

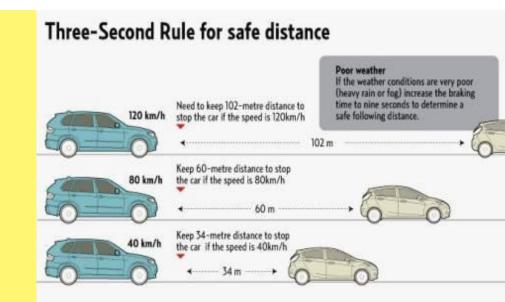
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The Problem we are addressing Accidents due to Speeding of vehicles



Our Solution: 3 second rule



#HumseFarakPadtaHai

Source: Dubai Police

Ramachandra Babu/OGulf News



The 3-second rule is implemented so that the driver maintain a safe travelling distance at any speed. It is more a guide to reaction time rather than safe stopping distance.

Github Link

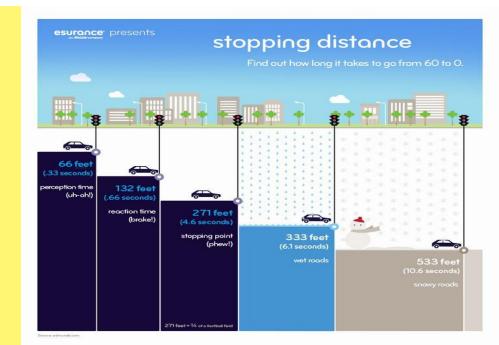
It is one thing to know the solution and other to actually think and act accordingly.



Why is it crucial?

A person cannot decide for himself that he is following the 3-second rule. Hence our application guides them.

Problem Tackling:
Alerting when 3-second Rule is
not followed



Implementation

Implementation

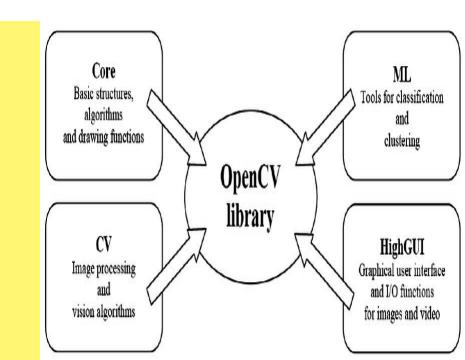
- Getting front view from driver's perspective using camera
- Using computer vision to find the distance of the car ahead
- Alerting when the 3-second rule is violated

Calculating Distance

 We find the distance of the car ahead by using the width ratio. And assuming that 2 m is the average width of a car. This helps in extending this model to trucks and other heavy vehicles

Tools Used

- OpenCV (Open Source)
- Visual Studio
- Dataset for different cars



DataSet used for training

- University of Illinois (550 images)
- Caltech (600 images)
- Other sources (1500 images)



Datasets play crucial roles in advancing Al. #ImageNet helped to enable the latest deep learning advances.



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Application in action

A Snap of our Application when the driving is safe



A Snap of our Application when the 3 second rule is being violated



Challenges

Challenges

- Lane Detection
- Proper identification of cars

Detecting Lane

- Pre-Processing Stage
- Post-Processing Stage

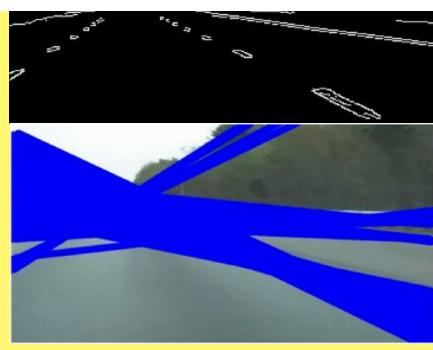
Pre-Processing Stage

- Original Image
- GrayScale Image (Canny Edge Detection)
- Region of Interest(ROI)



Post-Processing Stage

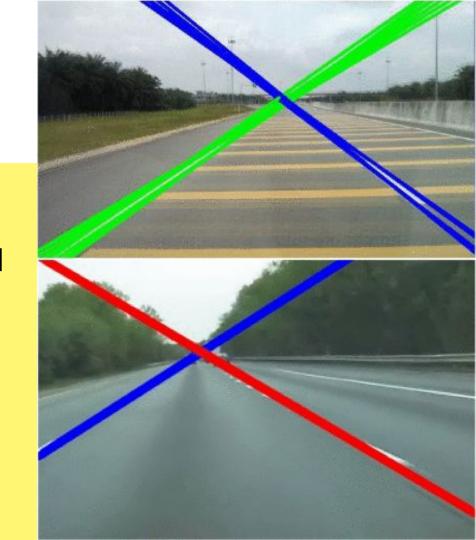
- Canny Edge Detected Image
- Hough Transform connecting discontinuous lines and differentiating different lines



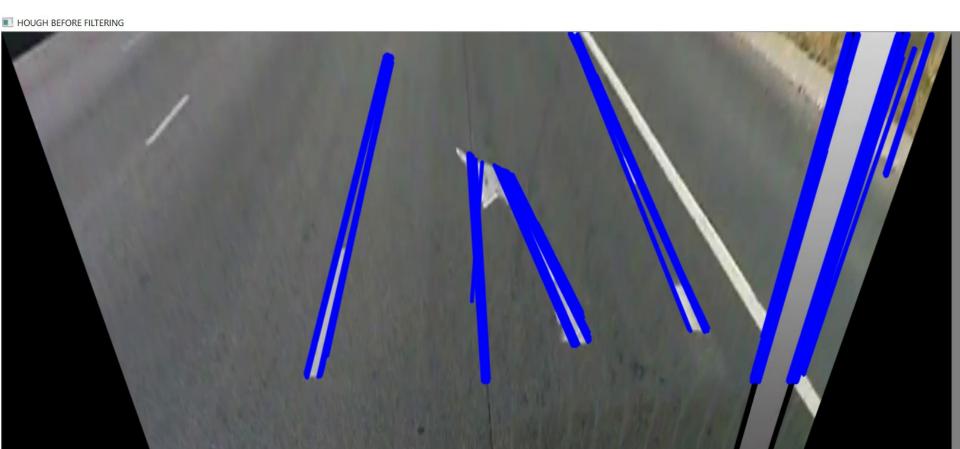
Hough transform detects relevant lines representing left and right lane markers.

Road Lane Modelling

- Computation done to recognize possible right and left lane markers
- Grouping Similar Lines together and getting an average results
- Final Result



Detecting current lane



Impact

10 Lakh + people were killed in road accidents over the past decade. Our application would greatly be reducing the root cause of all accidents: driver being distracted, and also aiding the more cautious ones and hence help us save many lives.

Activities to be conducted in next Quarter

- Complete Lane Detection System
- Road Signal symbol identification and alert system
 - Pedestrian Identification
 - Identification of Potholes in the road
 - More Data of Indian Cars and roads

DEMO

www.road-safety.co.in