

# From Traces To Proofs: Proving Concurrent Programs Safe

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# Motivation

# Example: Peterson's Algorithm

▶ Example trace

```

                                 $flag_1 = \text{true}, flag_2 = \text{true}, turn = 0$ 
while(true) do
a.  $flag_1 := \text{true}$ 
b.  $turn := 2$ 
A. assume( $\neg flag_2 \parallel turn = 1$ );
CS1.  $cs := 1$ ;
d.  $\ell_1 := cs$ ;
e.  $flag_1 := \text{false}$ 
od
|
while(true) do
p.  $flag_2 := \text{true}$ 
q.  $turn := 1$ 
P. assume( $\neg flag_1 \parallel turn = 2$ );
CS2.  $cs := 2$ ;
s.  $\ell_2 := cs$ ;
t.  $flag_2 := \text{false}$ 
od
```

Informal reasoning about the correctness of the mutual exclusion property



# Example: Peterson's Algorithm

▶ Example trace

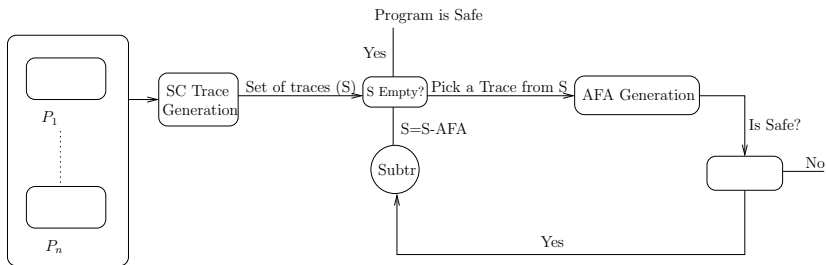
```

                                flag1 = true, flag2 = true, turn = 0
while(true) do                | while(true) do
a. flag1 := true                | p. flag2 := true
b. turn := 2                    | q. turn := 1
A. assume(¬flag2 || turn = 1); | P. assume(¬flag1 || turn = 2);
CS1. cs := 1;                  | CS2. cs := 2;
d. ℓ1 := cs;                    | s. ℓ2 := cs;
e. flag1 := false              | t. flag2 := false
od                             | od
```

**Informal reasoning** about the correctness of the mutual exclusion property

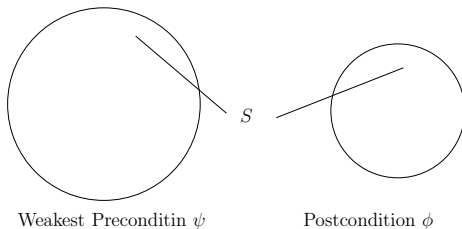
- When  $turn := 2$  is the last write to variable  $turn$
- When  $turn := 1$  is the last write to variable  $turn$

# Overall Partitioning Algorithm



# Some Preliminaries: Weakest Preconditions

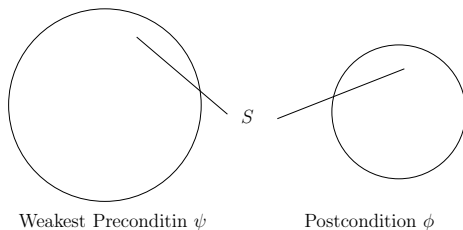
$\text{wp}(S, \phi)$  is the largest set of states from where the execution of the statement  $S$  halts in a state satisfying  $\phi$ .





# Some Preliminaries: Weakest Preconditions

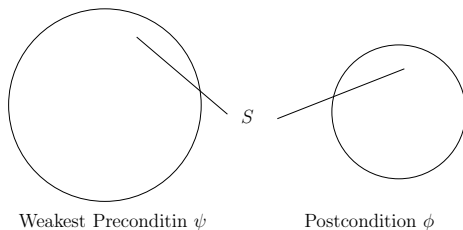
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- $\text{wp}(x := a + 1, x > 5) = a + 1 > 5$

# Some Preliminaries: Weakest Preconditions

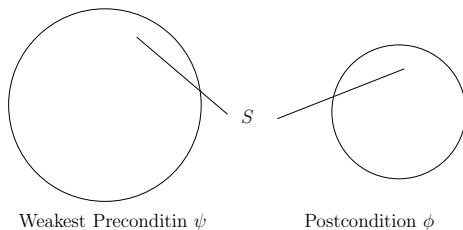
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- $\text{wp}(x := a + 1, x > 5) = a + 1 > 5$
- $\text{wp}(\text{assert}(\psi), \phi) = \psi \wedge \phi$

# Some Preliminaries: Weakest Preconditions

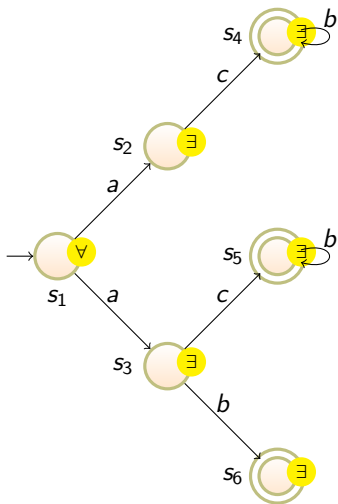
$\text{wp}(S, \phi)$  is the largest set of states from where the execution of the statement  $S$  halts in a state satisfying  $\phi$ .



- $\text{wp}(x := a + 1, x > 5) = a + 1 > 5$
- $\text{wp}(\text{assert}(\psi), \phi) = \psi \wedge \phi$
- $\text{wp}(\text{assume}(\psi), \phi) = \psi \wedge \phi$

# Preliminaries

# Some Preliminaries: Alternating Finite Automata



- $\text{lang}(s_2) = cb^*$
- $\text{lang}(s_3) = cb^* + b$
- $\text{lang}(s_1) = acb^*$

## Example

# Example trace and its AFA construction

▶ Peterson

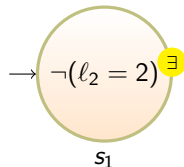
## Example trace $\sigma$

a.  $flag_1 := true$   
b.  $turn := 2$   
A.  $assume(\neg flag_2 \parallel turn = 1);$   
p.  $flag_2 := true$   
q.  $turn := 1$   
P.  $assume(\neg flag_1 \parallel turn = 2);$   
CS2.  $cs := 2$   
CS1.  $cs := 1$   
s.  $l_2 := cs$   
     $assert(l_2 = 2)$

Let  $\mathcal{I}$  be an initial condition. Then show that  $wp(\sigma, \neg(l_2 = 2)) \wedge \mathcal{I}$  is unsatisfiable

# Step 1

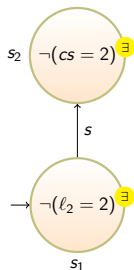
a.  $flag_1 := true$   
b.  $turn := 2$   
A.  $assume(\neg flag_2 \parallel turn = 1);$   
p.  $flag_2 := true$   
q.  $turn := 1$   
P.  $assume(\neg flag_1 \parallel turn = 2);$   
CS2.  $cs := 2$   
CS1.  $cs := 1$   
s.  $\ell_2 := cs$   
     $assert(\ell_2 = 2)$





# Step 2

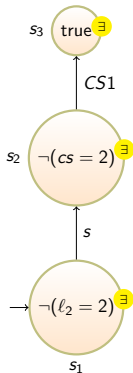
a.  $flag_1 := true$   
b.  $turn := 2$   
A.  $assume(\neg flag_2 \parallel turn = 1);$   
p.  $flag_2 := true$   
q.  $turn := 1$   
P.  $assume(\neg flag_1 \parallel turn = 2);$   
CS2.  $cs := 2$   
CS1.  $cs := 1$   
s.  $l_2 := cs$   
     $assert(l_2 = 2)$



Note that  $wp(s, \neg(l_2 = 2)) = \neg(cs = 2)$

# Step 3

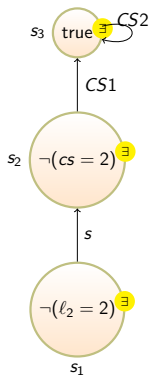
a.  $flag_1 := true$   
b.  $turn := 2$   
A.  $assume(\neg flag_2 \parallel turn = 1);$   
p.  $flag_2 := true$   
q.  $turn := 1$   
P.  $assume(\neg flag_1 \parallel turn = 2);$   
CS2.  $cs := 2$   
CS1.  $cs := 1$   
s.  $l_2 := cs$   
     $assert(l_2 = 2)$



Note that  $wp(c, \neg(cs = 2)) = true$

# Step 4

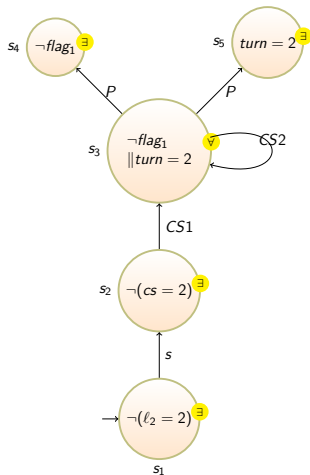
- a.  $flag_1 := true$
- b.  $turn := 2$
- A.  $assume(\neg flag_2 \parallel turn = 1);$
- p.  $flag_2 := true$
- q.  $turn := 1$
- P.  $assume(\neg flag_1 \parallel turn = 2);$
- CS2.  $cs := 2$
- CS1.  $cs := 1$
- s.  $l_2 := cs$   
     $assert(l_2 = 2)$



Note that  $wp(CS2, true) = true$

# Step 5

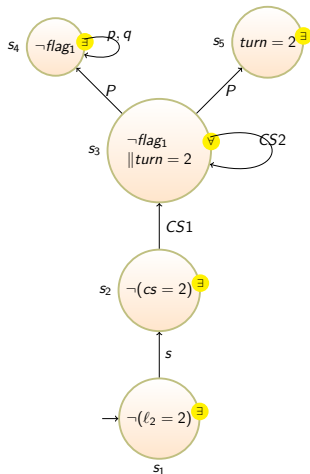
- a.  $flag_1 := true$
- b.  $turn := 2$
- A.  $assume(\neg flag_2 \parallel turn = 1);$
- p.  $flag_2 := true$
- q.  $turn := 1$
- P.  $assume(\neg flag_1 \parallel turn = 2);$
- CS2.  $cs := 2$
- CS1.  $cs := 1$
- s.  $l_2 := cs$   
     $assert(l_2 = 2)$



Note that  $wp(P, true) = (flag_1 = 0 \parallel turn = 2)$

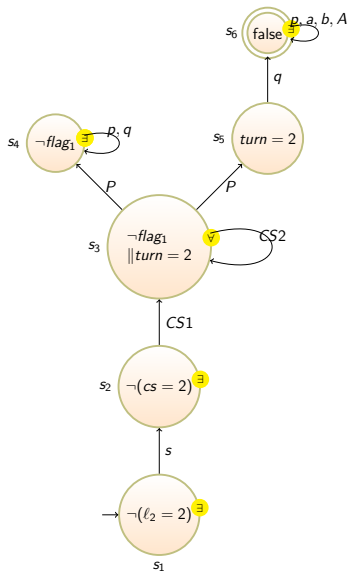
# Step 6

- a.  $flag_1 := true$
- b.  $turn := 2$
- A.  $assume(\neg flag_2 \parallel turn = 1);$
- p.  $flag_2 := true$
- q.  $turn := 1$
- P.  $assume(\neg flag_1 \parallel turn = 2);$
- CS2.  $cs := 2$
- CS1.  $cs := 1$
- s.  $\ell_2 := cs$   
     $assert(\ell_2 = 2)$



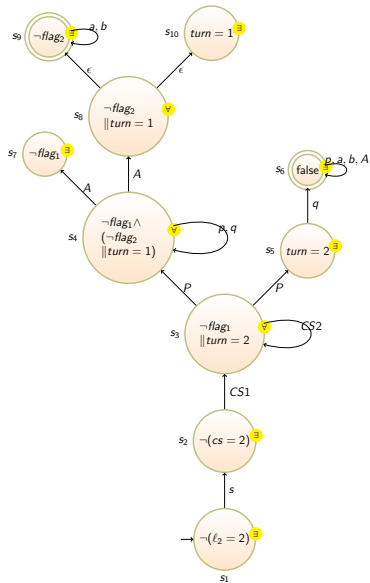
# Step 7

- a.  $flag_1 := true$
- b.  $turn := 2$
- A.  $assume(\neg flag_2 \parallel turn = 1);$
- p.  $flag_2 := true$
- q.  $turn := 1$
- P.  $assume(\neg flag_1 \parallel turn = 2);$
- CS2.  $cs := 2$
- CS1.  $cs := 1$
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     $assert(\ell_2 = 2)$



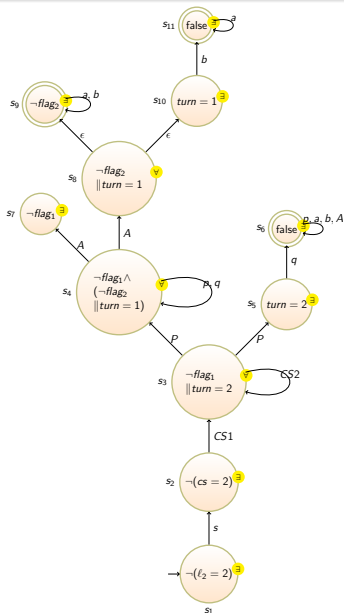
# Step 8

- a.  $flag_1 := true$
- b.  $turn := 2$
- A.  $assume(\neg flag_2 \parallel turn = 1);$
- p.  $flag_2 := true$
- q.  $turn := 1$
- P.  $assume(\neg flag_1 \parallel turn = 2);$
- CS2.  $cs := 2$
- CS1.  $cs := 1$
- s.  $\ell_2 := cs$   
     $assert(\ell_2 = 2)$



# Step 9

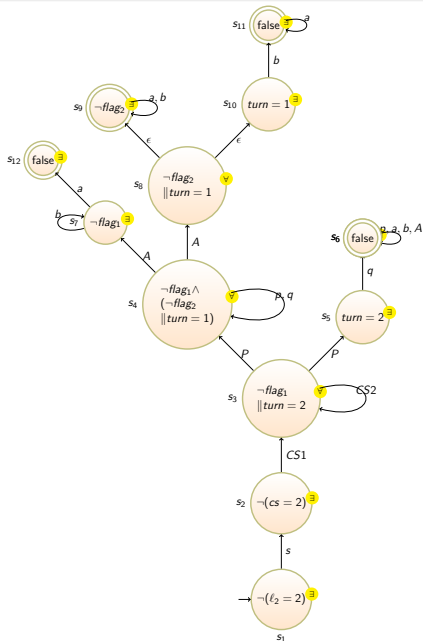
- a.  $flag_1 := true$
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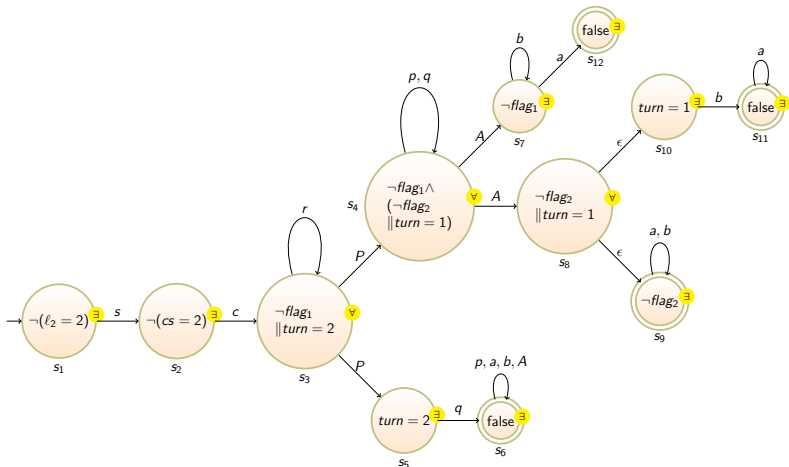


# Step 10

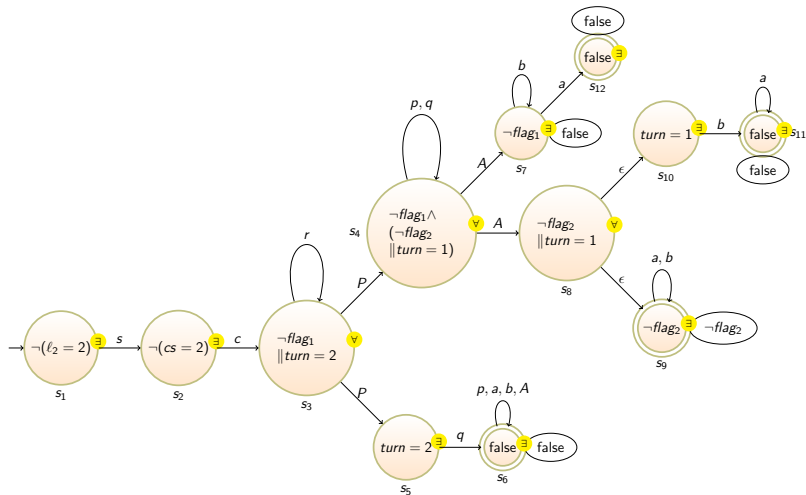
- a.  $flag_1 := true$
- b.  $turn := 2$
- A.  $assume(\neg flag_2 \parallel turn = 1);$
- p.  $flag_2 := true$
- q.  $turn := 1$
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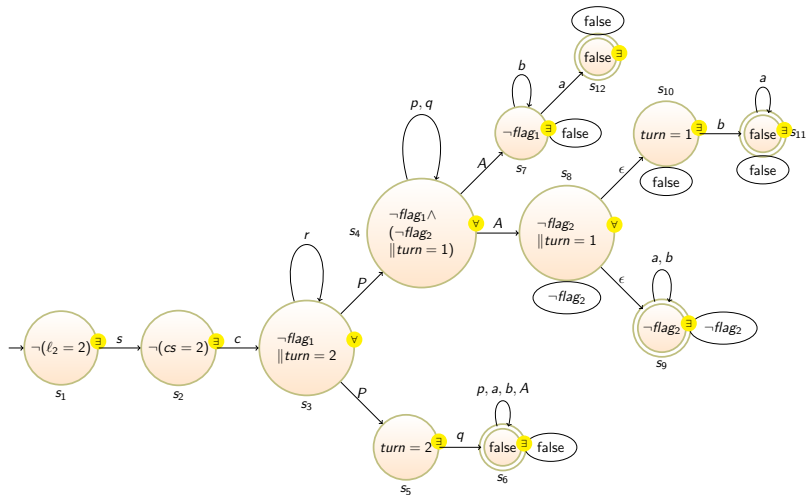
# AFA constructed from the given trace



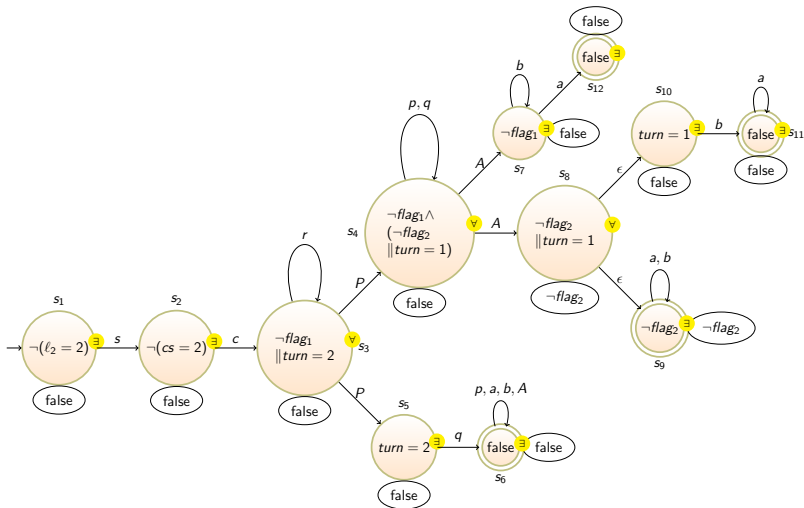
# Weakest precondition generation from this AFA



# Weakest precondition generation from this AFA



# Weakest precondition generation from this AFA: Final



# Overall Picture

# Overall Picture

- Let  $\mathcal{A}_{\sigma, \neg\phi}$  be the AFA constructed from the trace  $\sigma$  and the safety assertion  $\neg\phi$
- Let  $\psi$  be the annotation that flows to the initial state then

- 1 For every word  $\sigma'$  accepted by the AFA  $\mathcal{A}_{\sigma, \neg\phi}$

**Theorem 1:**  $\text{wp}(\text{rev}(\sigma'), \neg\phi)$  is same as  $\psi$

- 2  $\text{rev}(\sigma)$  is also accepted by the AFA  $\mathcal{A}_{\sigma, \neg\phi}$
- 3 If  $\psi \wedge \mathcal{I}$  is unsatisfiable then **Safe to exclude the words of this automaton** from safety checking

# Overall Picture

- Let  $\mathcal{A}_{\sigma, \neg\phi}$  be the AFA constructed from the trace  $\sigma$  and the safety assertion  $\neg\phi$
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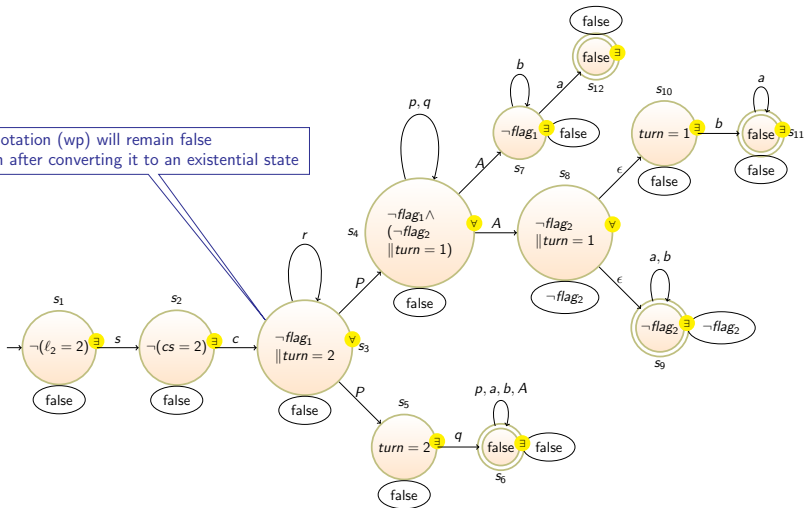
Optimizations to increase the set of accepted words but preserving **Theorem 1**



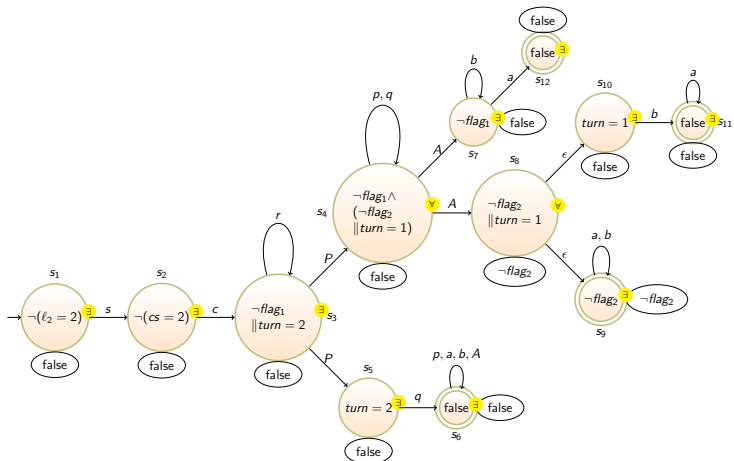
# Optimizations

# Optimization 1: Conversion from Universal to Existential states

Annotation (wp) will remain false even after converting it to an existential state

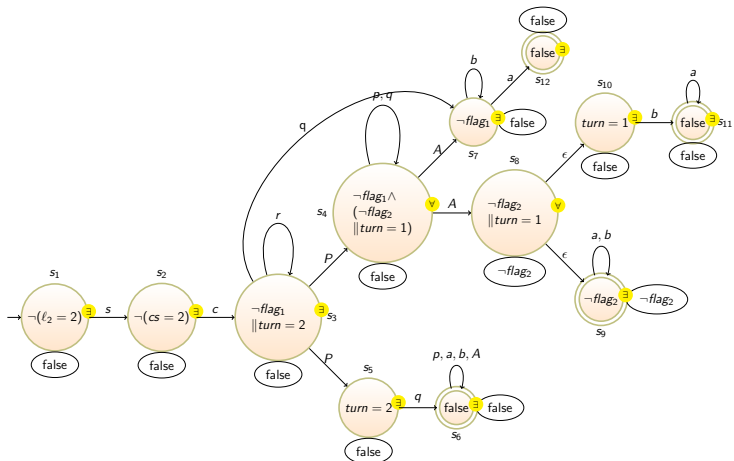


# Optimization 2: Adding Extra Edges



Label  $q$  in Peterson's algorithm is  $turn := 1$

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Label  $q$  in Peterson's algorithm is  $turn := 1$

# Performance Evaluation

# Performance Evaluation- Time in Seconds

Program	ProofTraPar	THREADER[GPR11]	Lazy-CSeq[ITF+14]
Peterson.safe	<b>0.3</b>	3.2	3.1
Dekker.safe	<b>1.1</b>	1.7	4.2
Lamport.safe	<b>2.4</b>	47	5.1
Szymanski.safe	<b>3</b>	12.8	4
TimeVarMutex.safe	<b>0.76</b>	8.56	4.2
RWLock.safe (2R+2W)	8.8	140	<b>6.7</b>
RWLock.unsafe (2R+2W)	3.8	153	<b>0.7</b>
Qrcu.safe (2R+1W)	<b>20</b>	-	41
Qrcu.unsafe (2R+1W)	13.8	76	<b>1.1</b>

# Contribution

- A novel algorithm to directly construct an AFA to give a sound and complete verification algorithm
  
- Demonstrated the feasibility of trace partitioning approach by implementing and comparing it against state-of-the-art tools



## Remarks

- 1 Trace partitioning and Partial Order Reduction
- 2 Comparison to *inductive Data Flow graph*(iDFG) proposed in Farzan et.al [FKP13]
  - *iDFG* Converted to AFA for set theoretic operations
  - No implementation hence difficult to compare the cost of direct AFA construction vs iDFG to AFA construction

Thank You



A. Farzan, Z. Kincaid, and A. Podelski.

Inductive data flow graphs.

In *POPL*, pages 129–142, 2013.



A. Gupta, C. Popeea, and A. Rybalchenko.

Threader: A constraint-based verifier for multi-threaded programs.

In *CAV*, pages 412–417, 2011.



O. Inverso, E. Tomasco, B. Fischer, S. La Torre, and G. Parlato.

Bounded model checking of multi-threaded C programs via lazy sequentialization.

In *CAV*, volume 8559 of *LNCS*, pages 585–602. Springer, 2014.