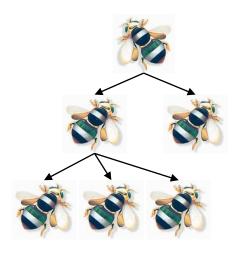
B- Trees



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Slide Credit : Yael Moses, IDC Herzliya

Animated demo: <u>http://ats.oka.nu/b-tree/b-tree.html</u> https://www.youtube.com/watch?v=coRJrcIYbF4

Motivation

- Large differences between time access to disk, cash memory and core memory
- Minimize expensive access (e.g., disk access)
- B-tree: Dynamic sets that is optimized for disks

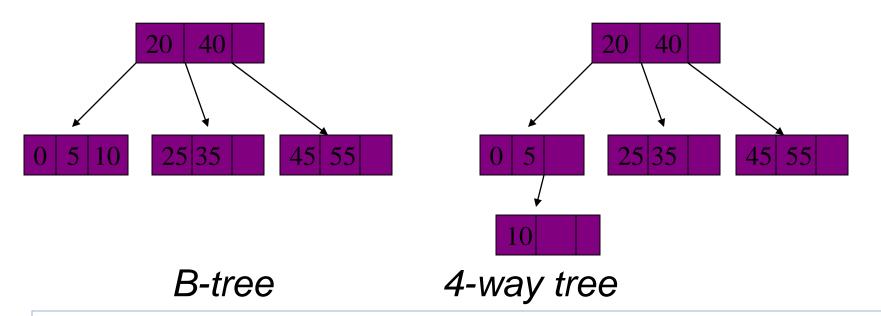
B-Trees

A B-tree is an M-way search tree with two properties :

- 1. It is perfectly balanced: every leaf node is at the same depth
- 2. Every internal node other than the root, is at least half-full, i.e. $M/2-1 \le \#keys \le M-1$
- Every internal node with k keys has k+1 non-null children

For simplicity we consider *M* even and we use t=M/2:
2.* Every internal node other than the root is at least half-full, i.e. *t*-1≤ #keys ≤2*t*-1, *t*≤ #children ≤2*t*

Example: a 4-way B-tree



B-tree

- 1. It is perfectly balanced: every leaf node is at the same depth.
- 2. Every node, except maybe the root, is at least half-full t-1≤ #keys ≤2t-1
- **3**. Every internal node with *k* keys has *k*+1 non-null children

B-tree Height

Claim: any B-tree with *n* keys, height *h* and minimum degree *t* satisfies:

$$h \le \log_t \frac{n+1}{2}$$

Proof:

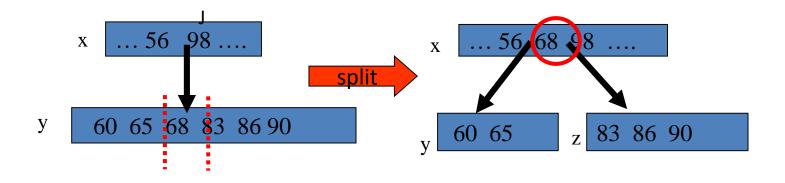
- The minimum number of KEYS for a tree with height *h* is obtained when:
 - The root contains one key
 - All other nodes contain *t-1* keys

B-Tree: Insert X

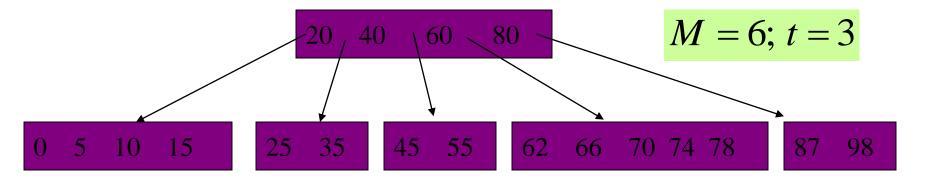
- 1. As in *M*-way tree find the leaf node to which X should be added
- Add X to this node in the appropriate place among the values already there (there are no subtrees to worry about)
- 3. Number of values in the node after adding the key:
 - Fewer than 2t-1: done
 - Equal to 2t: overflowed
- 4. Fix overflowed node

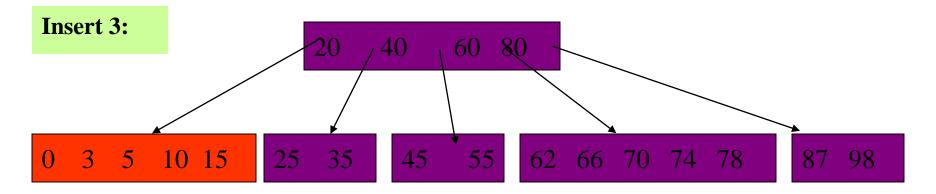
Fix an Overflowed

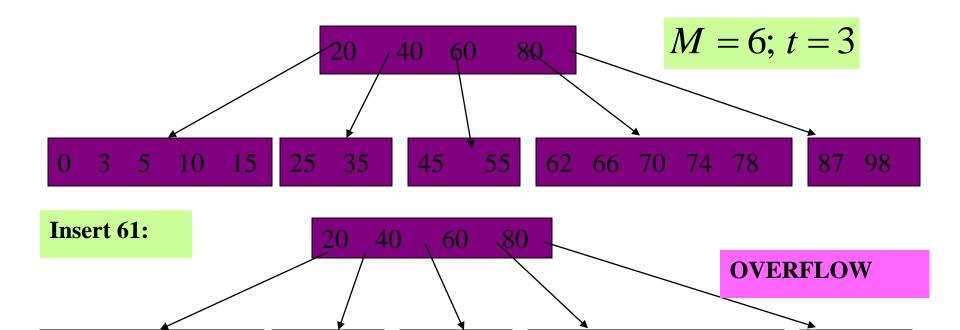
- 1. Split the node into three parts, *M=2t*:
 - Left: the first t values, become a left child node
 - Middle: the middle value at position t, goes up to parent
 - Right: the last *t-1* values, become a right child node
- 2. Continue with the parent:
 - 1. Until no overflow occurs in the parent
 - 2. If the root overflows, split it too, and create a new root node

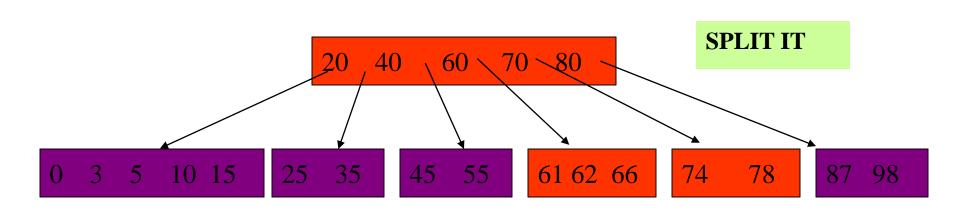


Insert example



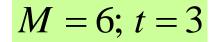


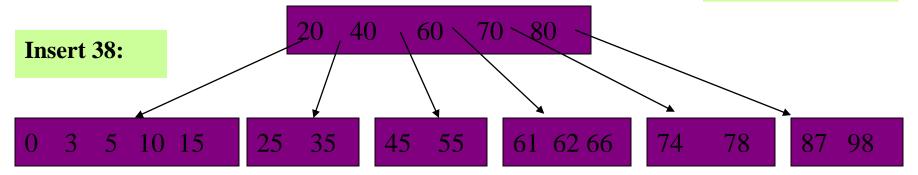


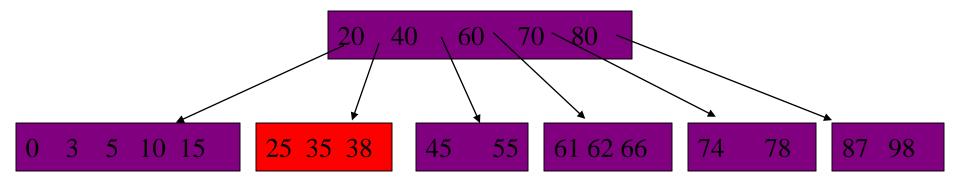


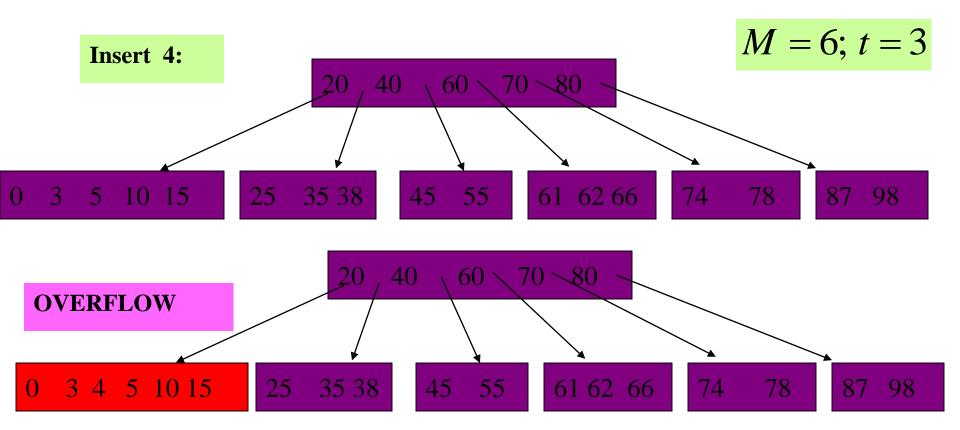
61 62 66 70 74 78

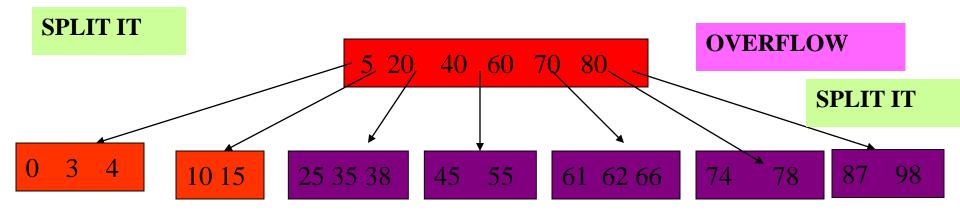
87 98

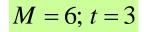


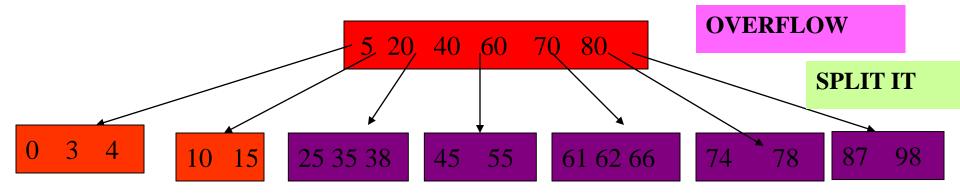


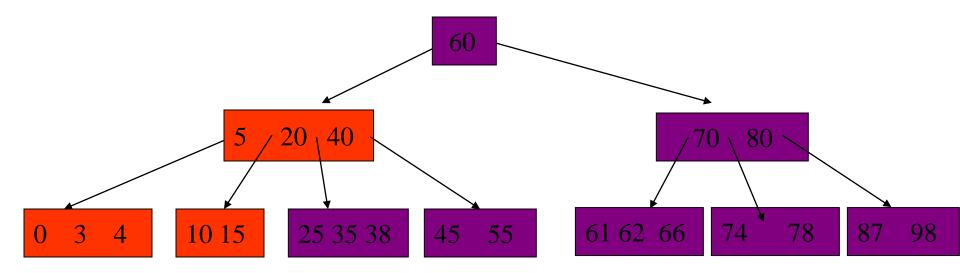












Complexity Insert

 Inserting a key into a B-tree of height h is done in a single pass down the tree and a single pass up the tree

Complexity: $O(h) = O(\log_t n)$

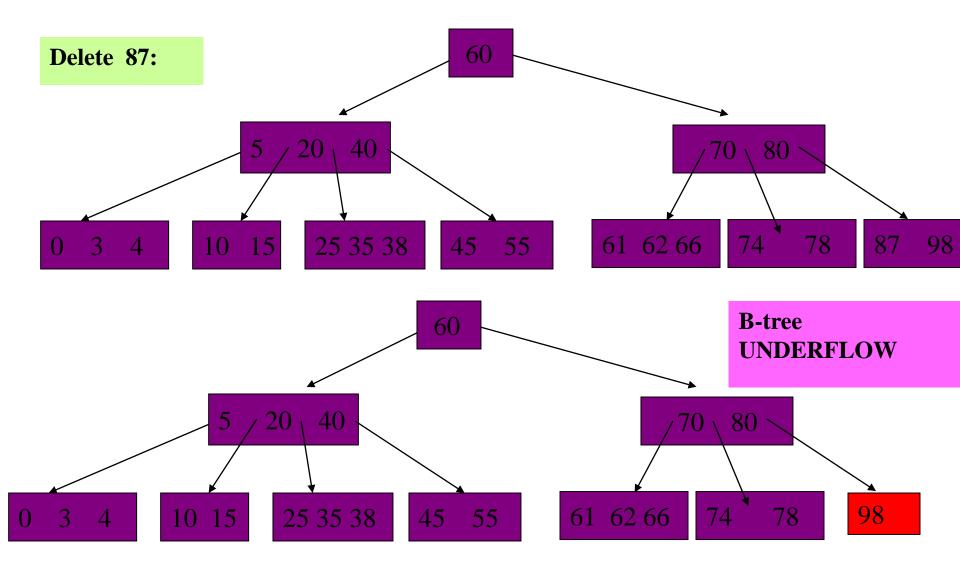
B-Tree: Delete X

- Delete as in M-way tree
- A problem:
 - might cause *underflow*: the number of keys remain in a node < t-1

Recall: The root should have at least 1 value in it, and all other nodes should have at least t-1 values in them

M = 6; t = 3

Underflow Example



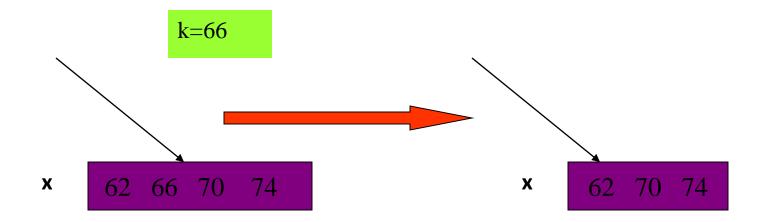
B-Tree: Delete X,k

- Delete as in M-way tree
- A problem:
 - might cause *underflow*: the number of keys remain in a node < t-1
- Solution:
 - make sure a node that is visited has at least t instead of t-1 keys.
 - If it doesn't have k
 - (1) either take from sibling via a rotate, or
 - (2) merge with the parent
 - If it does have k
 - See next slides

Recall: The root should have at least 1 value in it, and all other nodes should have at least t-1 (at most 2t-1) values in them

B-Tree-Delete(x,k)

1st case: k is in x and x is a *leaf* \rightarrow delete k

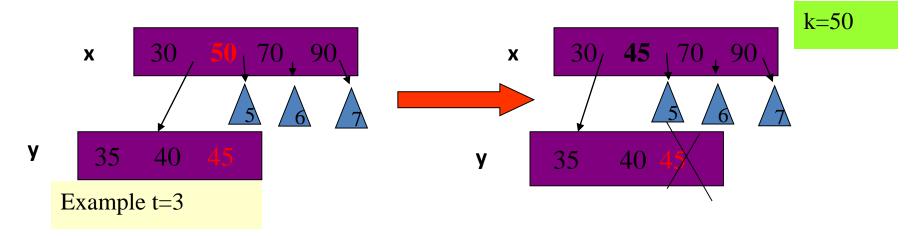


How many keys are left?

Example t=3

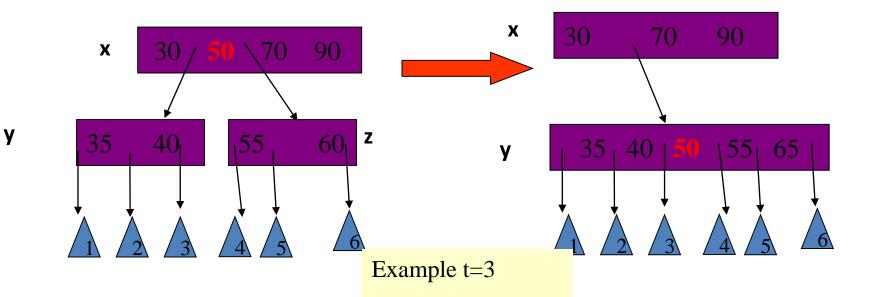
2nd case: *k* in the internal node *x*, *y* and *z* are the preceding and succeeding nodes of the key $k \in x$

- a. If y has at least t keys:
 - ▷ Replace k in x $k' \in y$, where k' is the predecessor of k in y
 - Delete k' recursively
- b. Similar check for successor case



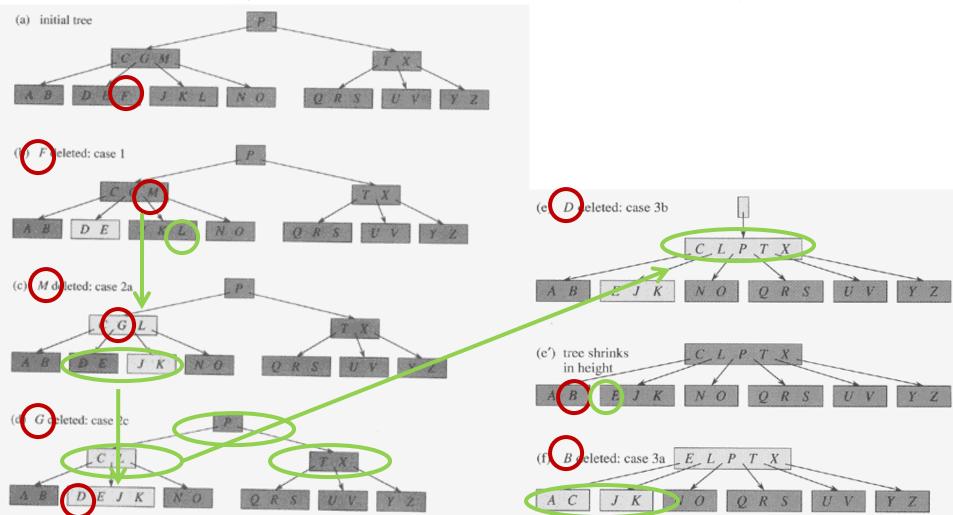
2nd case cont.:

- c. Both a and b are not satisfied: y and z have t-1 keys
 - Merge the two children, y and z
 - Recursively delete *k* from the merged cell



Questions

- When does the height of the tree shrink?
- Why do we need the number of keys to be at least *t* and not *t*-1 when we proceed down in the tree?



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Figure 18.8 Deleting keys from a B-tree. The minimum degree for this B-tree is t = 3, so a node (other than the root) cannot have fewer than 2 keys. Nodes that are modified are lightly shaded. (a) The B-tree of Figure 18.7(e). (b) Deletion of F. This is case 1: simple deletion from a leaf. (c) Deletion of M. This is case 2a: the predecessor L of M is moved up to take M's position. (d) Deletion of G. This is case 2c: G is pushed down to make node DEGJK, and then G is deleted from this leaf (case 1). (e) Deletion of D. This is case 3b: the recursion can't descend to node CL because it has only 2 keys, so P is pushed down and merged with CL and TX to form CLPTX; then, D is deleted from a leaf (case 1). (e') After (d), the root is deleted and the tree shrinks in height by one. (f) Deletion of B. This is case 3a: C is moved to fill B's position and E is moved to fill C's position.

Delete Complexity

- Basically downward pass:
 - Most of the keys are in the leaves one downward pass
 - When deleting a key in internal node may have to go one step up to replace the key with its predecessor or successor

Complexity
$$O(h) = O(\log_t n)$$

Run Time Analysis of B-Tree Operations

- For a B-Tree of order *M=2t*
 - #keys in internal node: M-1
 - #children of internal node: between M/2 and M
 - \rightarrow Depth of B-Tree storing *n* items is $O(\log_{M/2} N)$
- Find run time is:
 - O(log M) to binary search which branch to take at each node, since M is constant it is O(1).
 - Total time to find an item is $O(h*\log M) = O(\log n)$
- Insert & Delete
 - Similar to find but update a node may take : O(M)=O(1)

Note: if M is >32 it worth using binary search at each node

A typical B-Tree

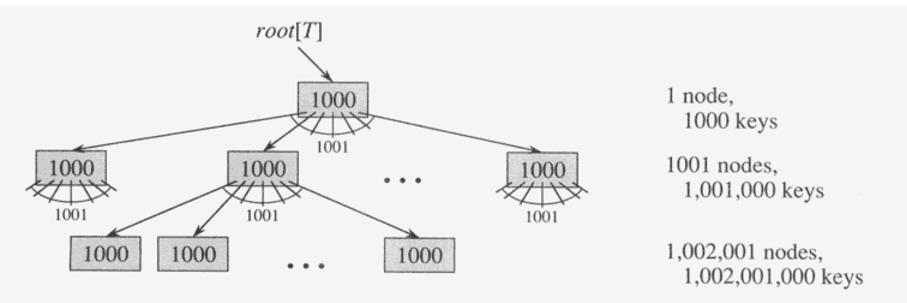


Figure 18.3 A B-tree of height 2 containing over one billion keys. Each internal node and leaf contains 1000 keys. There are 1001 nodes at depth 1 and over one million leaves at depth 2. Shown inside each node x is n[x], the number of keys in x.

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Why B-Tree?

- B-trees is an implementation of dynamic sets that is optimized for disks
 - The memory has an hierarchy and there is a tradeoff between size of units/blocks and access time
 - The goal is to optimize the number of times needed to access an "expensive access time memory"
 - The size of a node is determined by characteristics of the disk block size page size
 - The number of access is proportional to the tree depth