.

## 1.1 Previous results

Since we are not aware of previous results for the  $k$ -EDP and the  $k$ -DFP for  $k > 1$ , we will just survey the heavily studied case of  $k = 1$ , that is, the *edge-disjoint paths problem* (EDP) and the more general *unsplittable flow problem* (UFP).

Several results are known about the approximation ratio and competitive ratio achievable for the UFP under the assumption that the maximum demand of a commodity,  $d_{\max}$ , does not exceed the minimum edge capacity,  $c_{\min}$ , often referred to as the *no-bottleneck assumption* [1, 10, 3, ?, 8, 11, 12]. If the number of edges,  $m$ , is the only parameter considered, Baveja and Srinivasan [3] present a polynomial time algorithm with an approximation ratio  $O(\sqrt{m})$ . On the lower bound side, it was shown by Guruswami et al. [8] that on directed networks the UFP is NP-hard to approximate within a factor of  $m^{1/2-\epsilon}$  for any  $\epsilon > 0$ . The best result known so far for the EDP and the UFP was given by Kolman and Scheideler [12]. Using a new parameter called the *flow number*  $F$  of a network, they show that a simple online algorithm has a competitive ratio of  $O(F)$  and prove that  $F = O(\Delta\alpha^{-1} \log n)$ , where, for the EDP,  $\Delta$  is the maximal degree of the network,  $\alpha$  is the edge expansion, and  $n$  is the number of nodes. For the UFP,  $\Delta$  has to be defined as the maximal node capacity of the network and  $\alpha$  as the expansion with respect to the the edge capacities. Combining the approach of Kolman and Scheideler [12] with the randomized rounding technique, Chakrabarti et al. [?] recently proved a randomized approximation ratio of  $O(\Delta_G \alpha_G^{-1} \log^2 n)$  for the more general UFP with profits where  $\Delta_G$  and  $\alpha_G$  stand for the maximum degree and the expansion of the given network when ignoring the

capacities.

We also consider two related problems, the *integral splittable flow problem* (ISF) [8] and the *k-splittable flow problem* (*k*-SFP). In both cases, the input and the objective (i.e., to maximize the sum of accepted demands) are the same as in the UFP. The difference is that in the ISF all demands are integral and a flow satisfying a demand can be split into several paths, each carrying an integral amount of flow. In the *k*-SFP<sup>1</sup> a demand may be split into at most *k* flow paths (of not necessarily integral values). Under the no-bottleneck assumption Guruswami et al. [8] give an  $O(\sqrt{md_{\max}} \log^2 m)$  approximation for the ISF. Kolman and Scheideler [12] techniques allow us to achieve an  $O(F)$  randomized competitive ratio and an  $O(F)$  deterministic approximation ratio for both of these problems on unit-capacity networks. Although the ISF and the *k*-SFP on one side and the *k*-DFP on the other seem very similar at first glance, there is a serious difference between the two. Whereas the ISF and the *k*-SFP are *relaxations* of the UFP (they allow the use of more than one path for a single request and the paths are *not* required to be disjoint), the *k*-DFP is actually a *more complex* version of the UFP since it requires several *disjoint* paths for a single request.

## 1.2 New results

This paper's main results are

- a deterministic online algorithm for the *k*-EDP with competitive ratio  $O(k^3 F)$ ,
- a deterministic offline algorithm for the *k*-DFP on unit-capacity networks with an approximation ratio of  $O(k^3 F \log(kF))$ ,
- a lower bound  $\Omega(k \cdot F)$  for the competitive ratio of any deterministic online algorithm for the *k*-EDP (and thus, obviously, for the *k*-DFP).

Thus, for constant *k*, we have matching upper and lower bounds for the *k*-EDP.

Furthermore, we demonstrate that disjointness of the *k* paths for every single request seems to be the crucial condition that makes these problems harder than other problems such as the ISF or the *k*-SFP.

We also show how previously known techniques can be used to transform the online algorithm for the *k*-EDP an offline algorithm with an approximation ratio  $O(k^3 F)$  for the *k*-EDP with profits, and to convert the offline algorithm for the *k*-DFP into a randomized online algorithm for the *k*-DFP with an expected competitive ratio of  $O(k^3 F \log(kF))$ .

Our algorithms for the *k*-EDP and *k*-DFP are based on a simple concept, a natural extension of the *bounded greedy algorithm* (BGA) that has already been studied in several papers [10, 11, 12]: For a given request if we can find *k* disjoint flow paths of total length at most *L*, given the connections we have already made, without violating capacity constraints, select any such system of *k* paths for this request. The core of the paper is in the analysis of this simple algorithm. The problem is to show that this strategy works even if the optimal offline algorithm connects many requests via *k* disjoint paths of total length more than *L*. In order to solve this problem we use a new technique, based on Menger's theorem and the Lovász Local Lemma, that converts large systems of *k* disjoint paths into small systems of *k* disjoint paths. Previously, shortening strategies were only known for *k* = 1 [11, 12].

## 1.3 Basic notation and techniques

Many of the previous techniques for the EDP and related problems do not allow us to prove strong upper bounds on approximation or competitive ratios due to the use of inappropriate parameters. If

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<sup>1</sup>The *k*-splittable flow problem was recently independently introduced by Baier et al. [?].

$m$  is the only parameter used, an upper bound of  $O(\sqrt{m})$  is essentially the best possible for the case of directed networks [8]. Much better ratios can be shown if the expansion or the routing number [14] of a network are used. These measures give very good bounds for low-degree networks with uniform edge capacities, but are usually very poor when applied to networks of high degree or highly nonuniform degrees or edge capacities. To get more precise bounds for the approximation and competitive ratios of algorithms, Kolman and Scheideler [12] introduced a new network measure, the *flow number*  $F$ . Not only does the flow number lead to more precise results, it also has the major advantage that, in contrast to the expansion or the routing number, it can be computed exactly in polynomial time. Hence we use the flow number in this paper as well.

Before we introduce the flow number, we need some notation. In a *concurrent multicommodity flow problem* there are  $k$  commodities, each with two terminal nodes  $s_i$  and  $t_i$  and a demand  $d_i$ . A *feasible* solution is a set of flow paths for the commodities that obey capacity constraints but need not meet the specified demands. An important difference between this problem and the unsplittable flow problem is that the commodity between  $s_i$  and  $t_i$  can be routed along multiple paths. The *(relative) flow value of a feasible solution* is the maximum  $f$  such that at least  $f \cdot d_i$  units of commodity  $i$  are simultaneously routed for each  $i$ . The *max-flow* for a concurrent multicommodity flow problem is defined as the maximum flow value over all feasible solutions. For a path  $p$  in a solution, the *flow value of  $p$*  is the amount of flow routed along it. A special class of concurrent multicommodity flow problems is the *product multicommodity flow problem* (PMFP). In a PMFP, a nonnegative weight  $\pi(u)$  is associated with each node  $u \in V$ . There is a commodity associated with every pair of nodes  $(u, v)$  whose demand is equal to  $\pi(u) \cdot \pi(v)$ .

Suppose we have a network  $G = (V, E)$  with arbitrary non-negative edge capacities. For every node  $v$ , let the *capacity* of  $v$  be defined as  $c(v) = \sum_{w: \{v,w\} \in E} c(v, w)$  and the capacity of  $G$  be defined as  $\Gamma = \sum_v c(v)$ . Given a concurrent multicommodity flow problem with feasible solution  $\mathcal{S}$ , let the *dilation*  $D(\mathcal{S})$  of  $\mathcal{S}$  be defined as the length of the longest flow path in  $\mathcal{S}$  and the *congestion*  $C(\mathcal{S})$  of  $\mathcal{S}$  be defined as the inverse of its flow value (i.e., the congestion tells us how many times the edge capacities would have to be increased in order to fully satisfy all the original demands, along the paths of  $\mathcal{S}$ ). Let  $I_0$  be the PMFP in which  $\pi(v) = c(v)/\sqrt{\Gamma}$  for every node  $v$ , that is, each pair of nodes  $(v, w)$  has a commodity with demand  $c(v) \cdot c(w)/\Gamma$ . The *flow number*  $F(G)$  of a network  $G$  is the minimum of  $\max\{C(\mathcal{S}), D(\mathcal{S})\}$  over all feasible solutions  $\mathcal{S}$  of  $I_0$ . When there is no risk of confusion, we simply write  $F$  instead of  $F(G)$ . Note that the flow number of a network is invariant to scaling of capacities.

The smaller the flow number, the better are the communication properties of the network. For example,  $F(\text{line}) = \Theta(n)$ ,  $F(\text{mesh}) = \Theta(\sqrt{n})$ ,  $F(\text{hypercube}) = \Theta(\log n)$ ,  $F(\text{butterfly}) = \Theta(\log n)$ , and,  $F(\text{expander}) = \Theta(\log n)$ .

The *Shortening lemma* [12] will be a useful tool for the analysis of our algorithms.

**Lemma 1.1 (Shortening Lemma)** *For any network with flow number  $F$  it holds: for any  $\epsilon \in (0, 1]$  and any feasible solution  $\mathcal{S}$  to an instance of the concurrent multicommodity flow problem with a flow value of  $f$ , there exists a feasible solution with flow value  $f/(1 + \epsilon)$  that uses paths of length at most  $2 \cdot F(1 + 1/\epsilon)$ . Moreover, the flow through any edge  $e$  not used by  $\mathcal{S}$  is at most  $\epsilon \cdot c(e)/(1 + \epsilon)$ .*

Another useful class of concurrent multicommodity flow problems is the *balanced multicommodity flow problem* (or short BMFP). A BMFP is a multicommodity flow problem in which the sum of the demands of the commodities originating and the commodities terminating in a node  $v$  is at most  $c(v)$  for every  $v \in V$ . We make use of the following property of the problem [12]:

**Lemma 1.2** *For any network  $G$  with flow number  $F$  and any instance  $I$  of a BMFP for  $G$ , there is a feasible solution for  $I$  with congestion and dilation at most  $2F$ .*

Apart from the flow number we also need Chernoff bounds [9], the symmetric form of the Lovász Local Lemma [7] and Menger’s theorem [5, p. 75].

**Lemma 1.3 (Chernoff Bound)** *Consider any set of  $n$  independent binary random variables  $X_1, \dots, X_n$ . Let  $X = \sum_{i=1}^n X_i$  and  $\mu$  be chosen so that  $\mu \geq \mathbb{E}[X]$ . Then it holds for all  $\delta \geq 0$  that*

$$\Pr[X \geq (1 + \delta)\mu] \leq e^{-\min[\delta^2, \delta] \cdot \mu/3} .$$

**Lemma 1.4 (Lovász Local Lemma)** *Let  $A_1, \dots, A_n$  be “bad” events in an arbitrary probability space. Suppose that each event is mutually independent of all other events but at most  $b$ , and that  $\Pr[A_i] \leq p$  for all  $i$ . if  $ep(b + 1) \leq 1$ , the probability of no bad event occurring is greater than 0.*

**Lemma 1.5 (Menger’s theorem)** *Let  $s$  and  $t$  be distinct vertices of  $G$ . The minimal number of edges separating  $s$  from  $t$  is equal to the maximal number of edge-disjoint  $s$ - $t$  paths.*

In the following, a  $k$ -system is a set of  $k$  edge-disjoint paths connecting the same pair of vertices. A  $k$ -system is *small* if it uses at most  $L$  edges, for some fixed parameter  $L$  depending on network properties. The *flow value* of a  $k$ -system is the total amount of flow routed along the  $k$  paths in it. We require the flow to be the same along all the  $k$  paths. For a set  $M$  of  $k$ -systems, let  $\|M\|$  denote the total amount of flow sent along all of them, that is, the sum of the flow values. For a path  $p$  let  $|p|$  denote the number of edges of  $p$ , that is, its *length*.

## 1.4 Organization of the paper

In Section 2 we present our upper and lower bounds for the  $k$ -EDP and some related problems, and in Section 3 we present our upper bounds for the  $k$ -DFP. The paper ends with a conclusion and open problems.

## 2 Algorithms for the $k$ -EDP

Consider the following extension of the bounded greedy algorithm: Let  $L$  be a suitably chosen parameter. Given a request, if it is possible to find a short  $k$ -system for it that is disjoint with all previously selected  $k$ -systems, then accept the request and select any such  $k$ -system for it. Otherwise, reject the request. Let us call this algorithm  $k$ -BGA.

Note that the problem of finding  $k$  edge-disjoint paths of total length at most  $L$  between the same pair of nodes, that is, the problem of finding a short  $k$ -system, can be reduced to the classical min-cost (integral) flow problem, which can be solved by standard methods in polynomial time [6, Chapter 4]. The  $k$ -BGA can therefore also be used offline as an approximation algorithm. It is worth mentioning that if there were a bound of  $L/k$  on the length of every path, the problem would not be tractable (cf. [4]).

### 2.1 The upper bound

**Theorem 2.1** *Given a network  $G$  of flow number  $F$ , the competitive ratio of the  $k$ -BGA with parameter  $L = 24k^2 F$  is  $O(k^2 F)$ .*

**Proof.** Let  $\mathcal{B}$  be the solution obtained by the  $k$ -BGA and  $\mathcal{O}$  be the optimal solution. For notational simplicity we allow a certain ambiguity. Sometimes  $\mathcal{B}$  and  $\mathcal{O}$  refer to the subsets of  $T$  of the satisfied requests, and sometimes to the actual  $k$ -systems that realize the satisfied requests. We say that a

$k$ -system  $q \in \mathcal{B}$  is a *witness* for a  $k$ -system  $p$  if  $p$  and  $q$  share an edge. Obviously, a request with a small  $k$ -system in the optimal solution that was rejected by the  $k$ -BGA must have a witness in  $\mathcal{B}$ .

Let  $\mathcal{O}' \subseteq \mathcal{O}$  denote the set of all  $k$ -systems in  $\mathcal{O}$  that are larger than  $L$  and that correspond to requests *not* accepted by the  $k$ -BGA and that do *not* have a witness in  $\mathcal{B}$ . Then each  $k$ -system in  $\mathcal{O} - \mathcal{O}'$  either has a witness or was accepted by the  $k$ -BGA. Since the  $k$ -systems in  $\mathcal{O} - \mathcal{O}'$  are edge-disjoint, each request accepted by the  $k$ -BGA can be a witness to at most  $L$  requests in  $\mathcal{O} - \mathcal{O}'$ . Hence,  $|\mathcal{O} - \mathcal{O}'| \leq (1 + L)|\mathcal{B}|$ .

It remains to prove an upper bound on  $|\mathcal{O}'|$ . To achieve this, we transform the  $k$ -systems in  $\mathcal{O}'$  into a set  $\mathcal{P}$  of possibly overlapping but *small*  $k$ -systems. Since these small  $k$ -systems would have been candidates for the  $k$ -BGA but were not picked, each of them has at least one witness in  $\mathcal{B}$ . Then we show that the small  $k$ -systems in  $\mathcal{P}$  do not overlap much and thus many  $k$ -systems from  $\mathcal{B}$  are needed in order to provide a witness for every  $k$ -system in  $\mathcal{P}$ .

Note that the set  $\mathcal{O}'$  of  $k$ -systems can be viewed as a feasible solution of relative flow value 1 to the set of requests  $\mathcal{O}'$  of the concurrent multicommodity flow problem where each request has demand  $k$ . The Shortening lemma with parameter  $\epsilon = 1/(2k)$  immediately implies the following fact.

**Fact 2.2** *The  $k$ -systems in  $\mathcal{O}'$  can be transformed into a set  $\mathcal{R}$  of flow systems transporting the same amount of flow such that every flow path has a length of at most  $5k \cdot F$  (and at most  $2F$  edges of each of them were not used in  $\mathcal{O}'$ ). Furthermore,  $\mathcal{R}$  has the property that the congestion at every edge that is used by some  $k$ -system in  $\mathcal{O}'$  is at most  $1 + 1/(2k)$ , and the congestion at every other edge is at most  $1/(2k)$ .*

This does not immediately provide us with short  $k$ -systems for the requests in  $\mathcal{O}'$ . However, it is possible to extract short  $k$ -systems from the flow system  $\mathcal{R}$ .

**Lemma 2.3** *For every request in  $\mathcal{O}'$ , a set of small  $k$ -systems can be extracted out of its flow system in  $\mathcal{R}$  with a total flow value of at least  $1/4$ .*

**Proof.** Let  $(s_i, t_i)$  be a fixed request from  $\mathcal{O}'$  and let  $E_i$  be the set of all edges that are traversed by the flow system for  $(s_i, t_i)$  in  $\mathcal{R}$ . Consider any set of  $k - 1$  edges in  $E_i$ . Since the edge congestion caused by  $\mathcal{R}$  is at most  $1 + 1/(2k)$ , the total amount of flow in the flow system for  $(s_i, t_i)$  in  $\mathcal{R}$  that traverses the  $k - 1$  edges is at most  $(k - 1)(1 + 1/(2k)) < k - 1/2$ . Thus, the minimal  $s_i - t_i$ -cut in the graph  $(V, E_i)$  consists of at least  $k$  edges. Hence, Menger's theorem [5] implies that there are  $k$  edge-disjoint paths between  $s_i$  and  $t_i$  in  $E_i$ . We take any such  $k$  paths and denote them as the  $k$ -system  $\sigma_1$ . We associate a *weight* (i.e., total flow) of  $k \cdot \epsilon_1$  with  $\sigma_1$ , where  $\epsilon_1$  is the minimum flow from  $s_i$  to  $t_i$  through an edge in  $E_i$  belonging to the  $k$ -system  $\sigma_1$ .

Assume now that we have already found  $\ell$   $k$ -systems  $\sigma_1, \sigma_2, \dots, \sigma_\ell$  for some  $\ell \geq 1$ .

If  $\sum_{j=1}^{\ell} k \cdot \epsilon_j = \frac{1}{2}$  **we stop the process of defining  $\sigma_j$** . Otherwise, the minimal  $s_i - t_i$ -cut in  $(V, E_i)$  must still be at least  $k$ , because the total flow along any  $k - 1$  edges in  $E_i$  is still less than the total remaining flow from  $s_i$  to  $t_i$ . Thus, we can apply Menger's theorem again. This allows us to find another  $k$ -system  $\sigma_{\ell+1}$  between  $s_i$  and  $t_i$  and in the same way as above we associate with it a weight  $\epsilon_{\ell+1}$ . Let  $\hat{\ell}$  be the number of  $k$ -systems at the end of the process.

So far there is no guarantee that any of the  $k$ -systems defined above will be small, neither that they will transport enough flow between the terminal pair  $s_i$  and  $t_i$ . However, after a simple procedure they will satisfy our needs.

**The  $s_i - t_i$  flow system in  $\mathcal{R}$ , corresponding to the original  $k$ -system in  $\mathcal{O}'$ , has two parts: flow along edges in the original  $k$ -system, and flow along the shortcuts. Concerning the first part, there are at most  $8k^2F$  such edges (at most  $8kF$  per each of the  $k$  paths).**

Concerning the other part, since each shortcut has length at most  $2F$  and the total flow through all of them is  $k$ , its *volume* is upper bounded by  $2kF$ .

If there were  $k$ -systems in  $\sigma_1, \dots, \sigma_{\hat{\ell}}$  of total weight at least  $1/4$  that use more than  $16k^2F$  edges each, then they would not fit into the available volume: they would need strictly more than  $8k^2F \frac{1}{4k} = 2kF$  volume of the shortcuts. Thus, there exists a subset of the  $k$ -systems  $\sigma_1, \dots, \sigma_{\hat{\ell}}$  with total weight at least  $1/4$  such that each of them is small, that is, each of them uses at most  $16k^2F$  edges.  $\square$

We are ready to bound  $|\mathcal{O}'|$ , the number of  $k$ -systems in  $\mathcal{O}'$ , in terms of  $|\mathcal{B}|$ . Let  $\mathcal{S}_i$  denote the set of small  $k$ -systems for request  $(s_i, t_i) \in \mathcal{O}'$ , given by Lemma 2.3, and let  $\mathcal{S}$  be the set of all  $\mathcal{S}_i$ . By the definition of  $\mathcal{S}$ ,

$$\|\mathcal{O}'\| \leq 4k \cdot \|\mathcal{S}\|. \quad (1)$$

Since the  $k$ -systems in  $\mathcal{S}$  connect requests from  $\mathcal{O}'$  and they are short, each of them must have a witness in  $\mathcal{B}$ . Let  $E_{\mathcal{S}}$  denote the set of all edges on which a  $k$ -system from  $\mathcal{S}$  has a witness. According to the definition of  $\mathcal{O}'$ , no edge in  $E_{\mathcal{S}}$  can be part of a  $k$ -system in  $\mathcal{O}'$ . It follows from Fact 2.2 that  $\mathcal{S}$  has a congestion of at most  $1/(2k)$  on any one of the edges in  $E_{\mathcal{S}}$ . Thus, it holds for the total flow along  $k$ -systems in  $\mathcal{S}$  that

$$\|\mathcal{S}\| \leq k \cdot \left( \frac{1}{2k} \cdot |E_{\mathcal{S}}| \right). \quad (2)$$

Let  $E_{\mathcal{B}}$  be the set of all edges used by  $\mathcal{B}$ . Then

$$|E_{\mathcal{S}}| \leq |E_{\mathcal{B}}| \leq L \cdot |\mathcal{B}|. \quad (3)$$

Since  $|\mathcal{O}'| = \frac{1}{k} \cdot \|\mathcal{O}'\|$ , combining inequalities (1) to (3) gives  $|\mathcal{O}'| \leq 2L \cdot |\mathcal{B}|$  and completes the proof.  $\square$

The above upper bound on the competitive ratio for the  $k$ -BGA with parameter  $L = 20k^3F$  is the best possible, since a  $k$ -system of size  $\Theta(k^3F)$  may prevent  $\Theta(k^3F)$  other  $k$ -systems from being selected. An open question is whether it is possible to achieve a better competitive ratio with a stronger restriction on the size of the  $k$ -systems that are used by the  $k$ -BGA.

## 2.2 General online lower bound

We show there is a lower bound on the competitive ratio of any deterministic online algorithm for the  $k$ -EDP problem which is not far away from the performance of the  $k$ -BGA.

**Theorem 2.4** *For any  $n, k$ , and  $F \geq \log_k n$  with  $n \geq k^2 \cdot F$  there is a graph  $G$  of size  $\Theta(n)$  with maximum degree  $O(k)$  and flow number  $\Theta(F)$  such that the competitive ratio of any deterministic online algorithm on  $G$  is  $\Omega(k \cdot F)$ .*

**Proof.** A basic building block of our construction is the following simple graph. Let  $D_k$  (*diamond*) denote the graph consisting of two bipartite graphs  $K_{1,k}$  and  $K_{k,1}$  glued naturally together at the larger sides. The two  $k$ -degree nodes in  $D_k$  are its *endpoints*. Let  $C$  (*chaplet*) denote the graph consisting of  $F$  diamond graphs attached one to the other at the endpoints, like in an open chaplet.

The core of the graph  $G$  consists of  $m = n/(k \cdot F) \geq k$  disjoint copies of the chaplet graph  $C$  attached to the inputs of a  $k$ -ary multibutterfly (Figure 1). In addition, a node  $s$  is connected to the first  $k$  chaplet graphs and a node  $t$  is connected to the first  $k$  output nodes of the multibutterfly. Let  $s_{i,j}$  denote the first endpoint of a diamond  $j$  in a chaplet  $i$ , and let  $t_{i,j} (= s_{i,j+1})$  denote the other endpoint.

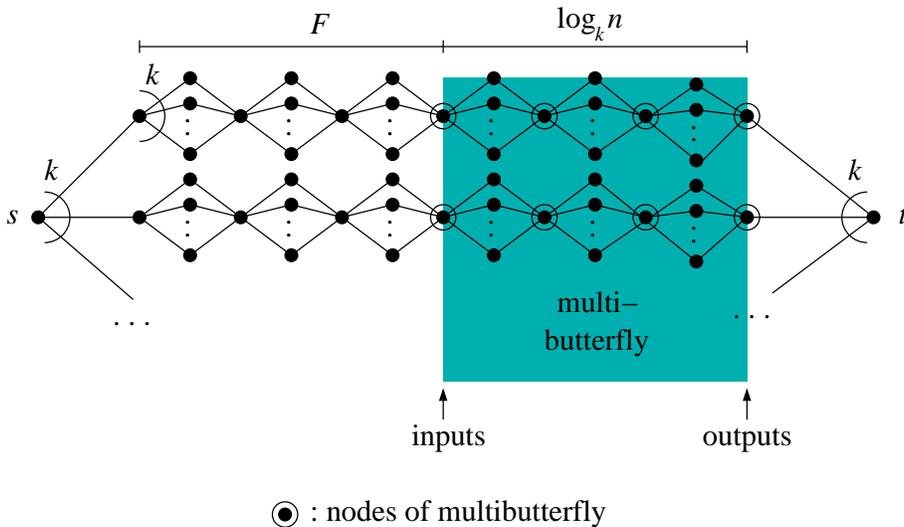


Figure 1: The graph for the lower bound.

We use the fact that a  $k$ -ary multibutterfly with  $n'$  inputs and outputs (which is a network of degree  $O(k)$ ) can route any  $r$ -relation from the inputs to the outputs with edge congestion and dilation at most  $O(\max[r/k, \log_k n'])$  [14].

First, we show that our graph  $G$  has a flow number of  $\Theta(F)$ . Since the diameter of  $G$  is  $\Omega(F)$  it is sufficient to prove that a PMFP with  $\pi(u) = c(u)/\Gamma$  for the given graph can be solved with congestion and dilation  $O(F)$ . Consider each node  $v$  of degree  $\delta_v$  to consist of  $\delta_v$  copies of itself and let  $V'$  be the set of all of these copies. Then the PMFP reduces to the problem of sending a packet of size  $1/N$  for any pair of nodes in  $V'$ , where  $N = |V'|$ . Such a routing problem can be split into  $N$  permutations  $\sigma_i$  with  $\sigma_i(v) = (v + i) \bmod N$  for all  $i \in \{0, \dots, N - 1\}$  and  $v \in V'$ . Each such permutation represents a routing problem  $\rho$  in the original network where each node is the starting point and endpoint of a number of packets that is equal to its degree. We want to bound the congestion and dilation for routing such a problem.

In order to route  $\rho$ , we first move all packets to the inputs of the  $k$ -ary multibutterfly in such a way that every input node of the multibutterfly will have  $O(kF)$  packets. This can clearly be done with edge congestion  $O(F)$  and dilation  $O(F)$ . Next, we use the multibutterfly to send the packets to the rows of their destinations. Since every input has  $O(k \cdot F)$  packets, this can also be done with congestion and dilation  $O(F)$ . Finally, all packets are sent to their correct destinations. This too causes a congestion and dilation of at most  $O(F)$ . Hence, routing  $\rho$  only requires a total congestion and dilation of  $O(F)$ .

Combining the fact that all packets are of size  $1/N$  with the fact that we have  $N$  permutations  $\sigma_i$ , it follows that the congestion and dilation of routing the PMFP in the given graph is  $O(F)$ . Hence, its flow number is  $\Theta(F)$ .

Now consider the following two sequences of requests:

- (1)  $(s, t)$ , and
- (2)  $(s, t), (s_{1,1}, t_{1,1}), (s_{1,2}, t_{1,2}), \dots, (s_{1,F}, t_{1,F}), (s_{2,1}, t_{2,1}), \dots, (s_{k,F}, t_{k,F})$

Obviously, every deterministic online algorithm has to accept  $(s, t)$  to ensure a finite competitive ratio for the sequence (1). However, in this case none of the other requests in (2) can be satisfied. But the

optimal solution for (2) is to reject  $(s, t)$  and to accept all other requests. Hence, the competitive ratio of any deterministic online algorithm is  $\Omega(k \cdot F)$ .  $\square$

### 2.3 Managing requests with profits

In the *k edge-disjoint paths with profits problem (k-EDPP)* we are given an undirected graph  $G = (V, E)$  and a set of requests  $T$ . Each request  $r_i = (s_i, t_i)$  has a positive profit  $b(r_i)$ . The problem is to find a subset  $S$  of the pairs in  $T$  of maximum profit for which it is possible to select disjoint paths such that each pair is connected by  $k$  disjoint paths.

It turns out that a simple offline variant of the  $k$ -BGA gives the same approximation ratio for the  $k$ -EDPP as we have for the  $k$ -EDP. The algorithm involves sorting the requests in decreasing order of their profits and running the  $k$ -BGA on this sorted sequence. We call this algorithm the *sorted k-BGA*.

**Theorem 2.5** *Given a network  $G$  of flow number  $F$ , the approximation ratio of the sorted  $k$ -BGA with parameter  $L = 20k^3F$  is  $O(k^3F)$  for the  $k$ -EDPP.*

**Proof.** The proof is almost identical to the proof of Theorem 2.1. The only additional observation is that, since the sorted  $k$ -BGA proceeds through the requests from the most profitable, every small  $k$ -system in  $\mathcal{O} - \mathcal{O}'$  and in the modified set  $\mathcal{P}$  has a witness in  $\mathcal{B}$  with larger or equal profit.  $\square$

### 2.4 The multi-EDP

Another variant of the  $k$ -EDP our techniques can be applied to is the *multiple edge-disjoint paths problem (multi-EDP)* which is defined as follows: given a graph  $G$  and a set of terminal pairs with integral demands  $d_i$ ,  $1 \leq d_i \leq \Delta$ , find a maximum subset of the pairs for which it is possible to select disjoint paths so that every selected pair  $i$  has  $d_i$  disjoint paths. Let  $d_{\max}$  denote the maximal demand over all requests.

A variant of the  $k$ -BGA, the *multi-BGA*, can be used here as well: Given a request with demand  $d_i$ , reject it if it is not possible to find  $d_i$  edge-disjoint paths between the terminal pairs of total length at most  $20d_i d_{\max}^2 F$ . Otherwise, select any such  $d_i$  paths for it.

**Theorem 2.6** *Given a network  $G$  of flow number  $F$ , the competitive ratio of the multi-BGA is  $O(d_{\max}^3 F)$ .*

**Proof.** The proof goes along the same lines as the proof of Theorem 2.1: first, the Shortening lemma with parameter  $\epsilon = 1/(2d_{\max})$  is applied and, afterwards, the extraction procedure is used. The difference is that now we extract only  $d_i$ -systems for a request with demand  $d_i$ , not  $d_{\max}$ -systems.  $\square$

## 3 Algorithms for the $k$ -DFP

We now turn to capacitated networks and consider requests with arbitrary demands. Throughout this section we will assume that the maximal demand is at most  $k$  times larger than the minimal edge capacity, which is analogous to assumptions made in almost all papers about the UFP. We call this the *weak bottleneck assumption*. Moreover, we assume that all edge capacities are the same. Since  $F$  is invariant to scaling, we simply set all edge capacities to one. The minimal demand of a request will be denoted by  $d_{\min}$ . We first give an offline algorithm for the  $k$ -DFP and prove that it has a good approximation ratio, and then mention how to convert it into a competitive online algorithm.

To solve the offline  $k$ -DFP, we first sort the requests in decreasing order of their demands. On this sorted sequence of requests we use an algorithm that is very similar to the  $k$ -BGA: Let  $L$  be a

suitably chosen parameter. Given a request with a demand of  $d$ , accept it if it is possible to find for it a short  $k$ -system with flow value  $d$  that fits into the network without violating the capacity constraints. Otherwise, reject it. This extension of the  $k$ -BGA will be called  $k$ -flow BGA.

The next theorem demonstrates that the performance of the  $k$ -flow BGA for the  $k$ -DFP is comparable to the performance of the  $k$ -BGA for the  $k$ -EDP. It is slightly worse due to a technical reason: it is much harder to use our technique for extracting short  $k$ -systems for the  $k$ -DFP than for the  $k$ -EDP.

**Theorem 3.1** *Given a unit-capacity network  $G$  with flow number  $F$ , the approximation ratio of the  $k$ -flow BGA for the  $k$ -DFP with parameter  $L = \gamma \cdot k^3 F \log(kF)$  for an appropriately large constant  $\gamma$ , when run on requests sorted in non-increasing order, is  $O(k^3 F \log(kF))$ .*

**Proof.** As usual, let  $\mathcal{B}$  denote the set of  $k$ -systems for the requests accepted by the BGA and  $\mathcal{O}$  be the set of  $k$ -systems in the optimal solution. Each  $k$ -system consists of  $k$  disjoint flow paths which we call *streams*. For notational simplicity we will sometimes think about  $\mathcal{B}$  and  $\mathcal{O}$  as a set of streams (instead of  $k$ -systems).

For each stream  $q \in \mathcal{B}$  or  $q \in \mathcal{O}$ , let  $f(q)$  denote the flow along that stream. If  $q$  belongs to the request  $(s_i, t_i)$  with demand  $d_i$ , then  $f(q) = d_i/k$ . For a set  $\mathcal{Q}$  of streams let  $\|\mathcal{Q}\| = \sum_{q \in \mathcal{Q}} f(q)$ . Also, for an edge  $e \in E$  and a stream  $q$ , let  $F(e, q)$  denote the sum of flow values of all streams in  $\mathcal{B}$  passing through  $e$  whose flow is at least as large as the flow of  $q$ , that is,  $F(e, q) = \|\{p \in \mathcal{B}, e \in p, f(p) \geq f(q)\}\|$ . A stream  $p \in \mathcal{B}$  is a *witness* for a stream  $q$  if  $f(p) \geq f(q)$  and  $p$  and  $q$  intersect in an edge  $e$  with  $F(e, q) + f(q) > 1$ . For each edge  $e$  let  $\mathcal{W}(e, \mathcal{B})$  denote the set of streams in  $\mathcal{B}$  that serve as witnesses on  $e$ . Similarly, for each edge  $e$  let  $\mathcal{V}(e, \mathcal{Q})$  denote the set of streams in  $\mathcal{Q}$  that have witnesses on  $e$ . We also say that a  $k$ -system has a witness on an edge  $e$  if any of its  $k$  streams has a witness on  $e$ . We start with a simple observation.

**Claim 3.2** *For any stream  $q \in \mathcal{O}$  and edge  $e$ , if  $q$  has a witness on  $e$  then  $\|\mathcal{W}(e, \mathcal{B})\| \geq 1/2$ .*

**Proof.** Let  $p$  be a witness of  $q$  on  $e$ . Assume, by contradiction, that  $F(e, q) < 1/2$ . It easily follows that  $f(p) < 1/2$ . Since  $f(q) \leq f(p)$  and  $F(e, q) + f(q) > 1$  by the definition of a witness, we have a contradiction.  $\square$

Let  $\mathcal{O}' \subset \mathcal{O}$  be the set of  $k$ -systems that are larger than  $L$  and that correspond to requests *not* accepted by the  $k$ -flow BGA and that do *not* have a witness in  $\mathcal{B}$ . The next two bounds on  $\|\mathcal{O} \setminus \mathcal{O}'\|$  and  $\|\mathcal{O}'\|$  complete the proof.

**Lemma 3.3**  $\|\mathcal{O} \setminus \mathcal{O}'\| \leq (1 + 2L) \cdot \|\mathcal{B}\|$ .

**Proof.** We partition  $\mathcal{O} \setminus \mathcal{O}'$  into two sets. Let  $\mathcal{O}_1 \subseteq \mathcal{O} \setminus \mathcal{O}'$  consist of all the  $k$ -systems corresponding to requests accepted by the BGA and let  $\mathcal{O}_2 = (\mathcal{O} \setminus \mathcal{O}') \setminus \mathcal{O}_1$ . Obviously,  $\|\mathcal{O}_1\| \leq \|\mathcal{B}\|$ . Note that each  $k$ -system in  $\mathcal{O}_2$  must have a witness in  $\mathcal{B}$ . Let  $E' \subseteq E$  denote the set of all edges on which some  $k$ -system from  $\mathcal{O}_2$  has a witness. We then have

$$\|\mathcal{O}_2\| \leq \sum_{e \in E'} k \cdot \|\mathcal{V}(e, \mathcal{O}_2)\| \leq \sum_{e \in E'} k \leq \sum_{e \in E'} k \cdot 2 \|\mathcal{W}(e, \mathcal{B})\|$$

The first inequality follows from the definition of  $\mathcal{V}(e, \mathcal{Q})$  and the above observation that each  $q \in \mathcal{O}_2$  has a witness in  $\mathcal{B}$ . The second inequality holds due to the unit capacities and the last one follows from Claim 3.2.

Since all  $k$ -systems in  $\mathcal{B}$  are of length at most  $L$ , we have

$$\begin{aligned} \sum_{e \in E'} \|\mathcal{W}(e, \mathcal{B})\| &\leq \sum_{\text{streams } p \in \mathcal{B}} |p| \cdot f(p) \\ &\leq \sum_{k\text{-systems } s \in \mathcal{B}} L \cdot d(s)/k \leq L \cdot \|\mathcal{B}\|/k. \end{aligned}$$

This completes the proof of Lemma 3.3.  $\square$

In the next lemma we bound  $\|\mathcal{O}'\|$  by first transforming the large  $k$ -systems in  $\mathcal{O}'$  into a set  $\mathcal{S}$  of small  $k$ -systems and then bounding  $\|\mathcal{S}\|$  in terms of  $\|\mathcal{B}\|$ .

**Lemma 3.4**  $\|\mathcal{O}'\| = O(L \cdot \|\mathcal{B}\|)$ .

**Proof.** In order to prove the lemma, we will transform the  $k$ -systems in  $\mathcal{O}'$  into a set of  $k$ -systems  $\mathcal{S}$  in which each  $k$ -system has a length at most  $L$  and therefore must have a witness in  $\mathcal{B}$ . To achieve this, we perform a sequence of transformations:

1. First, we scale the demands and edge capacities so that each edge in  $G$  has a capacity of  $C = \lceil 3k/d_{min} \rceil$  and all requests have demands that are integral multiples of  $k$ . More precisely, the demand of each request of original demand  $d$  is set to  $d' = k \cdot \lceil C \cdot d/k \rceil$ . Since  $d'/C \in [d, (1+1/3)d]$ , this slightly increases the demands and therefore it also increases the flows along the streams so that the total flow along an edge is now at most  $(1+1/3)C$ . Note that slightly increasing the demands only increases  $\|\mathcal{O}'\|$  and therefore only makes the bound on the relationship between  $\|\mathcal{O}'\|$  and  $\|\mathcal{B}\|$  more pessimistic.
2. Next, we replace each request  $(s_i, t_i)$  in  $\mathcal{O}'$  by  $d'_i/k$  elementary requests of demand  $k$  each, shipped along the same  $k$ -system as for  $(s_i, t_i)$ . For every  $k$ -system of such a request, we only keep the first  $8c \cdot kF$  and the last  $8c \cdot kF$  nodes along each of its  $k$  streams, for some  $c = O(\log(kF))$ . The resulting set of (possibly disconnected) streams of a  $k$ -system will be called a  $k$ -core. As shown in Claim 3.5, it is possible to distribute the elementary requests into  $C/c$  sets  $S_1, \dots, S_{C/c}$  so that the congestion caused by the  $k$ -cores within each set is at most  $2c$  at each edge.
3. Afterwards, we consider each  $S_i$  separately. We will reconnect disconnected streams in each  $k$ -core in  $S_i$  with flow systems derived from the flow number. The reconnected  $k$ -cores will not yet consists of  $k$  disjoint streams. We will show in Claim 3.6 how to extract  $k$ -systems of length at most  $L$  from each reconnected  $k$ -core.
4. Once we have found the short  $k$ -systems, we will be able to compare  $\|\mathcal{O}'\|$  with  $\|\mathcal{B}\|$  with the help of witnesses.

Next we present two vital claims. The proof of the first claim requires the use of the Lovász Local Lemma, and the proof of the second claim is similar to the proof of Theorem 2.1.

**Claim 3.5** *The elementary requests can be distributed into  $C/c$  sets  $S_1, \dots, S_{C/c}$  for some  $c = O(\log(kF))$  so that for each set  $S_i$  the edge congestion caused by its  $k$ -cores is at most  $2c$ .*

**Proof.** We first prove the claim for  $c = O(\log(kCF))$  and then demonstrate how to get to  $c = O(\log(kF))$ .

Consider the random experiment of assigning a number  $i \in \{1, \dots, C/c\}$  to each elementary request uniformly and independently at random, and let  $S_i$  be the set of all requests that got number  $i$ . For

every edge  $e$  let the random variable  $X_{e,i}$  denote the number of streams assigned to  $S_i$  that traverse  $e$ . Since the maximal edge congestion is at most  $4C/3$ , we have  $\mathbb{E}[X_{e,i}] \leq 4c/3$  for every edge  $e$ . Every edge  $e$  can be used by at most one stream of any  $k$ -core. Hence, a  $k$ -core can contribute a value of at most 1 to  $X_{e,i}$  and the contributions of different  $k$ -cores are independent. We can use Chernoff bounds to derive

$$\Pr[X_{e,i} \geq (1 + 1/3) \cdot 4c/3] \leq e^{-(1/3)^2 \cdot (4c/3)/3} = e^{-4c/3^4}.$$

For every edge  $e$  and every  $i \in \{1, \dots, C/c\}$  let  $A_{e,i}$  be the event that  $X_{e,i} > 2c$ . Since  $(4/3)^2 \leq 2$ , the above probability estimate bounds the probability that the event  $A_{e,i}$  appears. Our aim is to show, with the help of the LLL, that it is possible in the random experiment to assign numbers to the requests so that none of these events appears, which would yield our claim. To apply the LLL we have to bound the dependencies among the events  $A_{e,i}$ .

Each edge  $e$  can be used by at most  $4C/3 < 2C$   $k$ -cores and these are the only  $k$ -cores that affect the values  $X_{e,i}$ ,  $i \in \{1, \dots, C/c\}$ . Realizing that each of the  $k$ -cores contains at most  $2k(8c \cdot kF)$  edges and that the  $k$ -cores choose their sets  $S_i$  independently at random, we conclude that the event  $A_{e,i}$  depends on at most  $32ck^2CF$  other events  $A_{f,j}$ .

To be able to use the LLL, we only have to choose the value  $c$  so that

$$e \cdot e^{-4c/3^4} (32ck^2CF + 1) \leq 1.$$

This can certainly be achieved by setting  $c = \Theta(\ln(kCF))$  large enough.

The above procedure is sufficient for proving the lemma only if  $C = (kF)^{O(1)}$ . If  $C = (kF)^{\Omega(1)}$  a more involved technique will be used. The  $k$ -cores will be distributed into the sets  $S_i$  not in a single step but in a sequence of refinements (a similar approach was used, e.g., by Leighton et al. [13] and Scheideler [14]). In the first refinement, our aim is to show that for  $c_1 = O(\ln^3 C)$  the  $k$ -cores can be distributed into the sets  $S_1, \dots, S_{C/c_1}$  so that the edge congestion in each  $S_i$  is at most  $(1 + O(1/\ln C))4c_1/3$ . For this we use the same random experiment as for  $c$  above. It follows that  $\mathbb{E}[X_{e,i}] = 4c_1/3$  and that

$$\begin{aligned} \Pr[X_{e,i} \geq (1 + 1/\sqrt[3]{c_1}) \cdot 4c_1/3] &\leq e^{-(1/\sqrt[3]{c_1})^2 \cdot (4c_1/3)/3} \\ &= e^{-4\sqrt[3]{c_1}/9}. \end{aligned}$$

Hence, to be able to use the LLL, we have to choose the value  $c_1$  so that

$$e \cdot e^{-4\sqrt[3]{c_1}/9} (32c_1k^2CF + 1) \leq 1.$$

This can certainly be achieved by setting  $c_1 = \Theta(\ln^3 C)$  large enough, which completes the first refinement step.

In the second refinement step, each  $S_i$  is refined separately. Consider some fixed  $S_i$ . Our aim is to show that for  $c_2 = O(\ln^3 c_1)$  the  $k$ -cores in  $S_i$  can be distributed into the sets  $S_{i,1}, \dots, S_{i,c_1/c_2}$  so that the edge congestion in each  $S_{i,j}$  is at most  $(1 + 1/\sqrt[3]{c_2})(1 + 1/\sqrt[3]{c_1})4c_2/3$ . The proof for this follows exactly the same lines as for  $c_1$ . Thus, overall  $C/c_2$  sets  $S_{i,j}$  are produced in the second step, with the corresponding congestion bound.

In general, in the  $(\ell+1)$ st refinement step, each set  $S$  established in refinement  $\ell$  is refined separately, using  $c_{\ell+1} = O(\ln^3 c_\ell)$ , until  $c_{\ell+1} = O(\ln(kF))$  for the first time. Note that in this case,  $c_\ell = \omega(\ln(kF))$  and  $c_\ell = (kF)^{O(1)}$ . At this point we use the method presented at the beginning of the proof for the parameter  $c$  to obtain  $C/c'$  sets  $S_1, \dots, S_{C/c'}$  for some  $c' = O(\ln(kF))$  with a congestion of at most

$$\left( \prod_{j=1}^{\ell} (1 + 1/\sqrt[3]{c_j}) \right) \cdot (4/3)^2 \cdot c'$$

where  $l$  is the total number of refinement steps. Using the facts that  $1 + x \leq e^x$  for all  $x \geq 0$  and that  $e^x \leq 1 + 2x$  for all  $0 \leq x \leq 1/2$ , it holds for the product that

$$\prod_{j=1}^{\ell} (1 + 1/\sqrt[3]{c_j}) \leq e^{\sum_{j=0}^{\ell} 1/\sqrt[3]{c_j}} \leq e^{\epsilon} \leq 1 + 2\epsilon$$

for a constant  $0 < \epsilon \leq 1/2$  that can be made arbitrarily small by making sure that  $c_\ell$  is above a certain constant value depending on  $\epsilon$ . Hence, it is possible to select the values  $c_1, \dots, c_\ell, c'$  so that the congestion in each  $S_i$  at the end is at most  $2c'$ .  $\square$

**Claim 3.6** *For every set  $S_i$ , every elementary request in  $S_i$  can be given  $k$ -systems of total flow value at least  $1/4$  such that each of them consists of at most  $L$  edges. Furthermore, the congestion of every edge used by an original  $k$ -system in  $S_i$  is at most  $2c + 1/(2k)$ , and the congestion of every other edge is at most  $1/(2k)$ .*

**Proof.** For an elementary request  $r$  let  $p_1^r, \dots, p_{\ell_r}^r$  be all the disconnected streams in its  $k$ -core,  $1 \leq \ell_r \leq k$ . Let the first  $8c \cdot kF$  nodes in  $p_i^r$  be denoted by  $a_{i,1}^r, \dots, a_{i,8c \cdot kF}^r$  and the last  $8c \cdot kF$  nodes in  $p_i^r$  be denoted by  $b_{i,1}^r, \dots, b_{i,8c \cdot kF}^r$ . Consider the set of pairs

$$\mathcal{L} = \bigcup_{r \in S_1} \bigcup_{i=1}^{\ell_r} \bigcup_{j=1}^{8c \cdot kF} \{(a_{i,j}^r, b_{i,j}^r)\}.$$

Due to the congestion bound in Claim 3.5, a node  $v$  of degree  $\delta$  can be a starting point or endpoint of at most  $2c\delta$  pairs in  $\mathcal{L}$ . From Lemma 1.2 we know that for any network  $G$  with flow number  $F$  and any instance  $I$  of the BMFP on  $G$  there is a feasible solution for  $I$  with congestion and dilation at most  $2F$ . Hence, it is possible to connect all of the pairs in  $\mathcal{L}$  by flow systems of length at most  $2F$  and flow value  $f(p_i^r)$  so that the edge congestion is at most  $2c \cdot 2F$ . Let the flow system between  $a_{i,j}^r$  and  $b_{i,j}^r$  be denoted by  $f_{i,j}^r$ . For each elementary request  $r = (s, t)$  and each  $1 \leq i \leq \ell_r$  and each  $1 \leq j \leq 8c \cdot kF$ , we define a flow system  $g_{i,j}^r$ : first, it moves from  $s$  to  $a_{i,j}^r$  along  $p_i^r$ , then from  $a_{i,j}^r$  to  $b_{i,j}^r$  along  $f_{i,j}^r$ , and finally from  $b_{i,j}^r$  to  $t$  along  $p_i^r$ , and we assign to it a flow value of  $f(p_i^r)/(8c \cdot kF)$ . This ensures that a total flow of  $f(p_i^r)$  is still being shipped for each  $p_i^r$ . Furthermore, this allows us to reduce the flow along  $f_{i,j}^r$  by a factor of  $1/(8c \cdot kF)$ . Hence, the edge congestion caused by the  $f_{i,j}^r$  for all  $r, i, j$  reduces to at most  $4c \cdot F/(8c \cdot kF) = 1/(2k)$ . Therefore, the additional congestion at any edge is at most  $1/(2k)$ , which proves the congestion bounds in the claim.

Now consider any given elementary request  $r = (s, t)$ . For any set of  $k - 1$  edges, the congestion caused by the flow systems for  $r$  is at most  $(k - 1)(1 + 1/(2k)) \leq k - 1/2$ . Hence, according to Menger's theorem there are  $k$  edge-disjoint flows in the system from  $s$  to  $t$ . Continuing with the same arguments as in Theorem 2.1, we obtain a set of  $k$ -systems for  $r$  with as properties stated in the claim.  $\square$

Now that we have short  $k$ -systems for every elementary request, we combine them back into the original requests. For a request with demand  $d$  this results in a set of  $k$ -systems of size at most  $L$  each and total flow value at least  $d/(4k)$  (Claim 3.6). Let the set of all these  $k$ -systems for all requests be denoted by  $\mathcal{S}$ . Since every  $k$ -system has a size at most  $L$ , it could have been a candidate for the BGA. Thus, each of these  $k$ -systems must have a witness. Crucially, every edge that has witnesses for these  $k$ -systems must be an edge that is not used by *any* of the original  $k$ -systems in  $\mathcal{O}'$ . (This follows directly from the definition of  $\mathcal{O}'$ .) According to Claim 3.6, the amount of flow from  $\mathcal{S}$  traversing any of these edges is at most  $1/(2k)$ . Let  $E'$  be the set of all witness edges.

For each request we now choose one of its  $k$ -systems independently at random, with probability proportional to the flow values of the  $k$ -systems. This will result in a set of  $k$ -systems  $\mathcal{P}$  in which each

request has exactly one  $k$ -system and in which the expected amount of flow traversing any edge in  $E'$  is at most  $1/(2k)$ . Next, we assign the original demand of the request to each of these  $k$ -systems. This causes the expected amount of flow that traverses any edge in  $E'$  to increase from at most  $1/(2k)$  to at most  $4k \cdot 1/(2k) = 2$ .

We are now ready to bound  $\|\mathcal{P}\|$  in terms of  $\|\mathcal{B}\|$ . For every  $k$ -system  $h \in \mathcal{S}$ , let the indicator variable  $X_h$  take the value 1 if and only if  $h$  is chosen to be in  $\mathcal{P}$ . We shall look upon  $\|\mathcal{P}\|$  as a random variable (though it always has the same value) and bound its value by bounding its expected value  $E[\|\mathcal{P}\|]$ . In the following we assume that  $f(h)$  is the flow along a stream of the  $k$ -system  $h$  and  $d(h)$  is the demand of the request corresponding to  $h$ . Also, recall that the total flow value of  $k$ -systems in  $\mathcal{S}$  belonging to a request with demand  $d$  is at least  $d/(4k)$ .

$$\begin{aligned}
E[\|\mathcal{P}\|] &\leq E\left[\sum_{e \in E'} k \cdot \|\mathcal{V}(e, \mathcal{P})\|\right] \\
&\leq \sum_{e \in E'} k \cdot E\left[\sum_{p \in \mathcal{S}: e \in p} X_p \cdot \frac{d(p)}{k}\right] \\
&\leq \sum_{e \in E'} k \cdot \sum_{p \in \mathcal{S}: e \in p} \frac{k \cdot f(p)}{d(p)/(4k)} \cdot \frac{d(p)}{k} \\
&\leq \sum_{e \in E'} k \cdot 4k \sum_{p \in \mathcal{S}: e \in p} f(p) \\
&\leq \sum_{e \in E'} 4k^2 \cdot \frac{1}{2k} \leq \sum_{e \in E'} 2k \\
&\leq 4k \sum_{e \in E'} \|\mathcal{W}(e, \mathcal{B})\| \leq \dots \leq 4L \cdot \|\mathcal{B}\|
\end{aligned}$$

where the last calculations are done in the same way as in the proof of Lemma 3.3.  $\square$

Combining the two lemmas proves the theorem.  $\square$

We note that if the minimum demand of a request,  $d_{\min}$ , fulfills  $d_{\min} \geq k/\log(kF)$ , then one would not need Claim 3.5. In particular, if  $d_{\min}$  were known in advance, then the  $k$ -flow BGA could choose  $L = O(k^3 F/(d_{\min}/k))$  to achieve an approximation ratio of  $O(k^3 F/(d_{\min}/k))$ . This would allow a smooth transition from the bounds for the  $k$ -EDP (where  $d_{\min} = k$ ) to the  $k$ -DFP.

### 3.1 An online algorithm for the $k$ -DFP

In this section we present a randomized online algorithm for the  $k$ -DFP. This algorithm, which we shall call the *randomized*  $k$ -flow BGA, is an extension of the  $k$ -flow BGA algorithm for the offline  $k$ -DFP. The technique we present for making offline algorithms online has been used before [2, 12].

Consider, first, the set  $\mathcal{O}$  of  $k$ -systems for requests accepted by the optimal algorithm. Let  $\mathcal{O}_1 \subseteq \mathcal{O}$  consist of  $k$ -systems each with demand at least  $k/2$ , and let  $\mathcal{O}_2 = \mathcal{O} \setminus \mathcal{O}_1$ . Either  $\|\mathcal{O}_1\| \geq 1/2 \cdot \|\mathcal{O}\|$  or  $\|\mathcal{O}_2\| > 1/2 \cdot \|\mathcal{O}\|$ .

The randomized  $k$ -flow BGA begins by *guessing* which of these two events will happen. If it guesses the former, it ignores all requests with demand less than  $k/2$  and runs the regular  $k$ -flow BGA on the rest of the requests. If it guesses the latter, it ignores all requests with demand at least  $k/2$  and runs the  $k$ -flow BGA on the rest.

**Theorem 3.7** *Given a unit-capacity network  $G$  with flow number  $F$ , the expected competitive ratio of the randomized  $k$ -flow BGA for the online  $k$ -DFP is  $O(k^3 F \log(kF))$  when run with parameter  $L = \gamma \cdot k^3 F \log(kF)$  for an appropriately large constant  $\gamma$ .*

**Proof.** The proof runs along exactly the same lines as the proof for Theorem 3.1, but we have to prove Lemma 3.2 for the changed situation. Note that the original proof for Lemma 3.2 relies on the fact that requests are sorted in a non-decreasing order before being considered. That need not be true here. Let  $\mathcal{B}$  denote, as usual, the  $k$ -systems for requests accepted by the randomized  $k$ -flow BGA.

Consider the case when the algorithm guesses that  $\|\mathcal{O}_1\| \geq 1/2 \cdot \|\mathcal{O}\|$ . We claim that for any stream  $q \in \mathcal{O}_1$  and edge  $e$ , if  $q$  has a witness on  $e$  then  $\|\mathcal{W}(e, \mathcal{B})\| \geq 1/2$ . Let  $p \in \mathcal{B}$  be the stream witnessing  $q$  on  $e$ . Since the algorithm only considers requests with demand at least  $k/2$ ,  $f(p) \geq 1/2$ . The claim follows since  $\|\mathcal{W}(e, \mathcal{B})\| \geq f(p)$ . Following the rest of the proof for Theorem 3.1, substituting  $\mathcal{O}_1$  for  $\mathcal{O}$ , shows that in this case the randomized  $k$ -flow BGA will have a competitive ratio of  $O(k^3 F \log(kF))$ .

Now consider the case when the algorithm guesses  $\|\mathcal{O}_2\| \geq 1/2 \cdot \|\mathcal{O}\|$ . We claim that even in this case for any stream  $q \in \mathcal{O}_2$  and edge  $e$ , if  $q$  has a witness on  $e$  then  $\|\mathcal{W}(e, \mathcal{B})\| \geq 1/2$ . From the definition of witnessing, we have  $F(e, q) + f(q) > 1$ . Next, from the definition of  $\mathcal{O}_2$ ,  $f(q) < 1/2$ . The claim follows as  $\|\mathcal{W}(e, \mathcal{B})\| \geq F(e, q)$ . As in the previous case, the rest of the proof for Theorem 3.1 applies here too; substitute  $\mathcal{O}_2$  for  $\mathcal{O}$ .

The competitive ratio in both cases is  $O(k^3 F \log(kF))$ . Note that an incorrect guess just reduces the expected competitive ratio by a factor of 2.  $\square$

### 3.2 Comparison with other flow problems

In this section we demonstrate that the  $k$ -DFP is harder to approximate than other related flow problems because of the requirement that the  $k$  paths for every request must be disjoint.

The  $k$ -splittable flow problem and the integral splittable flow problem have been defined in the introduction. As already mentioned there, previous proof techniques [12] imply the following result under the no-bottleneck assumption (i.e., the maximal demand is at most equal to the minimal edge capacity).

**Theorem 3.8** *For a unit-capacity network  $G$  with flow number  $F$ , the approximation ratio of the 1-BGA with parameter  $L = 4F$  for the  $k$ -SFP and for the ISF, when run on requests ordered according to their demands starting from the largest, is  $O(F)$ .*

**Proof.** The crucial point is that in the analysis of the BGA algorithm for the UFP problem in the previous work [12] the solution of the BGA is compared with an optimal solution of a relaxed problem, namely the *fractional* maximum multicommodity flow problem, and this problem is also a relaxation for both the ISF and the  $k$ -SFP. It follows that the approximation guarantee  $O(F)$  of the BGA proved for the UFP problem holds for the  $k$ -SFP and the ISF problems as well.  $\square$

Using the standard techniques mentioned earlier, the algorithm can be converted into a randomized online algorithm with the same expected competitive ratio. If there is a guarantee that the ratio between the maximal and the minimal demand is at most 2 (or some other constant) or that the maximal demand is at most  $1/2$  (or some other constant smaller than 1, the edge capacity), the online algorithm can be made even deterministic with the same competitive ratio (cf. [11]). Taking into account the online lower bound of Theorem 2.4, this shows that the  $k$ -SFP and the ISF are indeed simpler problems than the  $k$ -DFP.

The techniques of the current paper imply results for the ISF even when the no-bottleneck assumption does not hold and only the weak bottleneck assumption is guaranteed (i.e., the maximal demand

is at most  $k$  times larger than the minimal edge capacity). Under this assumption, on unit-capacity networks the ISF resembles the multi-EDP problem from Section 2.4 and it is possible to use the multi-BGA algorithm for it and get the same guarantee as in Theorem 2.6.

**Corollary 3.9** *Given a unit-capacity network  $G$  with flow number  $F$ , the competitive ratio of the multi-BGA for the ISF under the weak bottleneck assumption is  $O(d_{\max}^3 F)$ .*

## 4 Conclusions

In this paper we introduced the  $k$ -EDP and the  $k$ -DFP problems and presented upper and lower bounds for them as well as for other related problems. Many questions remain open. For example, what is the best competitive ratio a deterministic algorithm can achieve for the  $k$ -EDP? We suspect that it is  $O(k \cdot F)$ , but it seems very hard to prove. Is it possible to simplify the proof for the  $k$ -DFP and improve the upper bound? We suspect that it should be possible to prove an  $O(k \cdot F)$  upper bound here as well. Even an improvement of the  $O(k^3 F \log(kF))$  bound  $k$ -DFP to  $O(k^3 F)$  would be interesting.

A number of other problems arise for networks with nonuniform edge capacities: the  $k$ -flow BGA algorithm can be used on them as well but is it possible to prove the same performance bounds?

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