

Extending Process Algebra with an undefined action

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Outline

- Motivation
- Process Model
- Basic Extended Process Algera
- Prebisimilarity
- Logical Characterisation: PHML
- Conclusion



Divergence, Livelock and Deadlock

- \approx [8] and weaker equivalences [4] are insensitive to "au-cycles".
- " τ -cycles" ($T \Leftarrow \tau . T$) are identified with divergence [11] and has the same solution as $X \Leftarrow X$.
- " τ -cycles" could also be due to "livelock" i.e. infinite "internal chatter". $P \Leftarrow a.P$, $Q \Leftarrow \overline{a}.Q$, $R = (P|Q) \backslash a \sim \tau.R$
- In SCCS [7] the solution of $X \Leftarrow X$ is identified with deadlock.

Theoretical Computer Science 25 (1983) 267-310 267 North-Holland	The derivation rule for recursion is as follows:	page 274
CALCULI FOR SYNCHRONY AND ASYNCHRONY"	$\frac{E_i\{\operatorname{fix} \hat{X}\hat{E}/\hat{X}\} \xrightarrow{a} E'}{\operatorname{fix}_i \hat{X}\hat{E} \xrightarrow{a} E'}$	
Robin MILNER Departmeni of Computer Science, Edinburgh University, Edinburgh EH9 3JZ, United Kingdom	(i) $F = \text{fix } XX$. The only instances of the rule which can have the form	n yield an action for F
Communicated by M. Nivat Received February 1982 Revised August 1982	$\frac{F \xrightarrow{a} E'}{F \xrightarrow{a} E'}$	
<u>.</u>	Hence, since every derivation must be inferred by a finite pa no actions. It will turn out to be congruent to 0 .	oof, F in this case has

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Our view

- Divergence (Ω). The least solution of $X \leftarrow X$ (modulo \sim) should be a totally "undefined" process.
- Livelock. The least solution (modulo \sim) of $T \leftarrow \tau T$ should be a process that can only perform " τ -cycles".
- Deadlock (0). A deadlocked process performs no computation unlike a livelocked process which consumes computational cycles and energy.

Hence any strong behavioural relation on processes should ensure that

- divergence, deadlock and livelock are distinguished from each other.
- Ω is the least defined process (modulo \sim),
- Deadlock (0) and livelock ($T \leftarrow \tau T$) are both well-defined processes and mutually incomparable.

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LTS



- $\mathbb{L}[L] = \langle S, L, \longrightarrow \rangle$ • $s \xrightarrow{\ell} = \{t \in S \mid s \xrightarrow{\ell} t\}$ is the set of ℓ -successors of s.
- $L(s) = \{\ell \in L \mid \exists t[s \xrightarrow{\ell} t]\}$ is the set of labels from s.
- $Succ(s) = \bigcup_{\ell \in L} s \xrightarrow{\ell} = \{t \mid \exists \ell \in L[s \xrightarrow{\ell} t]\}$ is the set of successors of s
- $\bullet \ Targets(\longrightarrow) = \{t \in S \ \mid \ \exists s \in S[t \in Succ(s)]\}.$
- $Der(s) = \{s\} \cup \bigcup_{t \in Succ(s)} Der(t)$ is the set of *derivatives* of *s*.

A sub-LTS of $\mathbb{L}[L]$ at a state $s_0 \in S$ is the rooted LTS $\langle Der(s_0), L, \longrightarrow, s_0 \rangle$. By convention $s \xrightarrow{\epsilon} s$ and for any $x = ay \in L^+$, $s \xrightarrow{x} s'$ if $s \xrightarrow{a} s'' \xrightarrow{y} s'$ for some $s'' \in S$.





Natural Bisimilarity

Definition 0.1: Natural bisimulation

A symmetric binary relation $\mathcal{R} \subseteq S \times T$ between (sub-)LTSs $\mathbb{L}[L] = \langle S, L, \longrightarrow \rangle$ and $\mathbb{M}[L] = \langle T, L, \longrightarrow \rangle$ such that $s\mathcal{R}t$ implies for all labels $\ell \in L$, $s \stackrel{\ell}{\longrightarrow} s' \Rightarrow \exists t' \in T[t \stackrel{\ell}{\longrightarrow} t' \wedge s'\mathcal{R}t']$. Notation: $\mathcal{R} \vdash s \sim t$).

Fact 0.1

Unions, relational converses and (relational) compositions of natural bisimulations are also natural bisimulations. Natural bisimilarity (\sim) is the largest natural bisimulation and is an equivalence relation.

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Actions and Traces

Definition 0.2: Actions

 $A_{\perp} = A \cup \{\perp\}$ where A is a countable set of (uninterpreted but) welldefined actions and $\perp \notin A$ is a special undefined action with $\perp < a$ for each $a \in A$.

- Ω can perform only \perp .
- *Traces* are words from $A^* \perp^*$.
- $A^* \perp^? := A^* \perp^* / (x \perp \perp = x \perp)$ the set of normal forms of traces.

Definition 0.3: Ordering

 $\leq \subseteq A^*\!\!\!\perp^? \times A^*\!\!\!\perp^? \text{ be the smallest relation such that for all } x, y \in A^* \text{, } x \leq x$ and $x \perp \leq xy \perp \leq xy$. u < v if $u \leq v \not\leq u$ for all $u, v \in A^*\!\!\!\perp^?$.



Process

Definition 0.4: Process

• A (partial) process is a sub-LTS $\langle Der(s_0), A_{\perp}, \longrightarrow, s_0 \rangle$ satisfying the irrecoverability constraint

$$\forall s \in Der(s_0)[s \xrightarrow{\perp} s' \Rightarrow A_{\perp}(s') = \{\perp\}]$$
(1)

- The process is total if $s \xrightarrow{\perp} s'$ for all $s, s' \in Der(s_0)$.
- If $s_0 \xrightarrow{u} t$ for $t \in Der(s_0)$ and $u \in A^* \bot$, then $s_0 \xrightarrow{u} t$ is a behaviour of the process.

Fact 0.2: Closed-under-transitions

If $\langle S, A_{\perp}, \longrightarrow, s_0 \rangle$ is a process then so is $\langle Der(s), A_{\perp}, \longrightarrow, s \rangle$ for any $s \in S$.

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BXPA: Basic Extended Process Algebra



Definition 0.5: Basic Extended Process Algebra (BXPA)

$$\mathbf{P}[A_{\perp}] = \langle \mathbb{P}[A_{\perp}], \Omega, \mathbf{0}, \{a_{\cdot-} \mid a \in A\}, \sum \rangle \text{ where }$$

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$$\Omega \stackrel{df}{=} \langle \{s_0\}, A_{\perp}, \{s_0 \stackrel{\perp}{\longrightarrow} s_0\}, s_0 \rangle$$
 the totally undefined process,

•
$$\mathbf{0} \stackrel{df}{=} \langle \{s_0\}, A_{\perp}, \emptyset, s_0 \rangle$$
 is the "terminated" or "deadlocked" process.

•
$$a.P \stackrel{df}{=} \langle S \cup \{s'_0\}, A_\perp, \longrightarrow \cup \{s'_0 \stackrel{a}{\longrightarrow} s_0\}, s'_0 \rangle$$
, for any $P = \langle S, A_\perp, \longrightarrow, s_0 \rangle$, $a \in A$, and $s'_0 \notin S$,

•
$$\sum_{i \in I} P_i \stackrel{df}{=} \langle S, A_{\perp}, \longrightarrow s_0 \rangle$$
 where $P_i = \langle S^i, A_{\perp}, \longrightarrow_i, s_0^i \rangle$, $i \in I$ and

$$-s_0 \not\in \bigcup_{i \in I} S^i \text{ and } S = Der(s_0) = \{s_0\} \cup \biguplus_{i \in I} Targets(\longrightarrow_i), \\ -s_0 \xrightarrow{a} t \text{ if for some } P_i, i \in I, s_0^i \xrightarrow{a}_i t \in S^i, \end{cases}$$

$$-s \xrightarrow{a} t$$
 if $s \xrightarrow{a}_i t$ for some $i \in I$, $s, t \in Der(s_0)$.

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Example: Summation 1



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Example: Summation 2



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BXPA: Basic Identities

Proposition 0.1

 $\mathbb{P}[A_{\perp}] \text{ is an idempotent abelian monoid under } + \text{ with } \mathbf{0} \text{ as identity. Further}$ $1. P \stackrel{a}{\longrightarrow} P', a \in A \text{ implies } P \sim a.P' + P.$ $2. P \stackrel{\perp}{\longrightarrow} P' \text{ implies } P' \sim \Omega \text{ and hence } P \sim \Omega + P.$ $3. \text{ (Canonical form modulo } \sim \text{).} \quad P \sim [\Omega +] \sum_{a \in A, P \stackrel{a}{\longrightarrow} P_a} a.P_a$ $\text{ where "}[\Omega +]" \text{ indicates that } \Omega \text{ occurs only if } P \stackrel{\perp}{\longrightarrow}.$

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Composition

Strictness condition (see irrecoverability)

$$(P \xrightarrow{\perp} Q \xrightarrow{\perp} Q) \implies ((P \otimes Q \xrightarrow{\perp} \Omega) \land (Q \otimes P \xrightarrow{\perp} \Omega)) \quad (2)$$

guarantees that $\mathbb{P}[A_{\perp}]$ is closed under \otimes . Hence expansion laws under the various composition operators (e.g. |||, ||, ||, \times) continue to hold.

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Lifted Strong Bisimulation (LSB)

Definition 0.6: lifted strong bisimulations (LSB)

A binary relation \mathcal{R} on processes is a lifted strong bisimulation (LSB) if for all states s, t, sRt implies for all $a, b \in A_{\perp,\epsilon}$,

$$s \xrightarrow{a} s' \Rightarrow \exists b, t' [a \leq b \land t \xrightarrow{b} t' \land s' \mathcal{R} t']$$
 (3)

$$t \xrightarrow{b} t' \Rightarrow \exists a, s'[a \leq b \land s \xrightarrow{a} s' \land s' \mathcal{R}t']$$
 (4)

- $s \sqsubseteq t$ (equivalently $t \sqsupseteq s$) if there exists a LSB \mathcal{R} such that $s\mathcal{R}t$.
- $s \sqsubseteq t$ if $s \sqsubseteq t$ and $s \sqsupseteq t$.
- $s \sqsubset t$ if $s \sqsubseteq t$ and $s \oiint t$.

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Examples



In addition, if τ is in A and $\mathbf{T} \leftarrow \tau$. \mathbf{T} denotes livelock, then we have $\bot < \tau$, $\bot < \epsilon$ and hence $\Omega \sqsubset \mathbf{0} \not\sqsubseteq \Omega$, $\Omega \sqsubset \mathbf{T} \not\sqsubseteq \Omega$ and $\mathbf{0} \not\sqsubseteq \mathbf{T} \not\sqsubseteq \mathbf{0}$

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Precongruence

LSB is an instance of the more general (ρ, σ) -bisimulation [1] with $\rho = \sigma = \leq$. By theorem 4.1 part 1 in [1], \sqsubseteq is a preorder.

Theorem 0.1: Precongruence.

The operators of $\mathbf{P}[A_{\perp}]$ are monotonic under \sqsubseteq and the relation \sqsubseteq is a precongruence on $\mathbf{P}[A_{\perp}]$.

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Logical Characterisation

Definition 0.7

- $\bullet \ensuremath{\mathcal{L}}$ a logical language and
- $\models^{X} \subseteq \mathbb{P} \times \mathcal{L}$ a satisfaction relation
- $\mathcal{L}_X(P) = \{ \phi \in \mathcal{L} \mid P \models^X \phi \}$
- (\mathcal{L}, \models^X) characterises a behavioural preorder \preceq over \mathbb{P}

$$P \preceq Q \Leftrightarrow \mathcal{L}_X(P) \subseteq \mathcal{L}_X(Q) \tag{5}$$

• $P \subseteq_X Q$ iff $\mathcal{L}_X(P) \subseteq \mathcal{L}_X(Q)$.

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PHML: A Modal logic

Definition 0.8

• Negation-free modal logic $\mathcal{L}_{(\leq,\leq)}{}^a$

$$\phi ::= \mathbf{tt} \mid \mathbf{ff} \mid \langle a \rangle \phi \mid [a] \phi \mid \bigwedge_{i \in I} \phi_i \mid \bigvee_{i \in I} \phi_i$$

where $a \in A_{\perp,\epsilon}$ and I is an indexing set,

• $\bigwedge_{i \in \emptyset} \phi_i \equiv \text{tt} \text{ and } \bigvee_{i \in \emptyset} \phi_i \equiv \text{ff} \text{ by convention.}$

^{*a*}For the present, we are assuming that every action in $A_{\perp,\epsilon}$ including the undefined action \perp is observable; this may be relaxed.

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(6)



Semantics: Satisfaction

Definition 0.9: Satisfaction

$$\begin{array}{ll} P \models^{S} \mathbf{tt} \text{ for each } P \in \mathbb{P}_{IF} & P \models^{S} \mathbf{ff} \text{ for no } P \in \mathbb{P}_{IF} \\ P \models^{S} \langle a \rangle \phi \text{ iff} & P \models^{S} [a] \phi \text{ iff} \\ \exists b \in A_{\perp,\epsilon} : b \geq a, P' : & \forall b \in A_{\perp,\epsilon} : b \leq a, P' : \\ [P \xrightarrow{b} P' \land P' \models^{S} \phi] & [P \xrightarrow{b} P' \Rightarrow P' \models^{S} \phi] \\ P \models^{S} \bigwedge_{i \in I} \phi_{i} \text{ iff } \forall i \in I[P \models^{S} \phi_{i}] & P \models^{S} \bigvee_{i \in I} \phi_{i} \text{ iff } \exists i \in I[P \models^{S} \phi_{i}] \\ \bullet P \text{ satisfies } \phi \text{ if } P \models^{S} \phi \text{ and} \\ \bullet \mathcal{L}_{S}(P) = \{ \phi \mid P \models^{S} \phi \} \\ \bullet P \subseteq_{S} Q \text{ if } \mathcal{L}_{S}(P) \subseteq \mathcal{L}_{S}(Q) \text{ for processes } P, Q, \end{array}$$

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PHML characterisation of LSB

Theorem 0.2: Logical characterisation of \Box

 $P \sqsubseteq Q$ if and only if $\mathcal{L}_S(P) \subseteq \mathcal{L}_S(Q)$ for image-finite processes.

Theorem 0.2 then directly follows from definition 5 and theorem 3 of [3]. But

- it is difficult to explain modalities like $\langle \perp \rangle$ and $[\perp].$
- \bullet Also modalities like $\langle\epsilon\rangle$ and $[\epsilon]$ do not add much value to the notion of observation.

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Redefining old notions

- s may diverge $(s\uparrow)$ if $s \xrightarrow{\perp}$. Otherwise it converges $(s\downarrow)$. Analogously for processes.
- A binary relation \mathcal{R} on processes is a **divergent strong bisimulation** (DSB) if for all $s, t \in S$, $s\mathcal{R}t$ implies the following.

$$\forall a \in \mathbf{A}[s \xrightarrow{a} s' \Rightarrow \exists t'[t \xrightarrow{a} t' \land s'\mathcal{R}t'] \qquad (7)$$

$$s \downarrow \Rightarrow (t \downarrow \land \forall a \in \mathbf{A}[t \xrightarrow{a} t' \Rightarrow \exists s'[s \xrightarrow{a} s' \land s'\mathcal{R}t']]) \qquad (8)$$

• $s \subseteq t$ (equivalently $t \supseteq s$) if there exists a DSB \mathcal{R} such that $s\mathcal{R}t$ (we write $\mathcal{R} \vdash s \subseteq t$ to denote this fact). $s \supseteq t$ if $s \subseteq t$ and $s \supseteq t$.

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Equivalence of LSB and DSB

- $\{\Omega\} \times \mathbb{P}$ is a DSB and hence $\Omega = P$ for all $P \in \mathbb{P}$.
- (\mathcal{R} completion) $\mathcal{R}^{\perp} = \mathcal{R} \cup \{(s, t') \mid s\mathcal{R}t, s\uparrow, A(s) = \emptyset, t\downarrow, t' \in Der(t)\}.$

Lemma 0.1

1. If \mathcal{R} is a DSB then so is \mathcal{R}^{\perp} .

2. \mathcal{R} is a DSB implies \mathcal{R}^{\perp} is a LSB.

3. If \mathcal{R} is a LSB then so is \mathcal{R}^{\perp} .

4. Every LSB is also a DSB.

Theorem 0.3

$$\overline{\frown} = \sqsubseteq$$
 and $\overline{\bigcirc} = \Box$

Affirmation



$\mathcal{L}^{-\perp}$ is \mathcal{L} without $\langle \perp \rangle$ and $[\perp]$.

Definition 0.10: Affirmation

 $\models^A \subseteq \mathbb{P} \times \mathcal{L}^{-\perp}$ is the smallest (infix) relation defined by induction on the structure of formulae for any process P and any action $a \in A_{\perp,\epsilon}$.

$$P \models^{A} \text{tt for each } P \in \mathbb{P} \qquad P \models^{A} \text{ff for no } P \in \mathbb{P} \\P \models^{A} \langle a \rangle \phi \text{ iff } \qquad P \models^{A} [a]\phi \text{ iff } \\\exists P'[P \xrightarrow{a} P' \land P' \models^{A} \phi] \qquad P \downarrow \land \forall P'[P \xrightarrow{a} P' \Rightarrow P' \models^{A} \phi] \\P \models^{A} \bigwedge_{i \in I} \phi_{i} \text{ iff } \forall i \in I[P \models^{A} \phi_{i}] \qquad P \models^{A} \bigvee_{i \in I} \phi_{i} \text{ iff } \exists i \in I[P \models^{A} \phi_{i}] \end{cases}$$

P affirms ϕ if $P \models^A \phi$ and $\mathcal{L}_A(P) = \{\phi \mid P \models^A \phi\}$. $P \subseteq_A Q$ if $\mathcal{L}_A(P) \subseteq \mathcal{L}_A(Q)$ for processes P and Q.

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Characterisation

Definition 0.11

1.
$$P \subseteq_S^{-\perp} Q$$
 iff $\mathcal{L}_S^{-\perp}(P) \subseteq \mathcal{L}_S^{-\perp}(Q)$.
2. $P \subseteq_A^{-\perp} Q$ iff $\mathcal{L}_A^{-\perp}(P) \subseteq \mathcal{L}_A^{-\perp}(Q)$.

Theorem 0.4

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$$\subseteq_{S}^{-\perp} = \sqsubseteq = \subseteq_{A}^{-\perp} \text{ i.e. } \mathcal{L}^{-\perp} \text{ characterises the preorder } \sqsubseteq.$$

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Conclusions & Future Work



Conclusions.

- Recursion not explicitly considered (since the model allows processes with infinite behaviours).
- But easy to see that guarded recursion (made up only of well-defined actions) will yield unique fixpoints.
- If $\tau \in A$ then $X \Leftarrow X$ and $X \Leftarrow \tau X$ will yield different least solutions.

Future Work.

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- \square could be used as a refinement relation that allows the progression from a totally undefined process to a well-defined process satisfying certain modal properties.
- $\mathbb{P}[A_{\perp}]$ is closed under various composition operations. This allows the possibility of using more than one parallel composition operator in the specification of systems.

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Thank You! Any Questions?

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