# Extending Process Algebra with an undefined action http://www.cse.iitd.ac.in/~sak/ 

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## Outline

- Motivation
- Process Model
- Basic Extended Process Algera
- Prebisimilarity
- Logical Characterisation: PHML
- Conclusion


## Divergence, Livelock and Deadlock

$\bullet \approx[8]$ and weaker equivalences [4] are insensitive to " $\tau$-cycles".

- " $\tau$-cycles" $(T \Leftarrow \tau . T)$ are identified with divergence [11] and has the same solution as $X \Leftarrow X$.
- " $\tau$-cycles" could also be due to "livelock" i.e. infinite "internal chatter". $P \Leftarrow a . P, Q \Leftarrow \bar{a} . Q, R=(P \mid Q) \backslash a \sim \tau . R$
- In SCCS [7] the solution of $X \Leftarrow X$ is identified with deadlock.

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| CALCULI FOR SYNCHRONY AND ASYNCHRONY* |  |
| Robin MILNER <br> Deparment of Computer Science. Edinburgh Universiry. Edinburgh EH9 3JZ, United Kingdom |  |
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| Communicated by M. Niva! Received February 1982 |  |
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Divergence ( $\Omega$ ). The least solution of $X \Leftarrow X$ (modulo $\sim$ ) should be a totally "undefined" process.
Livelock. The least solution (modulo $\sim$ ) of $T \Leftarrow \tau . T$ should be a process that can only perform " $\tau$-cycles".
Deadlock (0). A deadlocked process performs no computation unlike a livelocked process which consumes computational cycles and energy.
Hence any strong behavioural relation on processes should ensure that

- divergence, deadlock and livelock are distinguished from each other.
- $\Omega$ is the least defined process (modulo $\sim$ ),
- Deadlock $(0)$ and livelock $(T \Leftarrow \tau . T)$ are both well-defined processes and mutually incomparable.

- $\mathbb{Q}[L]=\langle S, L, \longrightarrow\rangle$
- $s \xrightarrow{\ell}{ }_{-}=\{t \in S \mid s \xrightarrow{\ell} t\}$ is the set of $\ell$-successors of $s$.
- $L(s)=\{\ell \in L \mid \exists t[s \xrightarrow{\ell} t]\}$ is the set of labels from $s$.
- $\operatorname{Succ}(s)=\bigcup_{\ell \in L} s \xrightarrow{\ell}{ }_{-}=\{t \mid \exists \ell \in L[s \xrightarrow{\ell} t]\}$ is the set of successors of $s$
- Targets $(\longrightarrow)=\{t \in S \mid \exists s \in S[t \in \operatorname{Succ}(s)]\}$.
- $\operatorname{Der}(s)=\{s\} \cup \bigcup_{t \in \operatorname{Succ}(s)} \operatorname{Der}(t)$ is the set of derivatives of $s$.

A sub-LTS of $\mathbb{L}[L]$ at a state $s_{0} \in S$ is the rooted $\operatorname{LTS}\left\langle\operatorname{Der}\left(s_{0}\right), L, \longrightarrow, s_{0}\right\rangle$. By convention $s \xrightarrow{\epsilon} s$ and for any $x=a y \in L^{+}, s \xrightarrow{x} s^{\prime}$ if $s \xrightarrow{a} s^{\prime \prime} \xrightarrow{y} s^{\prime}$ for some $s^{\prime \prime} \in S$.


Natural Bisimilarity

## Definition 0.1: Natural bisimulation

A symmetric binary relation $\mathcal{R} \subseteq S \times T$ between (sub-)LTSs $\mathbb{Q}[L]=\langle S, L, \longrightarrow\rangle$ and $\mathbb{M}[L]=\langle T, L, \longrightarrow\rangle$ such that $s \mathcal{R} t$ implies for all labels $\ell \in L, s \xrightarrow{\ell} s^{\prime} \Rightarrow \exists t^{\prime} \in T\left[t \xrightarrow{\ell} t^{\prime} \wedge s^{\prime} \mathcal{R} t^{\prime}\right]$. Notation: $\left.\mathcal{R} \vdash s \sim t\right)$.

## Fact 0.1

Unions, relational converses and (relational) compositions of natural bisimulations are also natural bisimulations. Natural bisimilarity $(\sim)$ is the largest natural bisimulation and is an equivalence relation.

## Actions and Traces

## Definition 0.2: Actions

$A_{\perp}=A \cup\{\perp\}$ where $A$ is a countable set of (uninterpreted but) welldefined actions and $\perp \notin A$ is a special undefined action with $\perp<a$ for each $a \in A$.

- $\Omega$ can perform only $\perp$.
- Traces are words from $A^{*} \perp^{*}$.
- $A^{*} \perp^{?}:=A^{*} \perp^{*} /(x \perp \perp=x \perp)$ the set of normal forms of traces.


## Definition 0.3: Ordering

$\leq \subseteq A^{*} \stackrel{?}{?} \times A^{*}$ ? be the smallest relation such that for all $x, y \in A^{*}, x \leq x$ and $x \perp \leq x y \perp \leq x y . u<v$ if $u \leq v \not \leq u$ for all $u, v \in A^{*} \perp$ ?

## Definition 0.4: Process

- A (partial) process is a sub-LTS $\left\langle\operatorname{Der}\left(s_{0}\right), A_{\perp}, \longrightarrow, s_{0}\right\rangle$ satisfying the irrecoverability constraint

$$
\begin{equation*}
\forall s \in \operatorname{Der}\left(s_{0}\right)\left[s \xrightarrow{\perp} s^{\prime} \Rightarrow A_{\perp}\left(s^{\prime}\right)=\{\perp\}\right] \tag{1}
\end{equation*}
$$

- The process is total if $s \xrightarrow{\nrightarrow} s^{\prime}$ for all $s, s^{\prime} \in \operatorname{Der}\left(s_{0}\right)$.
- If $s_{0} \xrightarrow{u} t$ for $t \in \operatorname{Der}\left(s_{0}\right)$ and $u \in A^{*}$ ? , then $s_{0} \xrightarrow{u} t$ is a behaviour of the process.


## Fact 0.2: Closed-under-transitions

If $\left\langle S, A_{\perp}, \longrightarrow, s_{0}\right\rangle$ is a process then so is $\left\langle\operatorname{Der}(s), A_{\perp}, \longrightarrow, s\right\rangle$ for any $s \in S$.

## Definition 0.5: Basic Extended Process Algebra (BXPA)

$\mathbf{P}\left[A_{\perp}\right]=\left\langle\mathbb{P}\left[A_{\perp}\right], \Omega, \mathbf{0},\{a .-\mid a \in A\}, \sum\right\rangle$ where

- $\Omega \stackrel{d f}{=}\left\langle\left\{s_{0}\right\}, A_{\perp},\left\{s_{0} \xrightarrow{\perp} s_{0}\right\}, s_{0}\right\rangle$ the totally undefined process,
$\bullet 0 \stackrel{d f}{=}\left\langle\left\{s_{0}\right\}, A_{\perp}, \emptyset, s_{0}\right\rangle$ is the "terminated" or "deadlocked" process.
- $a . P \stackrel{d f}{=}\left\langle S \cup\left\{s_{0}^{\prime}\right\}, A_{\perp}, \longrightarrow \cup\left\{s_{0}^{\prime} \xrightarrow{a} s_{0}\right\}, s_{0}^{\prime}\right\rangle, \quad$ for any $P=$ $\left\langle S, A_{\perp}, \longrightarrow, s_{0}\right\rangle, a \in A$, and $s_{0}^{\prime} \notin S$,
- $\sum_{i \in I} P_{i} \stackrel{\text { df }}{=}\left\langle S, A_{\perp}, \longrightarrow s_{0}\right\rangle$ where $P_{i}=\left\langle S^{i}, A_{\perp}, \longrightarrow i, s_{0}^{i}\right\rangle, i \in I$ and
$-s_{0} \notin \bigcup_{i \in I} S^{i}$ and $S=\operatorname{Der}\left(s_{0}\right)=\left\{s_{0}\right\} \cup \biguplus_{i \in I} \operatorname{Targets}\left(\longrightarrow_{i}\right)$, $-s_{0} \xrightarrow{a} t$ if for some $P_{i}, i \in I, s_{0}^{i} \xrightarrow{a}_{i} t \in S^{i}$,
$-s \xrightarrow{a} t$ if $s \xrightarrow{a}_{i} t$ for some $i \in I, s, t \in \operatorname{Der}\left(s_{0}\right)$.


Example: Summation 1


Example: Summation 2


## BXPA: Basic Identities

## Proposition 0.1

$\mathbb{P}\left[A_{\perp}\right]$ is an idempotent abelian monoid under + with $\mathbf{0}$ as identity. Further 1. $P \xrightarrow{a} P^{\prime}, a \in A$ implies $P \sim a . P^{\prime}+P$.
2. $P \xrightarrow{\perp} P^{\prime}$ implies $P^{\prime} \sim \Omega$ and hence $P \sim \Omega+P$.
3. (Canonical form modulo $\sim$ ). $\quad P \sim[\Omega+] \sum_{a \in A, P \xrightarrow{a} P_{a}} a \cdot P_{a}$ where " $[\Omega+]$ " indicates that $\Omega$ occurs only if $P \xrightarrow{\perp}$.

## Composition

Strictness condition (see irrecoverability)

$$
\begin{equation*}
\left(P \xrightarrow{\perp_{-}} \vee Q \xrightarrow{\perp_{-}}\right) \Longrightarrow((P \otimes Q \xrightarrow{\perp} \Omega) \wedge(Q \otimes P \xrightarrow{\perp} \Omega)) \tag{2}
\end{equation*}
$$

guarantees that $\mathbb{P}\left[A_{\perp}\right]$ is closed under $\otimes$. Hence expansion laws under the various composition operators (e.g. $\|\|, \mid\|,, \times$ ) continue to hold.

## Lifted Strong Bisimulation (LSB)

## Definition 0.6: lifted strong bisimulations (LSB)

A binary relation $\mathcal{R}$ on processes is a lifted strong bisimulation (LSB) if for all states $s, t$, sRt implies for all $a, b \in A_{\perp, \epsilon}$,

$$
\begin{align*}
& s \xrightarrow{a} s^{\prime} \Rightarrow \exists b, t^{\prime}\left[a \leq b \wedge t \xrightarrow{b} t^{\prime} \wedge s^{\prime} \mathcal{R} t^{\prime}\right]  \tag{3}\\
& t \xrightarrow{b} t^{\prime} \Rightarrow \exists a, s^{\prime}\left[a \leq b \wedge s \xrightarrow{a} s^{\prime} \wedge s^{\prime} \mathcal{R} t^{\prime}\right] \tag{4}
\end{align*}
$$

- $s \sqsubseteq t$ (equivalently $t \sqsupseteq s$ ) if there exists a LSB $\mathcal{R}$ such that $s \mathcal{R} t$.
- $s \sqsubseteq t$ if $s \sqsubseteq t$ and $s \sqsupseteq t$.
- $s \sqsubset t$ if $s \sqsubseteq t$ and $s \square t$.


## Examples



In addition, if $\tau$ is in $A$ and $\mathbf{T} \Leftarrow \tau$. $\mathbf{T}$ denotes livelock, then we have $\perp<\tau$,
$\perp<\epsilon$ and hence $\Omega \sqsubset \mathbf{0} \nsubseteq \Omega, \Omega \sqsubset \mathbf{T} \nsubseteq \Omega$ and $\mathbf{0} \nsubseteq \mathbf{T} \nsubseteq \mathbf{0}$

## Precongruence

LSB is an instance of the more general $(\rho, \sigma)$-bisimulation [1] with $\rho=\sigma=\leq$. By theorem 4.1 part 1 in [1], $\sqsubseteq$ is a preorder.
Theorem 0.1: Precongruence.
The operators of $\mathrm{P}\left[A_{\perp}\right]$ are monotonic under $\sqsubseteq$ and the relation $\sqsubseteq$ is a precongruence on $\mathbf{P}\left[A_{\perp}\right]$.

## Logical Characterisation

## Definition 0.7

- $\mathcal{L}$ a logical language and
- $\models^{X} \subseteq \mathbb{P} \times \mathcal{L}$ a satisfaction relation
- $\mathcal{L}_{X}(P)=\left\{\phi \in \mathcal{L} \mid P \models^{X} \phi\right\}$
- $\left(\mathcal{L}, \models^{X}\right)$ characterises a behavioural preorder $\preceq$ over $\mathbb{P}$

$$
\begin{equation*}
P \preceq Q \Leftrightarrow \mathcal{L}_{X}(P) \subseteq \mathcal{L}_{X}(Q) \tag{5}
\end{equation*}
$$

- $P \subseteq_{X} Q$ iff $\mathcal{L}_{X}(P) \subseteq \mathcal{L}_{X}(Q)$.



## PHML: A Modal logic

## Definition 0.8

- Negation-free modal logic $\mathcal{L}_{(\leq, \leq)}{ }^{a}$

$$
\begin{equation*}
\phi::=\mathrm{tt}|\mathrm{ff}|\langle a\rangle \phi|[a] \phi| \bigwedge_{i \in I} \phi_{i} \mid \bigvee_{i \in I} \phi_{i} \tag{6}
\end{equation*}
$$

where $a \in A_{\perp, \epsilon}$ and $I$ is an indexing set,

- $\bigwedge_{i \in \emptyset} \phi_{i} \equiv \mathrm{tt}$ and $\bigvee_{i \in \emptyset} \phi_{i} \equiv \mathrm{ff}$ by convention.
${ }^{a}$ For the present, we are assuming that every action in $A_{\perp, \epsilon}$ including the undefined action $\perp$ is observable; this may be relaxed.



## Semantics: Satisfaction

## Definition 0.9: Satisfaction

$P \models^{S}$ tt for each $P \in \mathbb{P}_{I F}$
$P \models^{S}\langle a\rangle \phi$ iff $\exists b \in A_{\perp, \epsilon}: b \geq a, P^{\prime}:$ $\left[P \xrightarrow{b} P^{\prime} \wedge P^{\prime} \models^{S} \phi\right]$

$$
P \models^{S} \bigvee_{i \in I} \phi_{i} \text { iff } \exists i \in I\left[P \models^{S} \phi_{i}\right]
$$

$P \models^{S} \bigwedge_{i \in I} \phi_{i}$ iff $\forall i \in I\left[P \models^{S} \phi_{i}\right] \quad P \models^{S} \bigvee_{i \in I} \phi_{i}$ iff $\exists i \in I\left[P \models^{S} \phi_{i}\right]$

- $P$ satisfies $\phi$ if $P \models^{S} \phi$ and
- $\mathcal{L}_{S}(P)=\left\{\phi \mid P \models^{S} \phi\right\}$
- $P \subseteq_{S} Q$ if $\mathcal{L}_{S}(P) \subseteq \mathcal{L}_{S}(Q)$ for processes $P, Q$,
$P \models^{S}$ ff for no $P \in \mathbb{P}_{I F}$
$P \models^{S}[a] \phi$ iff $\forall b \in A_{\perp, \epsilon}: b \leq a, P^{\prime}:$

$$
\left[P \xrightarrow[C]{b} P^{\prime} \Rightarrow P^{\prime} \models^{S} \phi\right]
$$

$\left[P \xrightarrow{b} P^{\prime} \Rightarrow P^{\prime} \models^{S} \phi\right]$

## PHML characterisation of LSB

## Theorem 0.2: Logical characterisation of $\sqsubseteq$

$P \sqsubseteq Q$ if and only if $\mathcal{L}_{S}(P) \subseteq \mathcal{L}_{S}(Q)$ for image-finite processes.
Theorem 0.2 then directly follows from definition 5 and theorem 3 of [3]. But

- it is difficult to explain modalities like $\langle\perp\rangle$ and $[\perp]$.
- Also modalities like $\langle\epsilon\rangle$ and $[\epsilon]$ do not add much value to the notion of observation.




## Redefining old notions

- $s$ may diverge $(s \uparrow)$ if $s \xrightarrow{\perp}$. Otherwise it converges $(s \downarrow)$. Analogously for processes.
- A binary relation $\mathcal{R}$ on processes is a divergent strong bisimulation (DSB) if for all $s, t \in S, s \mathcal{R} t$ implies the following.

$$
\begin{array}{r}
\forall a \in A\left[s \xrightarrow{a} s^{\prime} \Rightarrow \exists t^{\prime}\left[t \xrightarrow{a} t^{\prime} \wedge s^{\prime} \mathcal{R} t^{\prime}\right]\right. \\
s \downarrow \Rightarrow\left(t \downarrow \wedge \forall a \in A\left[t \xrightarrow{a} t^{\prime} \Rightarrow \exists s^{\prime}\left[s \xrightarrow{a} s^{\prime} \wedge s^{\prime} \mathcal{R} t^{\prime}\right]\right]\right) \tag{8}
\end{array}
$$

- $s \sqsubseteq t$ (equivalently $t \gtrsim s$ ) if there exists a DSB $\mathcal{R}$ such that $s \mathcal{R} t$ (we write $\mathcal{R} \vdash s \sqsubseteq t$ to denote this fact). $s \square t$ if $s \sqsubseteq t$ and $s \gtrsim t$.



## Equivalence of LSB and DSB

- $\{\Omega\} \times \mathbb{P}$ is a DSB and hence $\Omega \sqsubseteq P$ for all $P \in \mathbb{P}$.
- $\left(\mathcal{R}\right.$ completion) $\mathcal{R}^{\perp}=\mathcal{R} \cup\left\{\left(s, t^{\prime}\right) \mid s \mathcal{R} t, s \uparrow, A(s)=\emptyset, t \downarrow, t^{\prime} \in \operatorname{Der}(t)\right\}$.


## Lemma 0.1

1. If $\mathcal{R}$ is a DSB then so is $\mathcal{R}^{\perp}$.
2. $\mathcal{R}$ is a DSB implies $\mathcal{R}^{\perp}$ is a LSB.
3. If $\mathcal{R}$ is a LSB then so is $\mathcal{R}^{\perp}$.
4. Every LSB is also a DSB.

Theorem 0.3
$\sqsubseteq=\sqsubseteq$ and $\square=\square$.

Affirmation
$\mathcal{L}^{-\perp}$ is $\mathcal{L}$ without $\langle\perp\rangle$ and $[\perp]$.

## Definition 0.10: Affirmation

$\models^{A} \subseteq \mathbb{P} \times \mathcal{L}^{-\perp}$ is the smallest (infix) relation defined by induction on the structure of formulae for any process $P$ and any action $a \in A_{\perp, \epsilon}$.
$P \models^{A}$ tt for each $P \in \mathbb{P}$
$P \models^{A}$ ff for no $P \in \mathbb{P}$
$P \models^{A}\langle a\rangle \phi$ iff
$\exists P^{\prime}\left[P \xrightarrow{a} P^{\prime} \wedge P^{\prime} \models^{A} \phi\right] \quad P \downarrow \wedge \forall P^{\prime}\left[P \xrightarrow{a} P^{\prime} \Rightarrow P^{\prime} \models^{A} \phi\right]$
$P \models^{A} \bigwedge_{i \in I} \phi_{i}$ iff $\forall i \in I\left[P \models^{A} \phi_{i}\right] \quad P \models^{A} \bigvee_{i \in I} \phi_{i}$ iff $\exists i \in I\left[P \models^{A} \phi_{i}\right]$
$P$ affirms $\phi$ if $P \models^{A} \phi$ and $\mathcal{L}_{A}(P)=\left\{\phi \mid P \models^{A} \phi\right\} . P \subseteq_{A} Q$ if $\mathcal{L}_{A}(P) \subseteq \mathcal{L}_{A}(Q)$ for processes $P$ and $Q$.

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## Characterisation

## Definition 0.11

1. $P \subseteq{ }_{S}^{-\perp} Q$ iff $\mathcal{L}_{S}^{-\perp}(P) \subseteq \mathcal{L}_{S}^{-\perp}(Q)$.
2. $P \subseteq_{A}^{-\perp} Q$ iff $\mathcal{L}_{A}^{-\perp}(P) \subseteq \mathcal{L}_{A}^{-\perp}(Q)$.

Theorem 0.4
$\subseteq_{S}^{-\perp}=\sqsubseteq=\subseteq_{A}^{-\perp}$ i.e. $\mathcal{L}^{-\perp}$ characterises the preorder $\sqsubseteq$.


## Conclusions.

- Recursion not explicitly considered (since the model allows processes with infinite behaviours).
- But easy to see that guarded recursion (made up only of well-defined actions) will yield unique fixpoints.
- If $\tau \in A$ then $X \Leftarrow X$ and $X \Leftarrow \tau$. $X$ will yield different least solutions.


## Future Work.

- $\sqsubset$ could be used as a refinement relation that allows the progression from a totally undefined process to a well-defined process satisfying certain modal properties.
$\bullet \mathbb{P}\left[A_{\perp}\right]$ is closed under various composition operations. This allows the possibility of using more than one parallel composition operator in the specification of systems. specification ot systems.

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Thank You!
Any Questions?

