

COL866: Foundations of Data Science

Ragesh Jaiswal, IITD

Best Fit Subspaces and Singular Value Decomposition (SVD)

Best Fit Subspaces and SVD

Best fit line

Problem

Given an $n \times d$ matrix A , where we interpret the rows of the matrix as points in \mathbb{R}^d , find a **best fit line** through the origin for the given n points.

- Question: How do we define **best fit line**?

Best Fit Subspaces and SVD

Best fit line

Problem

Given an $n \times d$ matrix A , where we interpret the rows of the matrix as points in \mathbb{R}^d , find a **best fit line** through the origin for the given n points.

- Question: How do we define **best fit line**?
 - A line that minimises the sum of squared distance of the n points to the line.

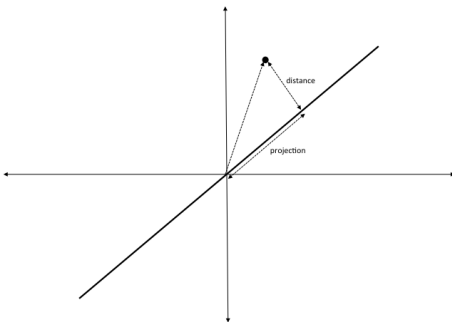
Best Fit Subspaces and SVD

Best fit line

Problem

Given an $n \times d$ matrix A , where we interpret the rows of the matrix as points in \mathbb{R}^d , find a **best fit line** through the origin for the given n points.

- Question: How do we define **best fit line**?
 - A line that minimises the sum of squared distance of the n points to the line.
 - Claim: The best fit line maximises the sum of projections squared of the n points to the line.



Best Fit Subspaces and SVD

Best fit line

Problem

Given an $n \times d$ matrix A , where we interpret the rows of the matrix as points in \mathbb{R}^d , find a **best fit line** through the origin for the given n points.

- The best fit line through the origin is one that minimises the sum of squared distance of the n points to the line.
- Let \mathbf{v} denote a unit vector ($d \times 1$ matrix) in the direction of the best fit line.
- Claim: The sum of squared lengths of projections of the points onto \mathbf{v} is $\|A\mathbf{v}\|^2$.

Best Fit Subspaces and SVD

Best fit line

Problem

Given an $n \times d$ matrix A , where we interpret the rows of the matrix as points in \mathbb{R}^d , find a **best fit line** through the origin for the given n points.

- The best fit line through the origin is one that minimises the sum of squared distance of the n points to the line.
- Let \mathbf{v} denote a unit vector ($d \times 1$ matrix) in the direction of the best fit line.
- Claim: The sum of squared lengths of projections of the points onto \mathbf{v} is $\|A\mathbf{v}\|^2$.
- So, the best fit line is defined by unit vector \mathbf{v} that maximises $\|A\mathbf{v}\|$.
- This is the **first singular vector** of the matrix A . So, the first singular vector is defined as:

$$\mathbf{v}_1 = \arg \max_{\|\mathbf{v}\|=1} \|A\mathbf{v}\|$$

Best Fit Subspaces and SVD

Best fit line

Problem

Given an $n \times d$ matrix A , where we interpret the rows of the matrix as points in \mathbb{R}^d , find a **best fit line** through the origin for the given n points.

- The best fit line through the origin is one that minimises the sum of squared distance of the n points to the line.
- Let \mathbf{v} denote a unit vector ($d \times 1$ matrix) in the direction of the best fit line.
- Claim: The sum of squared lengths of projections of the points onto \mathbf{v} is $\|A\mathbf{v}\|^2$.
- So, the best fit line is defined by unit vector \mathbf{v} that maximises $\|A\mathbf{v}\|$.
- This is the **first singular vector** of the matrix A . So, the first singular vector is defined as:

$$\mathbf{v}_1 = \arg \max_{\|\mathbf{v}\|=1} \|A\mathbf{v}\|$$

- The value $\sigma_1 = \|A\mathbf{v}_1\|$ is called the first singular value of A .

Best Fit Subspaces and SVD

Best fit line

Problem

Given an $n \times d$ matrix A , where we interpret the rows of the matrix as points in \mathbb{R}^d , find a **best fit line** through the origin for the given n points.

- The first singular vector is defined as:

$$\mathbf{v}_1 = \arg \max_{\|\mathbf{v}\|=1} \|\mathbf{A}\mathbf{v}\|$$

- The value $\sigma_1 = \|\mathbf{A}\mathbf{v}_1\|$ is called the first singular value of A .
- So, σ_1^2 is equal to the sum of squared length of projections.
- Note that if all the data points are “close” to a line through the origin, then the first singular vector gives such a line.
- Question: if the data points are close to a plane (and in general close to a k -dimensional subspace), then how do we find such a plane?

Best Fit Subspaces and SVD

Best fit line

Problem

Given an $n \times d$ matrix A , where we interpret the rows of the matrix as points in \mathbb{R}^d , find a **best fit plane** through the origin for the given n points.

- Let \mathbf{v}_1 denote the first singular vector of A .
- Idea: Find a unit vector \mathbf{v} perpendicular to \mathbf{v}_1 that maximises $\|A\mathbf{v}\|$. Output the plane through the origin defined by vectors \mathbf{v}_1 and \mathbf{v} .
- Claim: The plane defined above indeed maximises sum of squared distances of all the points.
- The second singular vector is defined as:

$$\mathbf{v}_2 = \arg \max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1} \|A\mathbf{v}\|.$$

- The value $\sigma_2 = \|A\mathbf{v}_2\|$ is called the second singular value of A .

Best Fit Subspaces and SVD

Best fit plane

Problem

Given an $n \times d$ matrix A , where we interpret the rows of the matrix as points in \mathbb{R}^d , find a **best fit plane** through the origin for the given n points.

- Let \mathbf{v}_1 denote the first singular vector of A .
- The second singular vector is defined as:

$$\mathbf{v}_2 = \arg \max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1} \|\mathbf{A}\mathbf{v}\|.$$

- The value $\sigma_2 = \|\mathbf{A}\mathbf{v}_2\|$ is called the second singular value of A .

Theorem

For any matrix A , the plane spanned by \mathbf{v}_1 and \mathbf{v}_2 is the best fit plane.

Best Fit Subspaces and SVD

Best fit plane

- The first singular vector is defined as: $\mathbf{v}_1 = \arg \max_{\|\mathbf{v}\|=1} \|\mathbf{A}\mathbf{v}\|$.
- The second singular vector is defined as:
$$\mathbf{v}_2 = \arg \max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1} \|\mathbf{A}\mathbf{v}\|.$$

Theorem

For any matrix A , the plane spanned by \mathbf{v}_1 and \mathbf{v}_2 is the best fit plane.

Proof sketch

- Let W denote the best fit plane for A .
- Claim 1: There exists an orthonormal basis $(\mathbf{w}_1, \mathbf{w}_2)$ of W such that \mathbf{w}_2 is perpendicular to \mathbf{v}_1 .
- Claim 2: $\|\mathbf{A}\mathbf{w}_1\|^2 \leq \|\mathbf{A}\mathbf{v}_1\|^2$.
- Claim 3: $\|\mathbf{A}\mathbf{w}_2\|^2 \leq \|\mathbf{A}\mathbf{v}_2\|^2$.
- This gives $\|\mathbf{A}\mathbf{w}_1\|^2 + \|\mathbf{A}\mathbf{w}_2\|^2 \leq \|\mathbf{A}\mathbf{v}_1\|^2 + \|\mathbf{A}\mathbf{v}_2\|^2$. □

Best Fit Subspaces and SVD

Best fit subspace

- The first singular vector and first singular value is defined as:

$$\mathbf{v}_1 = \arg \max_{\|\mathbf{v}\|=1} \|\mathbf{A}\mathbf{v}\| \quad \text{and} \quad \sigma_1 = \|\mathbf{A}\mathbf{v}_1\|$$

- The second singular vector and second singular value is defined as:

$$\mathbf{v}_2 = \arg \max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1} \|\mathbf{A}\mathbf{v}\| \quad \text{and} \quad \sigma_2 = \|\mathbf{A}\mathbf{v}_2\|.$$

- The third singular vector and third singular value is defined as:

$$\mathbf{v}_3 = \arg \max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1, \mathbf{v}_2} \|\mathbf{A}\mathbf{v}\| \quad \text{and} \quad \sigma_3 = \|\mathbf{A}\mathbf{v}_3\|.$$

- ...and so on.
- Let r be the smallest positive integer such that:
 $\max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1, \dots, \mathbf{v}_r} \|\mathbf{A}\mathbf{v}\| = 0$. Then A has r singular vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$.

Theorem

Let A be any $n \times d$ matrix with r singular vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$. For $1 \leq k \leq r$, let V_k be the subspace spanned by $\mathbf{v}_1, \dots, \mathbf{v}_k$. For each k , V_k is the best-fit k -dimensional subspace for A .

Best Fit Subspaces and SVD

Best fit subspace

- The first singular vector and first singular value is defined as:

$$\mathbf{v}_1 = \arg \max_{\|\mathbf{v}\|=1} \|\mathbf{A}\mathbf{v}\| \quad \text{and} \quad \sigma_1 = \|\mathbf{A}\mathbf{v}_1\|$$

- The second singular vector and second singular value is defined as:

$$\mathbf{v}_2 = \arg \max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1} \|\mathbf{A}\mathbf{v}\| \quad \text{and} \quad \sigma_2 = \|\mathbf{A}\mathbf{v}_2\|.$$

- The third singular vector and third singular value is defined as:

$$\mathbf{v}_3 = \arg \max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1, \mathbf{v}_2} \|\mathbf{A}\mathbf{v}\| \quad \text{and} \quad \sigma_3 = \|\mathbf{A}\mathbf{v}_3\|.$$

- ...and so on.
- Let r be the smallest positive integer such that:
 $\max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1, \dots, \mathbf{v}_r} \|\mathbf{A}\mathbf{v}\| = 0$. Then A has r singular vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$.
- The vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$ are more specifically called the **right singular vectors**.

Best Fit Subspaces and SVD

Best fit subspace

- The first singular vector and first singular value is defined as:

$$\mathbf{v}_1 = \arg \max_{\|\mathbf{v}\|=1} \|\mathbf{A}\mathbf{v}\| \quad \text{and} \quad \sigma_1 = \|\mathbf{A}\mathbf{v}_1\|$$

- The second singular vector and second singular value is defined as:

$$\mathbf{v}_2 = \arg \max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1} \|\mathbf{A}\mathbf{v}\| \quad \text{and} \quad \sigma_2 = \|\mathbf{A}\mathbf{v}_2\|.$$

- The third singular vector and third singular value is defined as:

$$\mathbf{v}_3 = \arg \max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1, \mathbf{v}_2} \|\mathbf{A}\mathbf{v}\| \quad \text{and} \quad \sigma_3 = \|\mathbf{A}\mathbf{v}_3\|.$$

- ...and so on.
- Let r be the smallest positive integer such that:
 $\max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1, \dots, \mathbf{v}_r} \|\mathbf{A}\mathbf{v}\| = 0$. Then A has r singular vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$.
- The vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$ are more specifically called the **right singular vectors**.
- For any singular vector \mathbf{v}_i , $\sigma_i = \|\mathbf{A}\mathbf{v}_i\|$ may be interpreted as the **component** of the matrix A along \mathbf{v}_i .
- Given this interpretation, the *"the components should add up to give the whole content of A "*.

Best Fit Subspaces and SVD

Frobenius Norm

- Let r be the smallest positive integer such that:
 $\max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1, \dots, \mathbf{v}_r} \|\mathbf{A}\mathbf{v}\| = 0$. Then A has r singular vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$.
- The vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$ are more specifically called the **right singular vectors**.
- For any singular vector \mathbf{v}_i , $\sigma_i = \|\mathbf{A}\mathbf{v}_i\|$ may be interpreted as the **component** of the matrix A along \mathbf{v}_i .
- Given this interpretation, the *“the components should add up to give the whole content of A ”*.
- For any row a_j in the matrix A , we can write $\|a_j\|^2 = \sum_{i=1}^r (a_j \cdot \mathbf{v}_i)^2$.
This further gives:

$$\sum_{j=1}^n \|a_j\|^2 = \sum_{j=1}^n \sum_{i=1}^r (a_j \cdot \mathbf{v}_i)^2 = \sum_{i=1}^r \|\mathbf{A}\mathbf{v}_i\|^2 = \sum_{i=1}^r \sigma_i^2.$$

Best Fit Subspaces and SVD

Frobenius Norm

- Let r be the smallest positive integer such that:
 $\max_{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{v}_1, \dots, \mathbf{v}_r} \|\mathbf{A}\mathbf{v}\| = 0$. Then A has r singular vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$.
- The vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$ are more specifically called the **right singular vectors**.
- For any singular vector \mathbf{v}_i , $\sigma_i = \|\mathbf{A}\mathbf{v}_i\|$ may be interpreted as the **component** of the matrix A along \mathbf{v}_i .
- Given this interpretation, the “*the components should add up to give the whole content of A*”.
- For any row a_j in the matrix A , we can write $\|a_j\|^2 = \sum_{i=1}^r (a_j \cdot \mathbf{v}_i)^2$.
This further gives:

$$\sum_{j=1}^n \|a_j\|^2 = \sum_{j=1}^n \sum_{i=1}^r (a_j \cdot \mathbf{v}_i)^2 = \sum_{i=1}^r \|\mathbf{A}\mathbf{v}_i\|^2 = \sum_{i=1}^r \sigma_i^2.$$

- The LHS of the above equation may be interpreted as “*content of the matrix*” defines the **Frobenius Norm** of the matrix A .

Definition (Frobenius Norm)

The Frobenius norm of a given $n \times d$ matrix A , denoted by $\|A\|_F$, is

defined as: $\|A\|_F = \sqrt{\sum_{i=1}^n \sum_{j=1}^d A_{i,j}^2}$.

Best Fit Subspaces and SVD

Frobenius Norm

- For any row a_j in the matrix A , we can write $\|a_j\|^2 = \sum_{i=1}^r (a_j \cdot \mathbf{v}_i)^2$. This further gives:

$$\sum_{j=1}^n \|a_j\|^2 = \sum_{j=1}^n \sum_{i=1}^r (a_j \cdot \mathbf{v}_i)^2 = \sum_{i=1}^r \|A\mathbf{v}_i\|^2 = \sum_{i=1}^r \sigma_i^2.$$

- The LHS of the above equation may be interpreted as “*content of the matrix*” defines the **Frobenius Norm** of the matrix A .

Definition (Frobenius Norm)

The Frobenius norm of a given $n \times d$ matrix A , denoted by $\|A\|_F$, is defined as: $\|A\|_F = \sqrt{\sum_{i=1}^n \sum_{j=1}^d A_{i,j}^2}$.

Theorem

For any matrix A , the sum of squares of the right singular values equals the square of the Frobenius norm of the matrix.

Singular Value Decomposition (SVD)

Left singular vectors

- Let $\mathbf{v}_1, \dots, \mathbf{v}_r$ be the right singular vectors and $\sigma_1, \dots, \sigma_r$ be the corresponding singular values of matrix A .
- The **left singular vectors** are defined as $\mathbf{u}_j = \frac{1}{\sigma_j} A\mathbf{v}_j$.
- $\sigma_j \mathbf{u}_j$ may be interpreted as a vector whose components are the projections of the rows of A onto \mathbf{v}_j .

Singular Value Decomposition (SVD)

Left singular vectors

- Let $\mathbf{v}_1, \dots, \mathbf{v}_r$ be the right singular vectors and $\sigma_1, \dots, \sigma_r$ be the corresponding eigenvalues of matrix A .
- The **left singular vectors** are defined as $\mathbf{u}_i = \frac{1}{\sigma_i} A \mathbf{v}_i$.
- $\sigma_i \mathbf{u}_i$ may be interpreted as a vector whose components are the projections of the rows of A onto \mathbf{v}_i .
- $\sigma_i \mathbf{u}_i \mathbf{v}_i^T$ is a rank one matrix whose rows can be interpreted as component of rows of A along \mathbf{v}_i .
- Given this, the following decomposition of A into rank one matrices should make sense (we will prove this): $A = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T$.

Theorem

Let A be any $n \times d$ matrix with right singular vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$, left-singular vectors $\mathbf{u}_1, \dots, \mathbf{u}_r$, and corresponding singular values $\sigma_1, \dots, \sigma_r$. Then $A = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T$.

Singular Value Decomposition (SVD)

Theorem

Let A be any $n \times d$ matrix with right singular vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$, left-singular vectors $\mathbf{u}_1, \dots, \mathbf{u}_r$, and corresponding singular values $\sigma_1, \dots, \sigma_r$. Then $A = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T$.

Proof sketch

- Lemma: Matrices A and B are identical iff for all vectors \mathbf{v} , $A\mathbf{v} = B\mathbf{v}$.
- Let $B = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T$.
- For any j , $A\mathbf{v}_j = \sigma_j \mathbf{u}_j$ from the definition of u_j .
- $B\mathbf{v}_j = \left(\sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T \right) \mathbf{v}_j = \sigma_j \mathbf{u}_j$ from orthonormality.
- Fact: Any vector \mathbf{v} can be written as a linear combination of right eigenvectors $\mathbf{v}_1, \dots, \mathbf{v}_r$ and a vector perpendicular to $\mathbf{v}_1, \dots, \mathbf{v}_r$. □

Singular Value Decomposition (SVD)

Theorem

Let A be any $n \times d$ matrix with right singular vectors $\mathbf{v}_1, \dots, \mathbf{v}_r$, left-singular vectors $\mathbf{u}_1, \dots, \mathbf{u}_r$, and corresponding singular values $\sigma_1, \dots, \sigma_r$. Then $A = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T$.

- The decomposition $A = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T$ is called the **Singular Value Decomposition** (or SVD in short).
- In matrix notation, we can write $A = UDV^T$ where:
 - U is a $n \times r$ matrix where the i^{th} column is \mathbf{u}_i .
 - D is a $r \times r$ diagonal matrix with the i^{th} diagonal element σ_i .
 - V is a $d \times r$ matrix where the i^{th} column is \mathbf{v}_i .
- Question: How do we compute the SVD?
- Question: What are the applications of SVD?

Singular Value Decomposition (SVD)

Best rank- k approximation

- Let $A = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T$ be the SVD of an $n \times d$ matrix A .
- For $k \in \{1, \dots, r\}$ let

$$A_k = \sum_{i=1}^k \sigma_i \mathbf{u}_i \mathbf{v}_i^T \quad (\text{i.e., sum truncated to first } k \text{ elements})$$

- Claim 1: A_k has rank k .
- Claim 2: The rows of A_k are the projections of the rows of A onto the subspace V_k spanned by the first k singular vectors of A .
- We will prove that A_k is the best **rank k approximation** to A where the error is measured in terms of the Frobenius norm.

Theorem

For any matrix B with rank at most k :

$$\|A - A_k\|_F \leq \|A - B\|_F.$$

Singular Value Decomposition (SVD)

Best rank- k approximation

Theorem

For any matrix B with rank at most k :

$$\|A - A_k\|_F \leq \|A - B\|_F.$$

- The above theorem tells us that A_k is a good approximation for A (w.r.t. Frobenius norm).
- The approximation A_k also is good for computation of product with any vector \mathbf{x} with $\|\mathbf{x}\| \leq 1$.
 - Computing $A\mathbf{x}$ would cost $O(nd)$ multiplications.
 - However, computing $A_k = \sum_{i=1}^k \sigma_i \mathbf{u}_i \mathbf{v}_i^T$ only costs $O(kd + nk)$ multiplications.
- Question: Is A_k best rank- k approximation to A w.r.t. the computation $A\mathbf{x}$ for an arbitrary \mathbf{x} with $\|\mathbf{x}\| \leq 1$?
 - We want a rank- k matrix B such that $\max_{\|\mathbf{x}\| \leq 1} \|(A - B)\mathbf{x}\|$ is minimized.

Singular Value Decomposition (SVD)

Best rank- k approximation

Theorem

For any matrix B with rank at most k :

$$\|A - A_k\|_F \leq \|A - B\|_F.$$

- The above theorem tells us that A_k is a good approximation for A (w.r.t. Frobenius norm).
- The approximation A_k also is good for computation of product with any vector \mathbf{x} with $\|\mathbf{x}\| \leq 1$.
 - Computing $A\mathbf{x}$ would cost $O(nd)$ multiplications.
 - However, computing $A_k = \sum_{i=1}^k \sigma_i \mathbf{u}_i \mathbf{v}^T$ only costs $O(kd + nk)$ multiplications.
- Question: Is A_k best rank- k approximation to A w.r.t. the computation $A\mathbf{x}$ for an arbitrary \mathbf{x} with $\|\mathbf{x}\| \leq 1$?
 - We want a rank- k matrix B such that $\max_{\|\mathbf{x}\| \leq 1} \|(A - B)\mathbf{x}\|$ is minimized.

Definition (Spectral norm)

The 2-norm or spectral norm of a matrix A , denoted by $\|A\|_2$, is defined as: $\|A\|_2 = \max_{\|\mathbf{x}\| \leq 1} \|A\mathbf{x}\|$.

Singular Value Decomposition (SVD)

Best rank- k approximation

- The approximation A_k also is good for computation of product with any vector \mathbf{x} with $\|\mathbf{x}\| \leq 1$.
 - Computing $A\mathbf{x}$ would cost $O(nd)$ multiplications.
 - However, computing $A_k = \sum_{i=1}^k \sigma_i \mathbf{u}_i \mathbf{v}_i^T$ only costs $O(kd + nk)$ multiplications.
- Question: Is A_k best rank- k approximation to A w.r.t. the computation $A\mathbf{x}$ for an arbitrary \mathbf{x} with $\|\mathbf{x}\| \leq 1$?
 - We want a rank- k matrix B such that $\max_{\|\mathbf{x}\| \leq 1} \|(A - B)\mathbf{x}\|$ is minimized.

Definition (Spectral norm)

The 2-norm or spectral norm of a matrix A , denoted by $\|A\|_2$, is defined as: $\|A\|_2 = \max_{\|\mathbf{x}\| \leq 1} \|A\mathbf{x}\|$.

- Claim: $\|A\|_2 = \sigma_1$.

Singular Value Decomposition (SVD)

Best rank- k approximation

- The approximation A_k also is good for computation of product with any vector \mathbf{x} with $\|\mathbf{x}\| \leq 1$.
 - Computing $A\mathbf{x}$ would cost $O(nd)$ multiplications.
 - However, computing $A_k = \sum_{i=1}^k \sigma_i \mathbf{u}_i \mathbf{v}_i^T$ only costs $O(kd + nk)$ multiplications.
- Question: Is A_k best rank- k approximation to A w.r.t. the computation $A\mathbf{x}$ for an arbitrary \mathbf{x} with $\|\mathbf{x}\| \leq 1$?
 - We want a rank- k matrix B such that $\max_{\|\mathbf{x}\| \leq 1} \|(A - B)\mathbf{x}\|$ is minimized.

Definition (Spectral norm)

The 2-norm or spectral norm of a matrix A , denoted by $\|A\|_2$, is defined as: $\|A\|_2 = \max_{\|\mathbf{x}\| \leq 1} \|A\mathbf{x}\|$.

- Claim: $\|A\|_2 = \sigma_1$.
- The question can now be rephrased as:
Is A_k the best rank- k approximation to A w.r.t. the spectral norm?

Singular Value Decomposition (SVD)

Best rank- k approximation

Definition (Spectral norm)

The 2-norm or spectral norm of a matrix A , denoted by $\|A\|_2$, is defined as: $\|A\|_2 = \max_{\|x\| \leq 1} \|Ax\|$.

- Question: Is A_k the best rank- k approximation to A w.r.t. the spectral norm?

Theorem

Let A be any $n \times d$ matrix. For any matrix B of rank at most k :

$$\|A - A_k\|_2 \leq \|A - B\|_2.$$

- First, we show that the left singular vectors $\mathbf{u}_1, \dots, \mathbf{u}_r$ are pairwise orthogonal.

Singular Value Decomposition (SVD)

Best rank- k approximation

Theorem

The left singular vectors $\mathbf{u}_1, \dots, \mathbf{u}_r$ are pairwise orthogonal.

Singular Value Decomposition (SVD)

Best rank- k approximation

Theorem

Let A be any $n \times d$ matrix. For any matrix B of rank at most k :

$$\|A - A_k\|_2 \leq \|A - B\|_2.$$

- First, we show that the left singular vectors $\mathbf{u}_1, \dots, \mathbf{u}_r$ are pairwise orthogonal.

Theorem

The left singular vectors $\mathbf{u}_1, \dots, \mathbf{u}_r$ are pairwise orthogonal.

- We will also need the following theorem.

Theorem

$$\|A - A_k\|_2^2 = \sigma_{k+1}^2.$$

Singular Value Decomposition (SVD)

Best rank- k approximation

Theorem

Let A be any $n \times d$ matrix. For any matrix B of rank at most k :

$$\|A - A_k\|_2 \leq \|A - B\|_2.$$

Theorem

The left singular vectors $\mathbf{u}_1, \dots, \mathbf{u}_r$ are pairwise orthogonal.

Theorem

$$\|A - A_k\|_2^2 = \sigma_{k+1}^2.$$

- Finally, we show the following:

Theorem

Let A be an $n \times d$ matrix. For any matrix B of rank at most k :

$$\|A - A_k\|_2 \leq \|A - B\|_2.$$

Singular Value Decomposition (SVD)

- Exercise: Show that u_i 's are the right singular vectors for the matrix A^T .

End