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**COL 752 Geometric Algorithms**  
Minor 2 Sem I 2016 -17 Max 15, Time 1 hrs

Name \_\_\_\_\_ Entry No. \_\_\_\_\_ Group \_\_\_\_\_

Given a set  $S$  of  $n$  points in  $\mathbb{R}^3$ , design an efficient algorithm (preferably linear but no more than  $O(n \log n)$ ) to find the smallest enclosing sphere of  $S$ .

Your algorithm can be randomized and you must provide detailed proof of correctness and running time.

Answer in the space provided below.

Use RIC where let  $Minball(S, f)$  be defined as the smallest ball containing a set of  $S$  points of which  $f$  are known points  $0 \leq f \leq 4$ . The initial algorithm is called as  $Minball(N, 0)$  since all the (maximum) 4 points on the boundary must be determined. Note that there can be 2,3 or 4 points on the surface of the smallest ball containing all the points. If there are 2 or 3 points on the boundary then the ball can be determined by the points in dimensions 2 or 3 by considering the line (plane) passing through these points.

In the algorithm described below, we call  $Minball(N, \phi)$ .

Let  $T(i, u)$  denote the expected running time of the algorithm  $Minball$  with  $n$  points of which  $u$  are to be determined. Note that  $0 \leq u \leq 4$ .

Using backward analysis we can show that

$$T(i, u) \leq T(i-1, u-1) + \frac{u}{i} \cdot T(i-1, u-1) + O(1)$$

Using  $T(i, 0) = O(1)$ , we can show that  $T(i, u) = O((u)!i)$  similar to the RIC based LP algorithm.

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**Procedure** Compute the smallest enclosing ball( $S, D$ )

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1 Input  $S$  is a set of points in 3D where  $S$  is given as a random sequence ;
2 Let  $C_j$  denote the smallest ball containing the first  $j$  points defined by  $k \leq 4$   $C_0 = D$  ;
3 while  $j \leq n$  do
4   if  $p_{j+1} \notin C_j$  then
5     if  $D < 4$  then
6        $C_{j+1}$  is defined by  $D \cup p_{j+1}$  ;
7        $Minball(S - p_{j+1}, D \cup p_{j+1})$ 
8     else
9       Replace the last added point in  $D$  by  $p_{j+1}$ 
10    ;
11   $j \leftarrow j + 1$  ;
12 Output ( $C_n$ ) ;
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