

# Computational Geometry Lecture 37

Topic : Geometric set cover

$S = (X, \mathcal{R})$  has  $S$  has  
finite VC dimension.

$X$  : set of  $n$  points

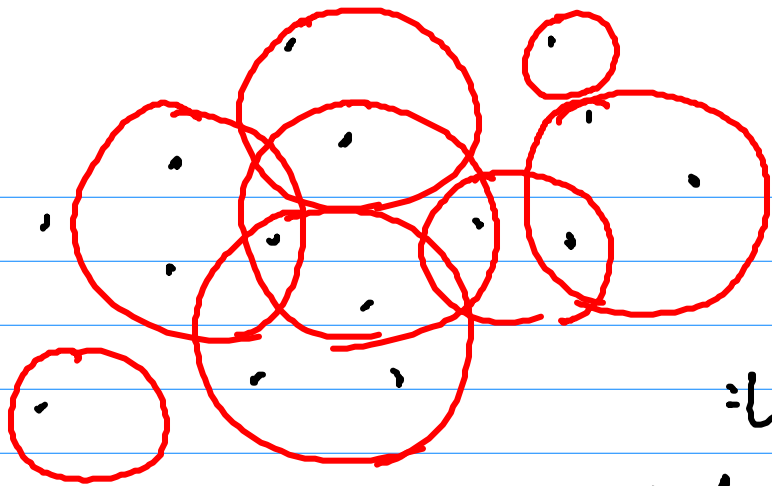
$\mathcal{R}$  : " "  $m$  ranges

We want to choose a subset

$\mathcal{R}' \subset \mathcal{R}$  that covers all  
points of  $X$ , namely  $\forall x \in X,$

$\exists R \in \mathcal{R}', x \in R$

We can use the general  
set cover algorithm (say the  
greedy algorithm) to find a cover  
of size  $k \cdot \log n$   $k = |\text{OPT cover}|$



This problem is known to be NP-hard.  $\therefore$  finding the smallest size set cover.

Can we improve upon the generic set cover soln?

$$S = (X, \mathcal{R})$$

Defn:  $\epsilon$ -net. A subset  $N \subseteq X$  is

a  $\epsilon$ -net for  $X$ , if for any range  $r \in \mathcal{R}$  and  $m(r) \geq \epsilon$

then  $N$  contains at least one point of  $r \cap X$ .

$$m(r) = \frac{|r \cap X|}{|X|}$$

$$m(r) \geq \epsilon$$

$$\left| \frac{|N \cap r|}{|N|} - \frac{|r \cap X|}{|X|} \right|$$

$\leq \epsilon$

How does one construct an  $\epsilon$ -net?

Theorem Let  $(X, \mathcal{R})$  be a range space of VC dimension  $\delta$  and  $\mathcal{X}$  be a finite subset of  $X$ .

For  $0 < \epsilon < 1$  and  $\varphi < 1$

let  $N$  be a subset obtained by  $m$  independent draws from  $\mathcal{X}$  (uniformly chosen), where

$$m \geq \max \left\{ \frac{4}{\epsilon} \log \left( \frac{4}{\varphi} \right), \frac{8\delta}{\epsilon} \log \left( \frac{16}{\epsilon} \right) \right\}$$

Then  $N$  is an  $\epsilon$ -net with probability  $\geq 1 - \varphi$

$$|N| = m$$

Suppose we use the shattering dimension of  $\mathcal{S}$ , say  $d$ .

-Then sample size  $\geq O\left(\frac{d \log d}{\epsilon}\right)$

Comment: Suppose the elements

$\eta$  of  $X$  are weighted, i.e.

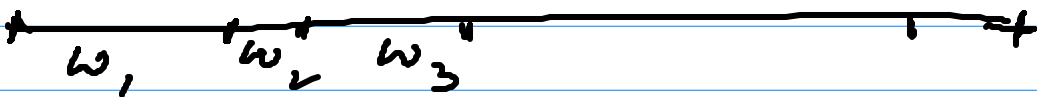
there is a weight function

$$w: X \rightarrow \mathbb{R}^+ \quad w(\eta) = \sum_{\tilde{y} \in \eta} w(\tilde{y})$$

$$\therefore \text{Suppose } W = \sum_{y \in X} w(y)$$

then we may be interested to  
hit the "large weighted"  
ranges, namely those whose  
weights are  $> \epsilon \cdot W$

A similar result can be proved  
where the ordinary sampling  
is replaced with "weighted sampling"



# Algorithm set cover

It repeatedly selects an  $\epsilon$ -net for some " $\epsilon$ "

$\exists S^*$  : Suppose has a shattering dimension  $\delta^*$

- Choose an  $\epsilon$ -net (weighted) of size  $O\left(\frac{\delta^*}{\epsilon} \log\left(\frac{\delta^*}{\epsilon}\right)\right)$ , call it  $\gamma$

- Verify if  $\gamma$  is an  $\epsilon$ -net : if not discard

: else (if  $\gamma$  is an  $\epsilon$ -net), then

we check if  $\gamma$  is a cover

(brute force)

If it is a cover, - then output  $\gamma$

else (if not a cover)

- then there must be at least one

point  $p \in X$  that is not covered by  $\gamma$ .  
Let  $R_p = \{r \in R \mid p \in r\}$

Note that  $R_p$  must include  
same range  $v_i \in OPT$

We will double the weight  
of elements in  $R_p$

if  $W(R_p) < \epsilon W$ .

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Observation: Every time, we  
double the weight, we are  
increasing the weight by no more  
than  $(1 + \epsilon)$  multiplicative factor

Therefore  $W_i \leq (1 + \epsilon) W_{i-1}$

$$\Rightarrow W_i \leq (1 + \epsilon)^i m = W_0$$

( $i$  is an iteration where weights are  
doubled)